

DSC291: Machine Learning with Few Labels

Deep Generative Models / Generative Adversarial Learning

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Lecture 11, May 6, 2025

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Outline

- Deep Generative Models
 - Generative adversarial learning
- Paper presentation:
 - Devanshi Garg, Shrenik Jain: “RHO-1: Not All Tokens Are What You Need”

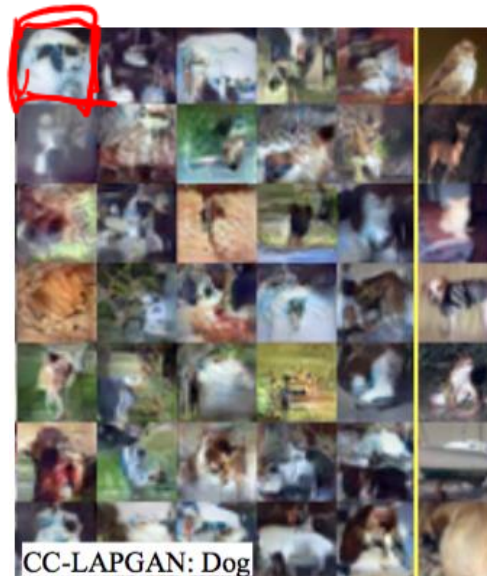
Generative modeling

- In generative modeling, we'd like to train a network that models a distribution, such as a distribution over images.
- One way to judge the quality of the model is to sample from it.
- This field has seen rapid progress:



MNIST

2009



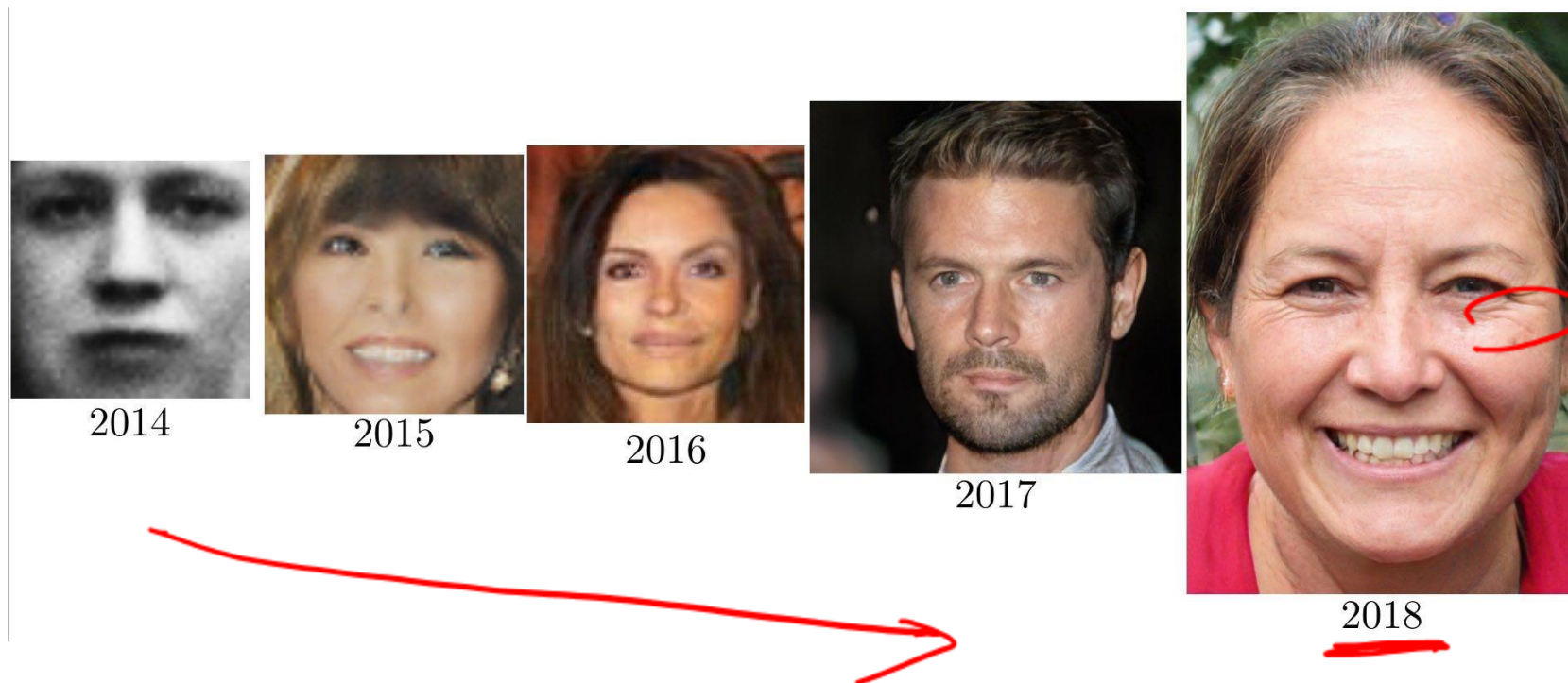
2015



2018

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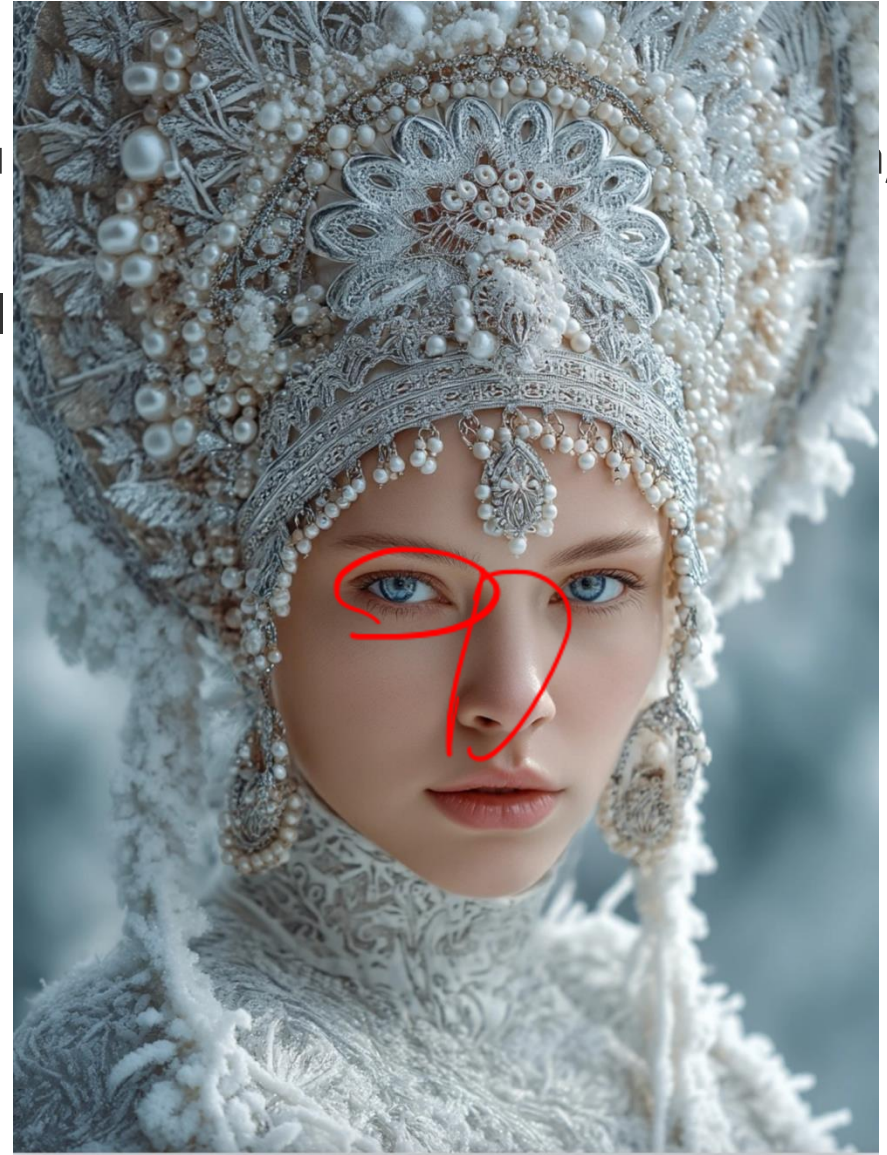


Generative modeling



Midjourney, 2025

diffusion



Generative modeling

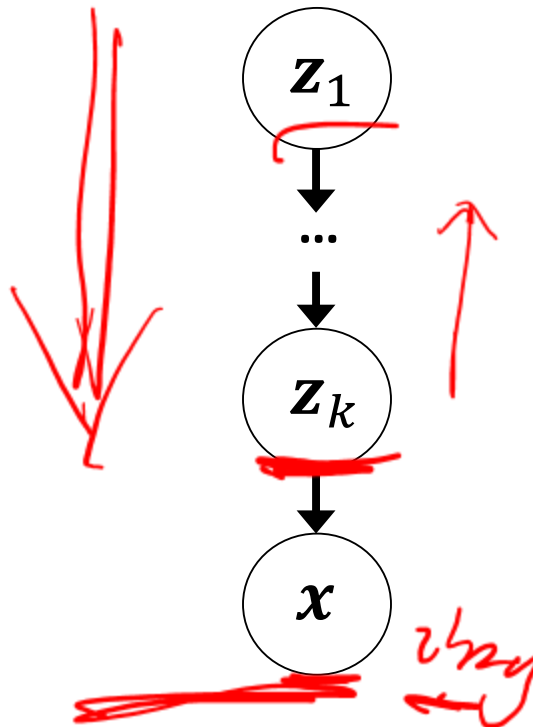
- In general, generative models are used for image generation, such as text-to-image, image-to-image, and video-to-video.
- One of the most popular generative models is the Variational Autoencoder (VAE).
- This model is used to generate images from a latent space.



Google Veo2, 12/2024

Deep generative models

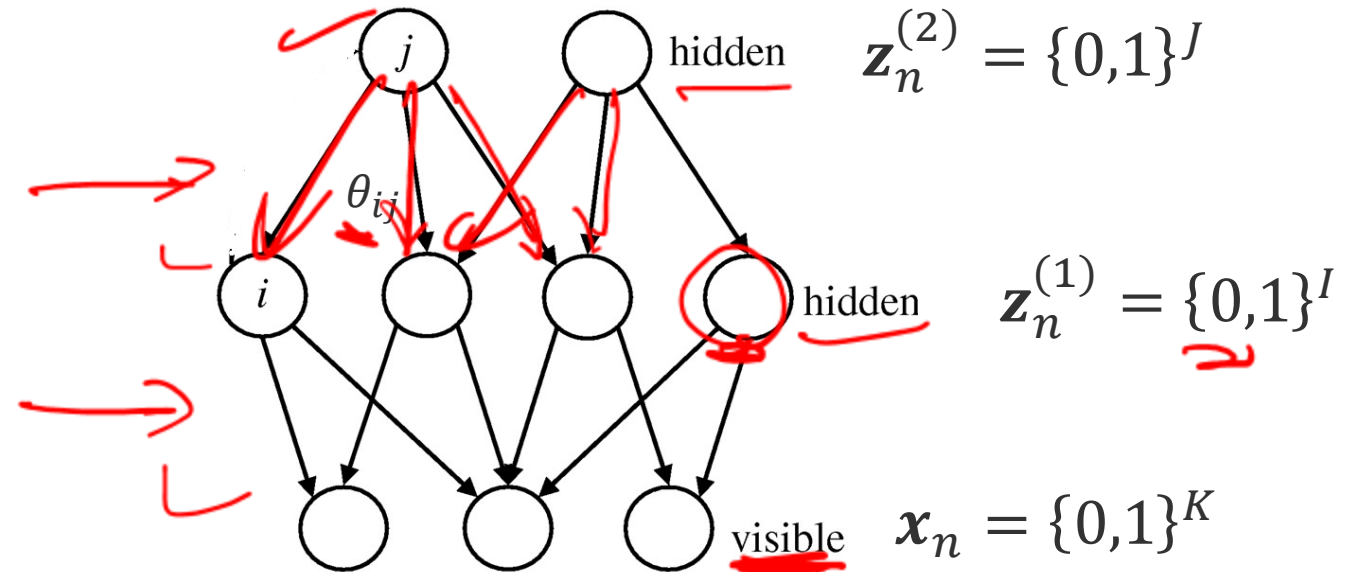
- Define probabilistic distributions over a set of variables
- "Deep" means multiple layers of hidden variables!



Early forms of deep generative models

- Hierarchical Bayesian models

- Sigmoid belief nets [Neal 1992]

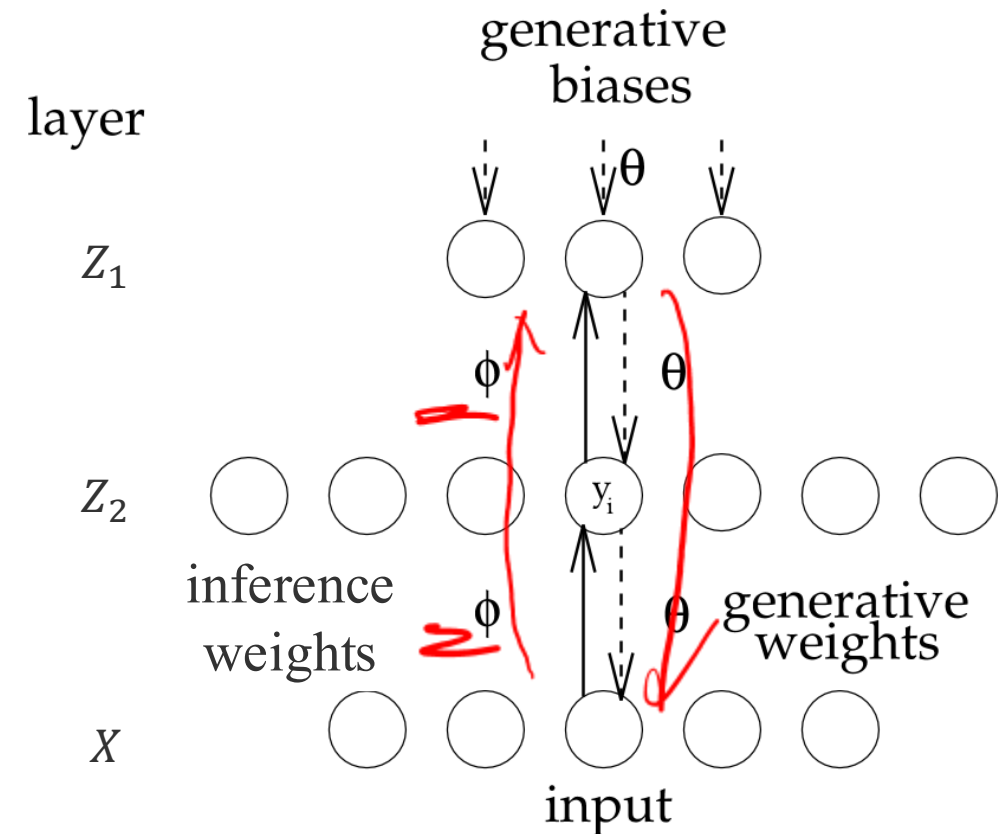


$$p\left(x_{kn} = 1 \mid \boldsymbol{\theta}_k, \mathbf{z}_n^{(1)}\right) = \sigma\left(\boldsymbol{\theta}_k^T \mathbf{z}_n^{(1)}\right)$$

$$p\left(z_{in}^{(1)} = 1 \mid \boldsymbol{\theta}_i, \mathbf{z}_n^{(2)}\right) = \sigma\left(\boldsymbol{\theta}_i^T \mathbf{z}_n^{(2)}\right)$$

Early forms of deep generative models

- Hierarchical Bayesian models
 - Sigmoid belief nets [Neal 1992]
- Neural network models
 - Helmholtz machines [Dayan et al., 1995]



[Dayan et al. 1995]

Early forms of deep generative models

- Hierarchical Bayesian models
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- Neural network models
 - Helmholtz machines [Dayan et al., 1995]
 - Predictability minimization [Schmidhuber 1995]

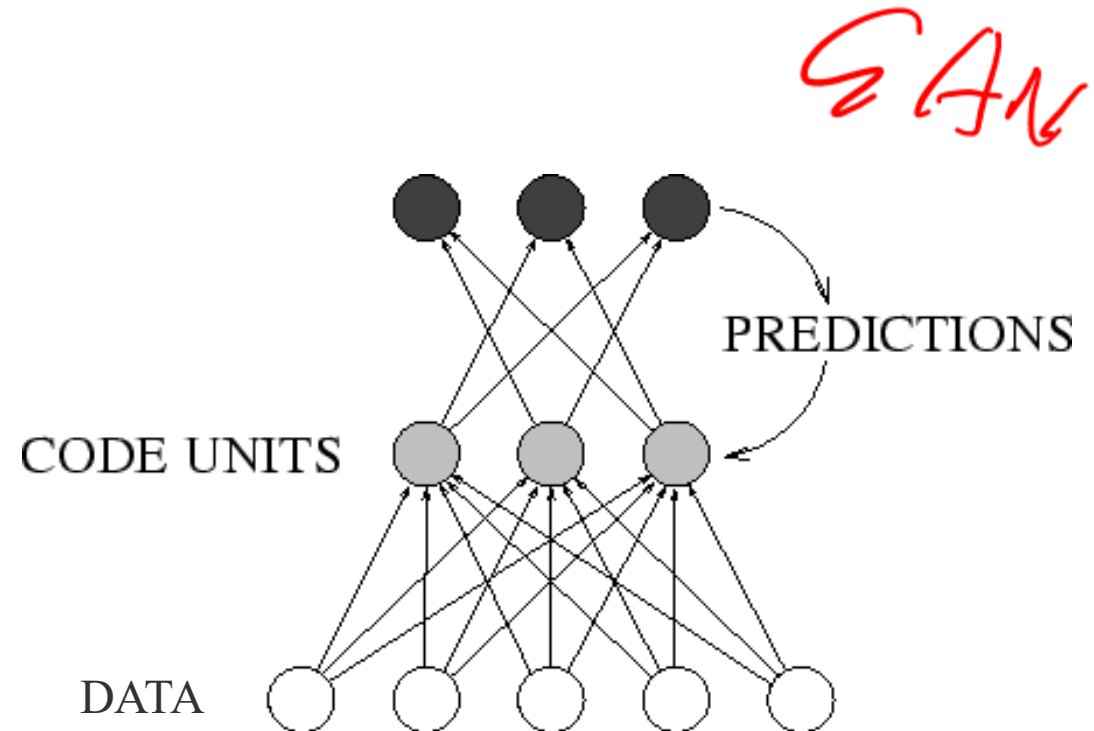
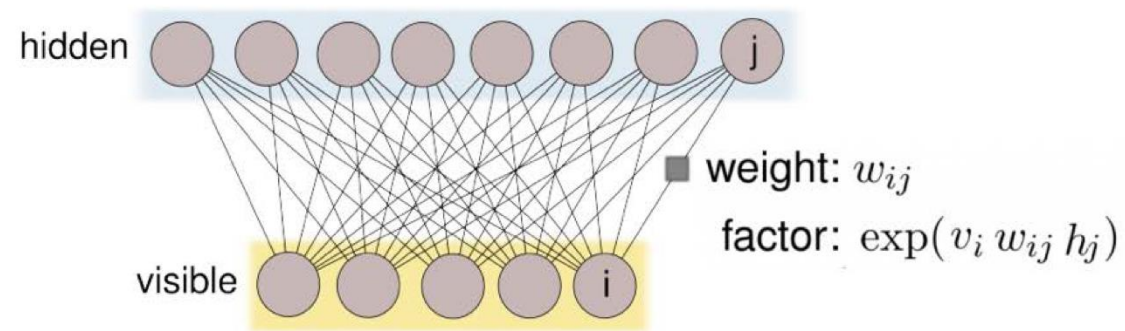


Figure courtesy: Schmidhuber 1996

Resurgence of deep generative models

- Restricted Boltzmann machines (RBMs) [Smolensky, 1986]
 - Building blocks of deep probabilistic models

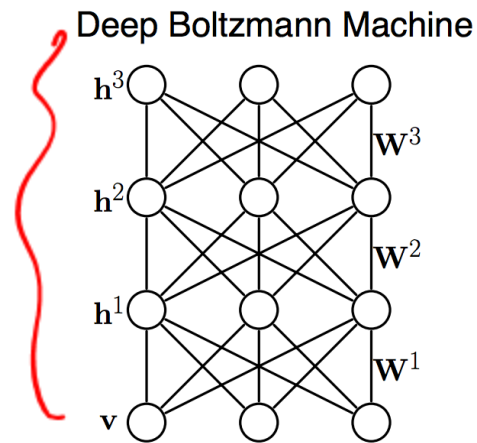
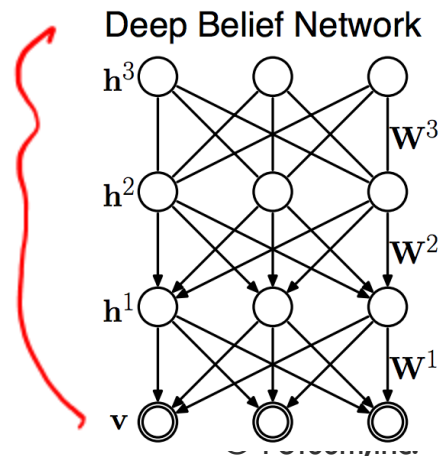


Resurgence of deep generative models

- Restricted Boltzmann machines (RBMs) [Smolensky, 1986]
 - Building blocks of deep probabilistic models
- Deep belief networks (DBNs) [Hinton et al., 2006]
 - Hybrid graphical model
 - Inference in DBNs is problematic due to explaining away
- Deep Boltzmann Machines (DBMs) [Salakhutdinov & Hinton, 2009]
 - Undirected model

energy-based models (EBMs)
② AlexNet 2012

naive



Resurgence of deep generative models

- Variational autoencoders (VAEs) [Kingma & Welling, 2014]
/ Neural Variational Inference and Learning (NVIL) [Mnih & Gregor, 2014]

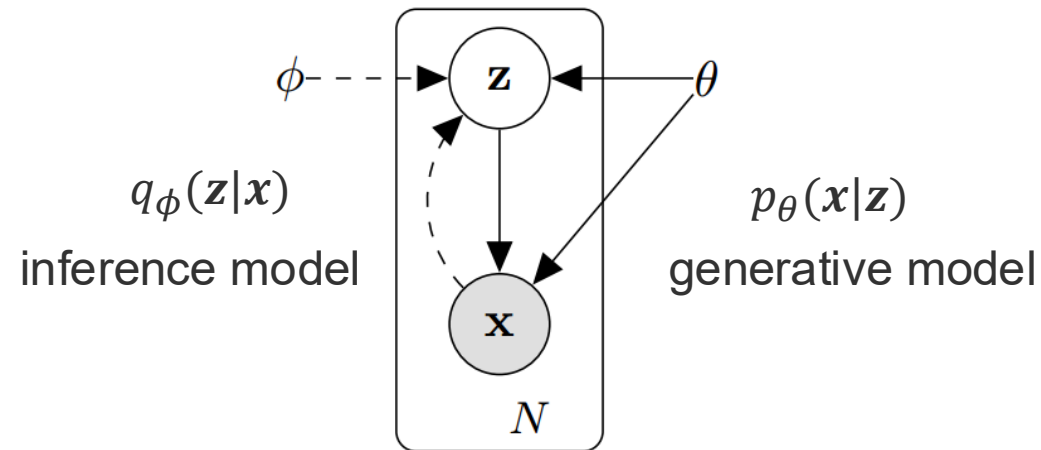


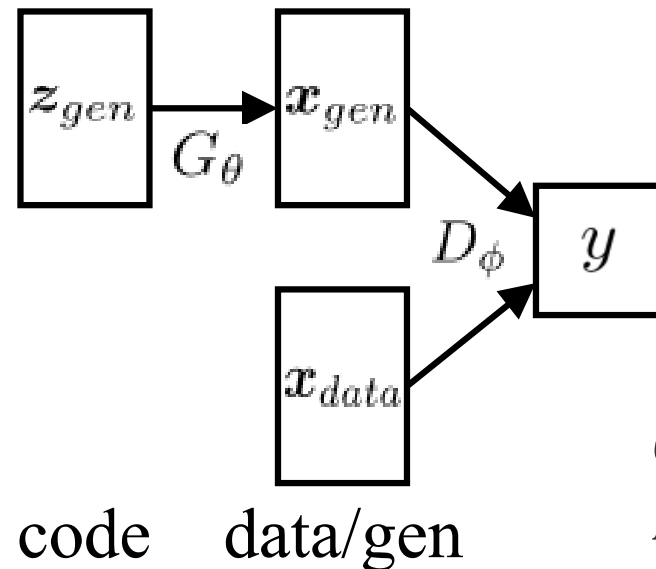
Figure courtesy: Kingma & Welling, 2014

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2024
ICML

NeurIPS



G_θ : generative model ?

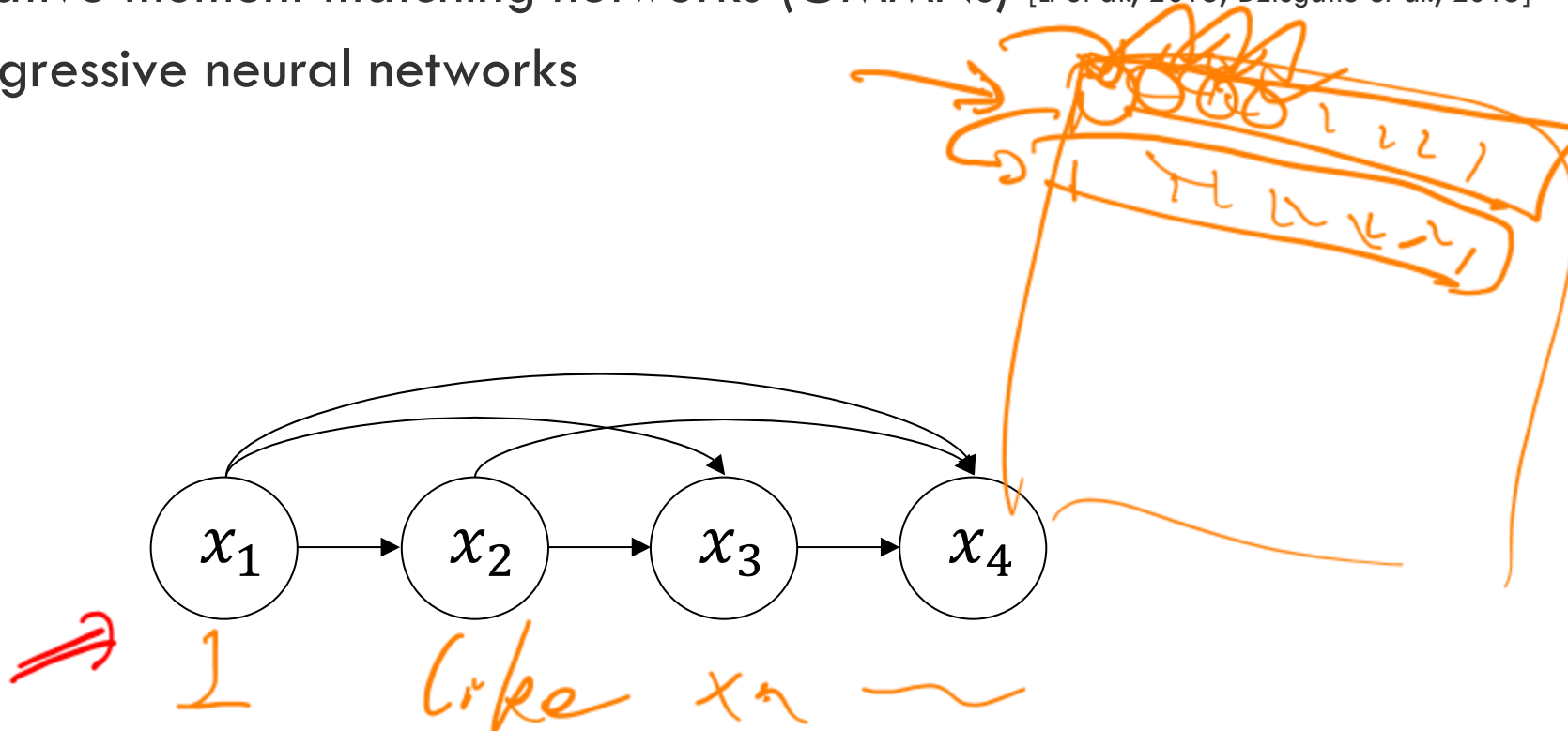
D_ϕ : discriminator

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- Generative moment matching networks (GMMNs) [Li et al., 2015; Dziugaite et al., 2015]

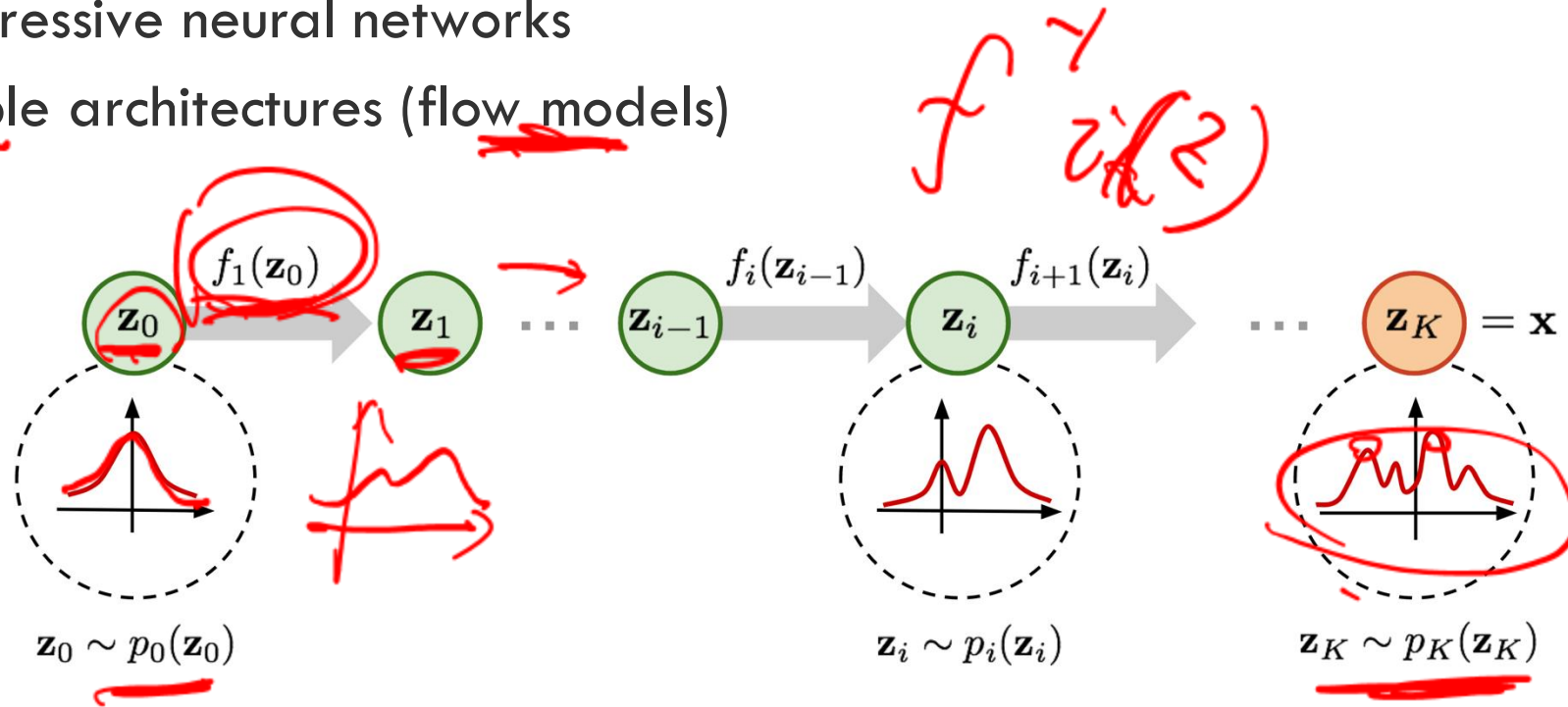
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- Autoregressive neural networks



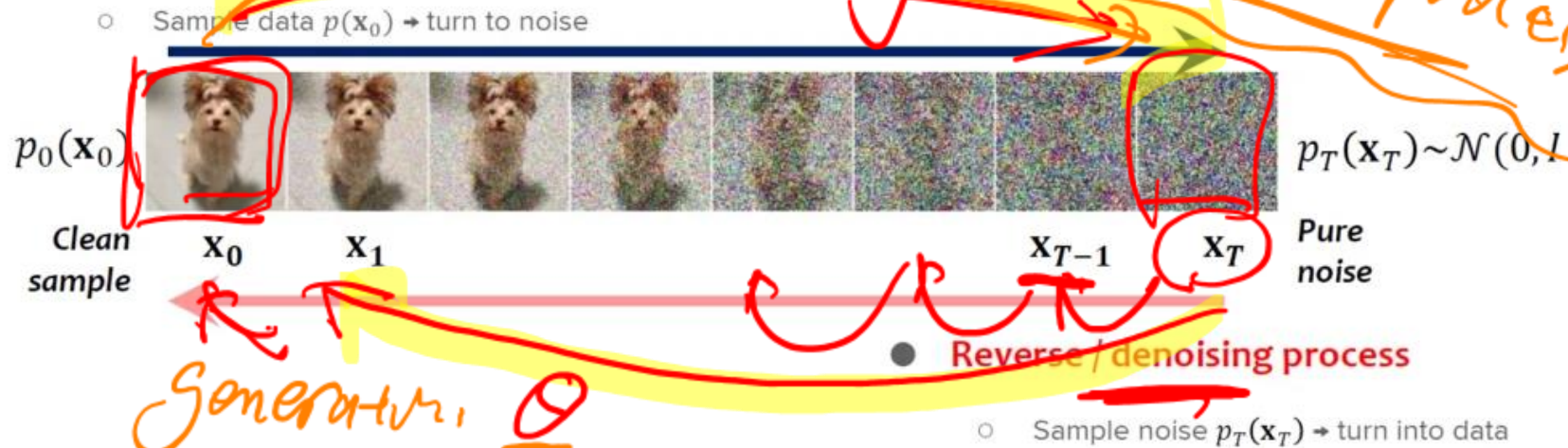
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- Reversible architectures (flow models)



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- Autoregressive neural networks \rightarrow LLM
- Reversible architectures (flow models)
- Diffusion models



Generative Adversarial Networks

GANs.

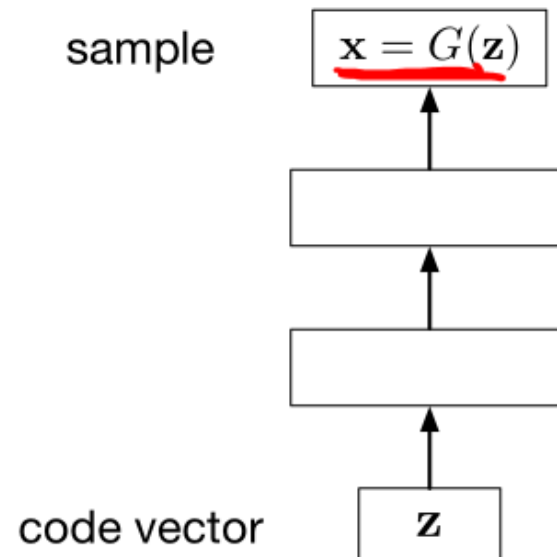
model

Generative Adversarial Learning

Implicit Generative Models

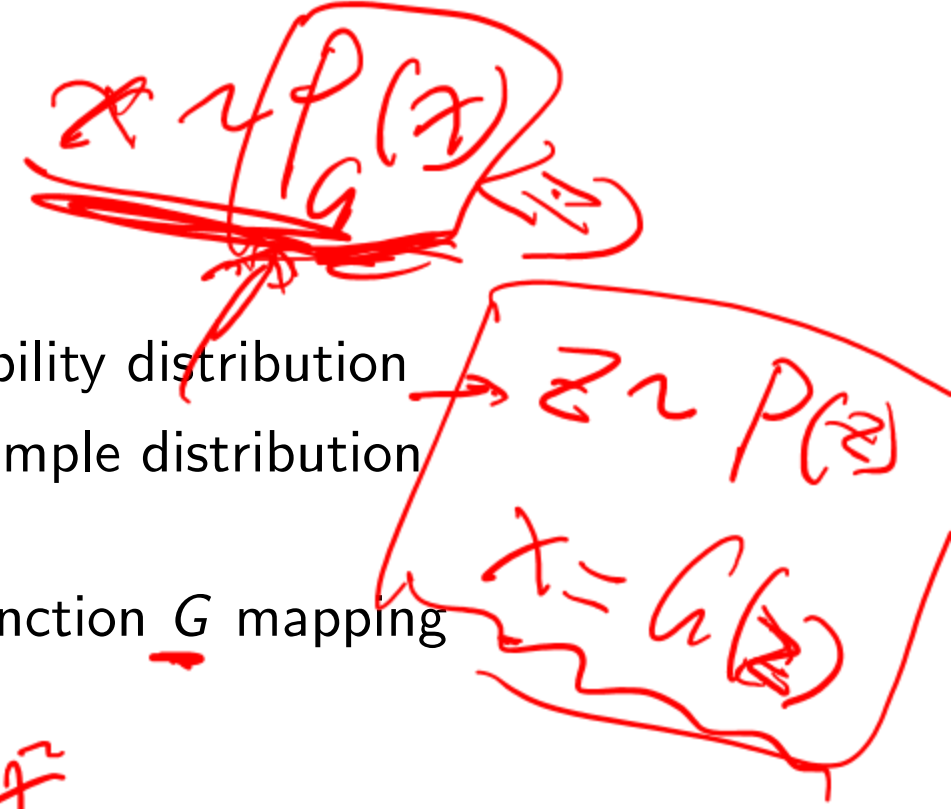
- Implicit generative models implicitly define a probability distribution
- Start by sampling the code vector \mathbf{z} from a fixed, simple distribution (e.g. spherical Gaussian)
- The generator network computes a differentiable function G mapping \mathbf{z} to an \mathbf{x} in data space

image



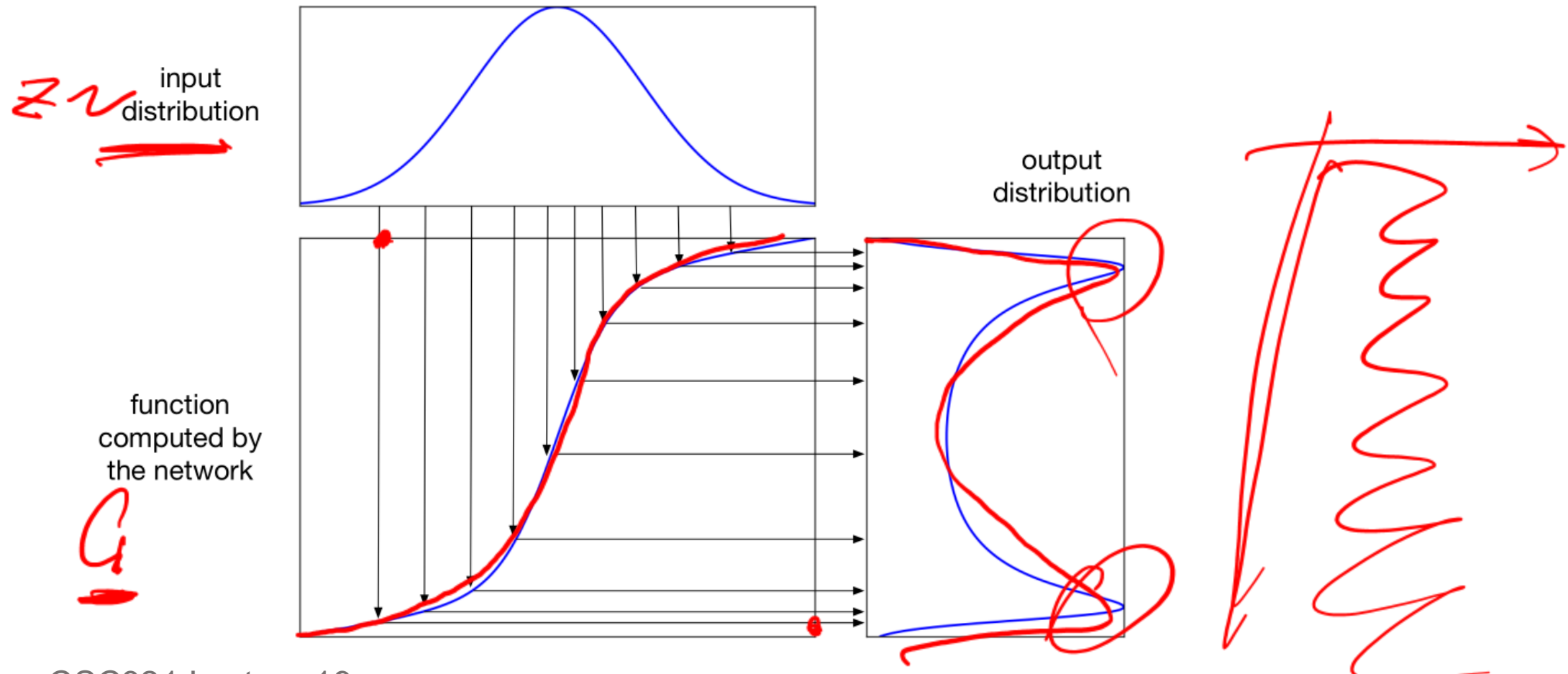
\mathcal{X}

- a stochastic process to simulate data \mathcal{X}
- Intractable to evaluate likelihood

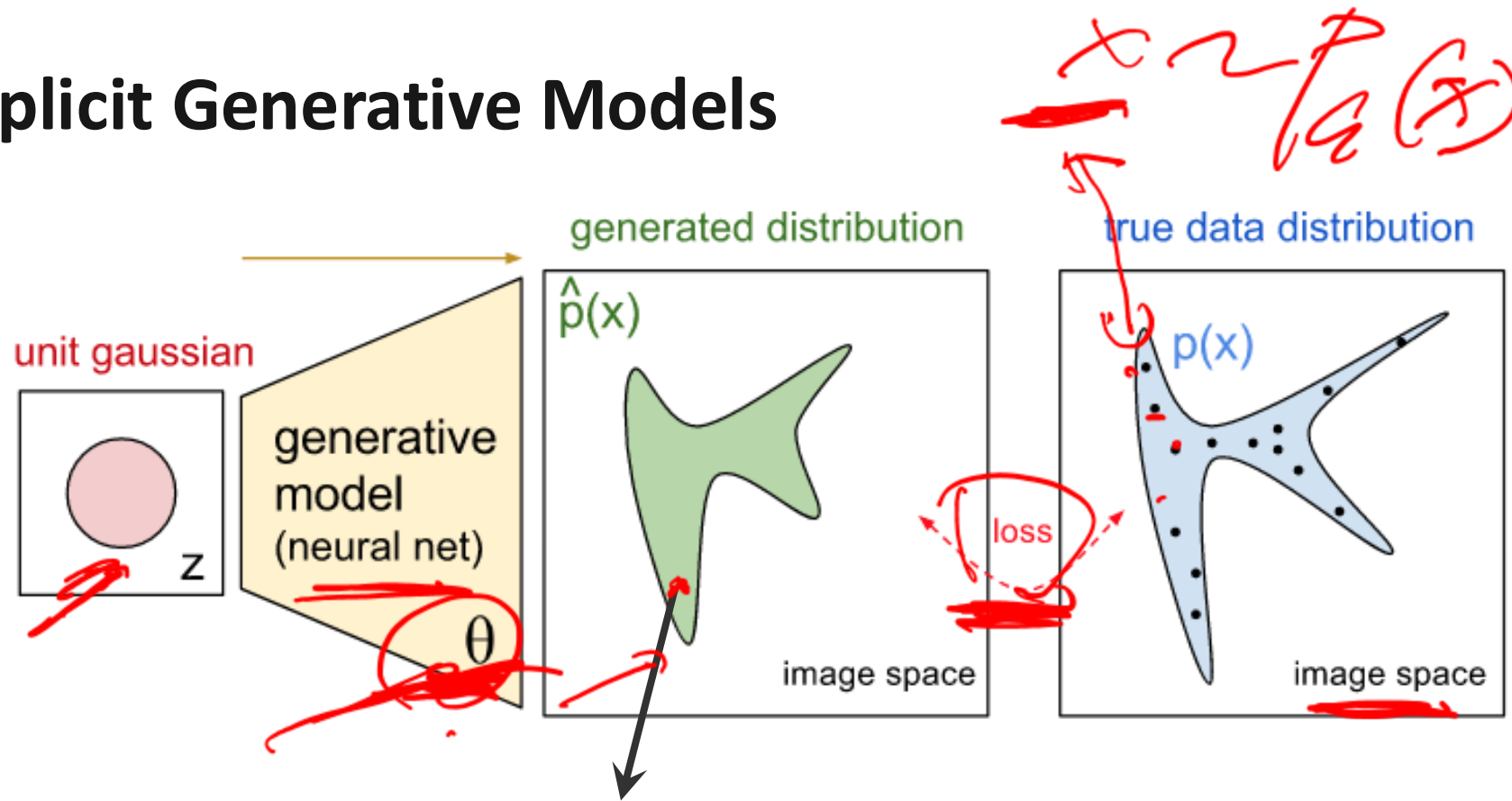


Implicit Generative Models

A 1-dimensional example:



Implicit Generative Models



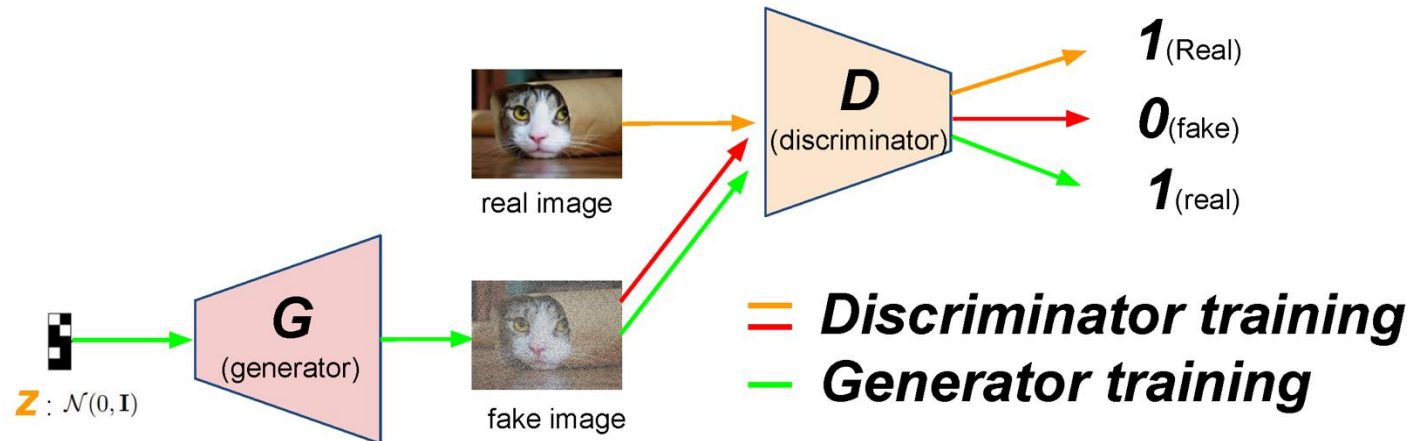
<https://blog.openai.com/generative-models/>

Implicit Generative Models

- The advantage of implicit generative models: if you have some criterion for evaluating the quality of samples, then you can compute its gradient with respect to the network parameters, and update the network's parameters to make the sample a little better
- The idea behind **Generative Adversarial Networks (GANs)**: train two different networks
 - The generator network tries to produce realistic-looking samples
 - The discriminator network tries to figure out whether an image came from the training set or the generator network
- The generator network tries to fool the discriminator network

Generative Adversarial Nets (GANs)

- Generative model $x = G_{\theta}(z)$, $z \sim p(z)$
 - Maps noise variable z to data space x
 - Defines an implicit distribution over x : $p_{g_{\theta}}(x)$
- Discriminator $D_{\phi}(x)$
 - Output the probability that x came from the data rather than the generator

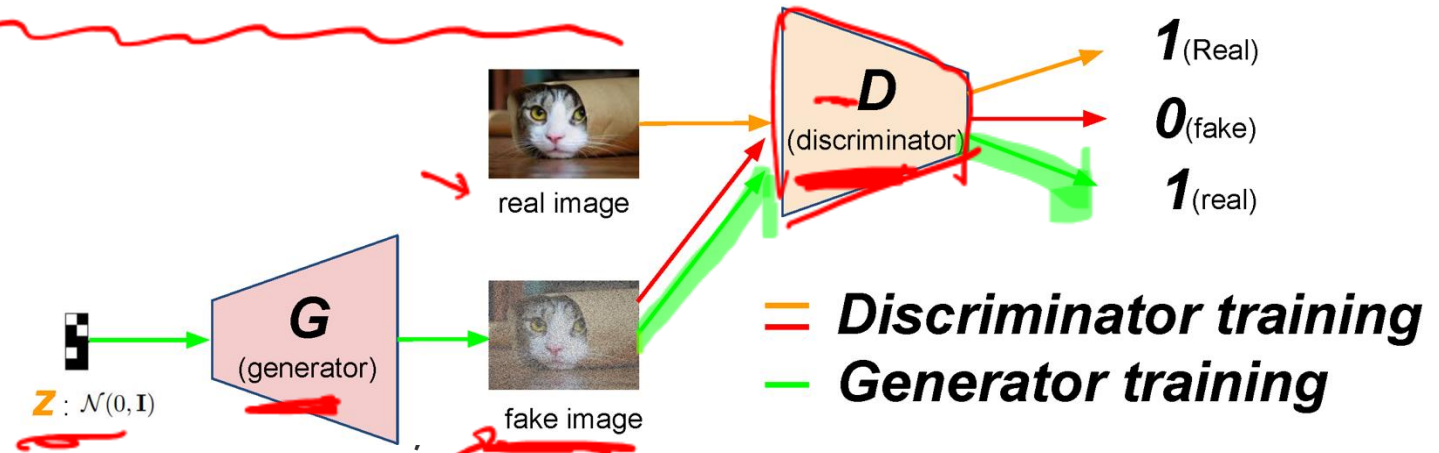


Generative Adversarial Nets (GANs)

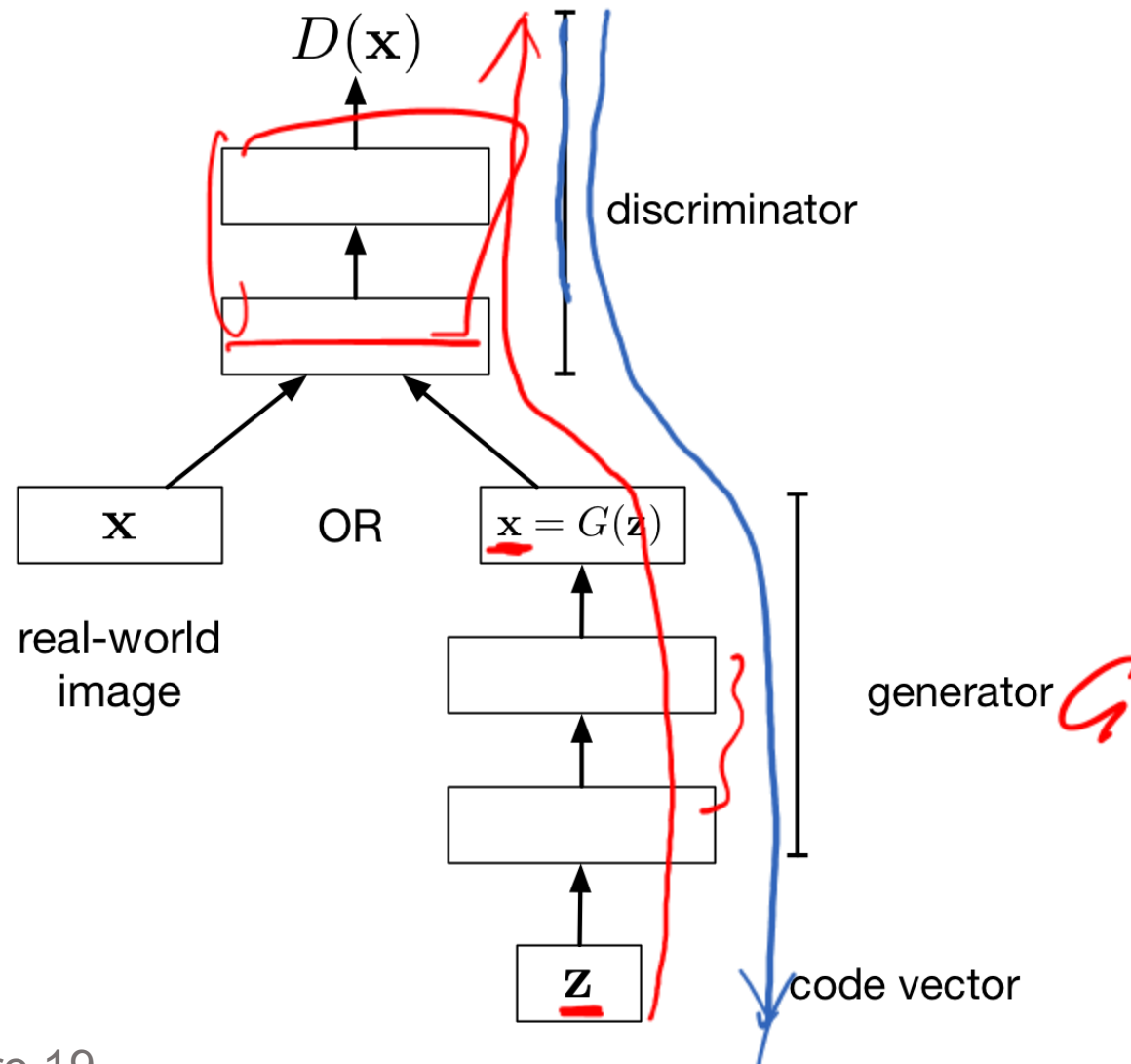
- Learning
 - A minimax game between the generator and the discriminator
 - Train D to maximize the probability of assigning the correct label to both training examples and generated samples
 - Train G to fool the discriminator

binary classification

$$\max_D \mathcal{L}_D = \mathbb{E}_{\mathbf{x} \sim p_{data}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{x} \sim G(\mathbf{z}), \mathbf{z} \sim p(\mathbf{z})} [\log(1 - D(\mathbf{x}))]$$
$$\min_G \mathcal{L}_G = \mathbb{E}_{\mathbf{x} \sim G(\mathbf{z}), \mathbf{z} \sim p(\mathbf{z})} [\log(1 - D(\mathbf{x}))].$$

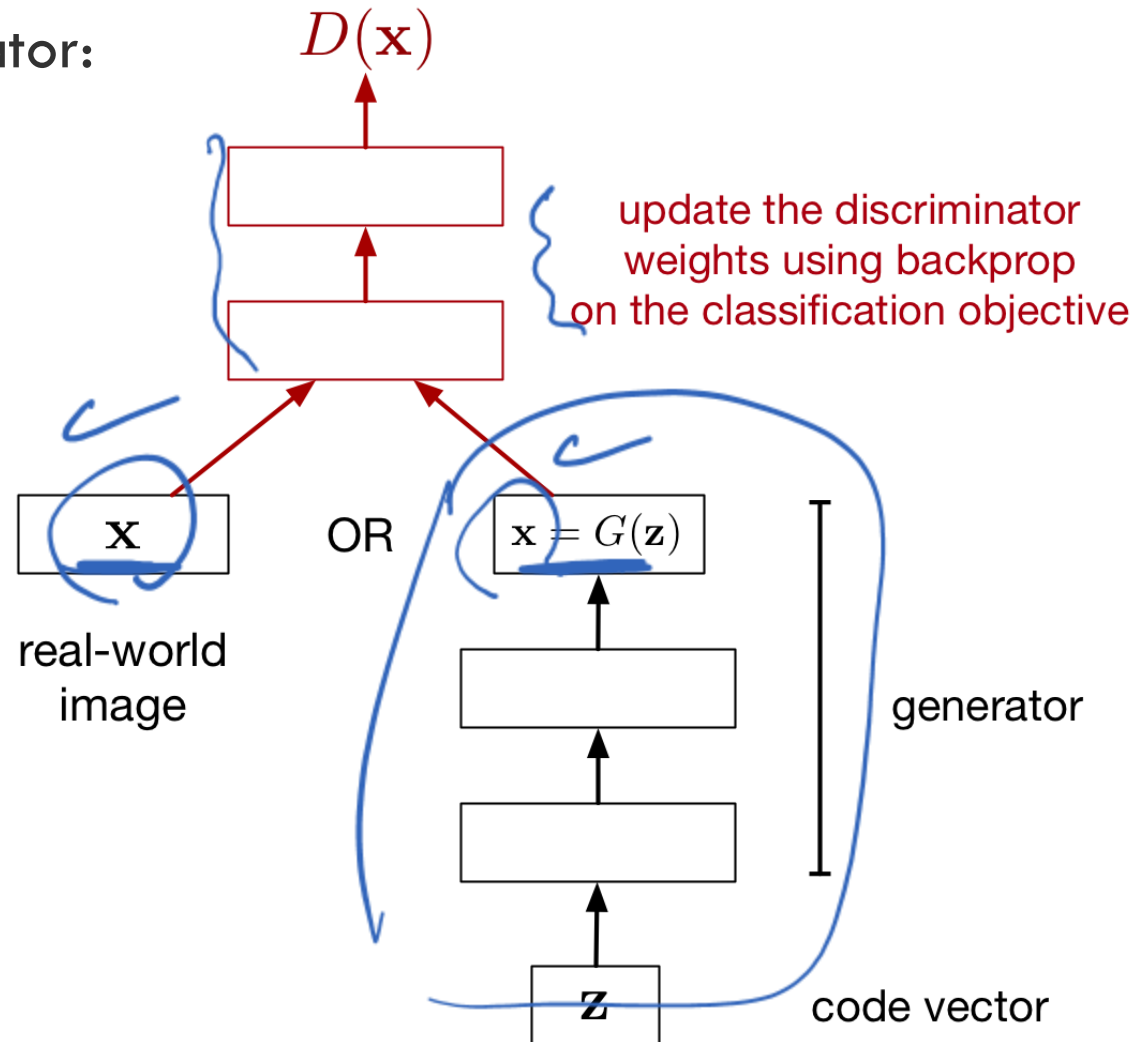


Generative Adversarial Nets (GANs)



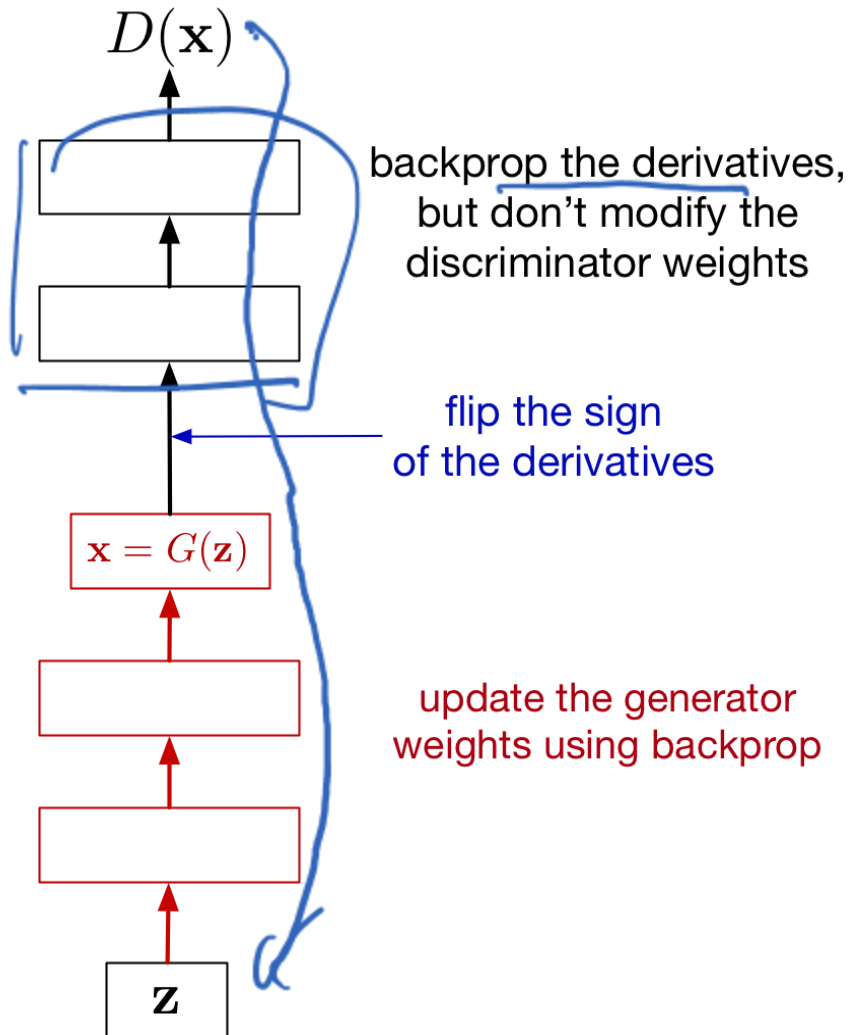
Generative Adversarial Nets (GANs)

Updating the discriminator:



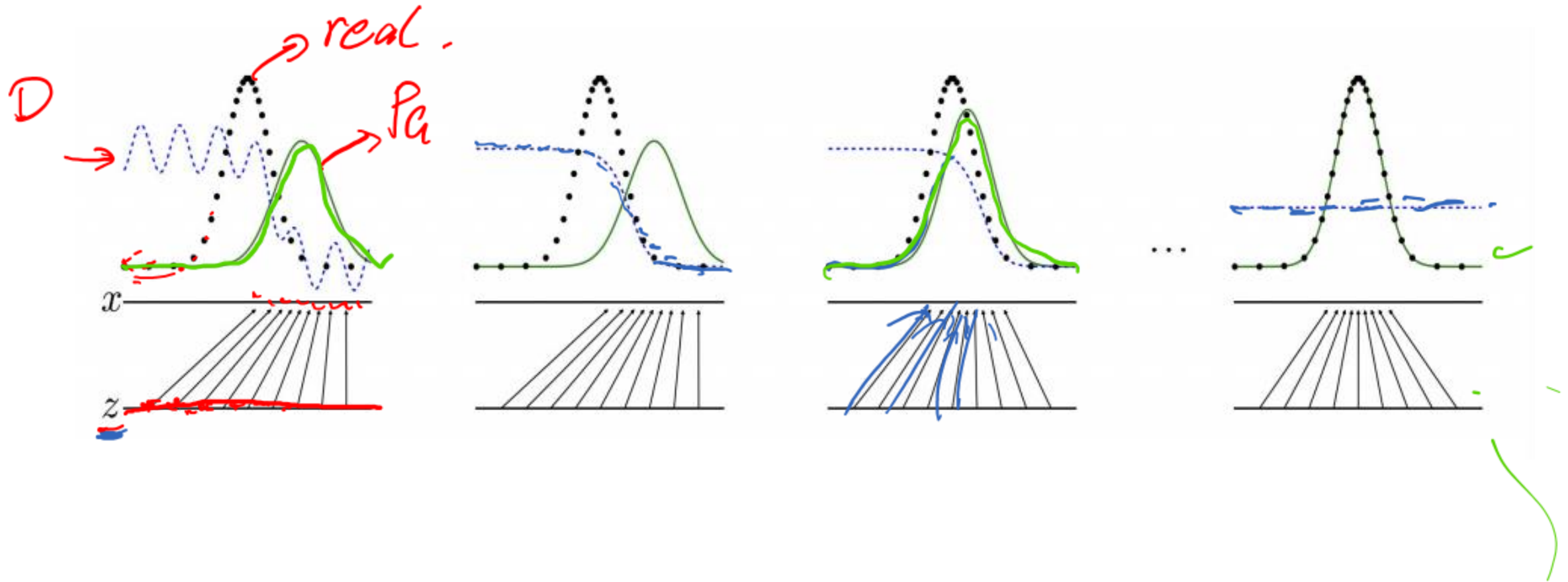
Generative Adversarial Nets (GANs)

Updating the generator:




Generative Adversarial Nets (GANs)

Alternating training of the generator and discriminator:



Optimality of GANs

- Objectives:


$$\begin{aligned}\max_D \mathcal{L}_D &= \mathbb{E}_{\mathbf{x} \sim p_{data}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{x} \sim G(\mathbf{z}), \mathbf{z} \sim p(\mathbf{z})} [\log(1 - D(\mathbf{x}))] \\ \min_G \mathcal{L}_G &= \mathbb{E}_{\mathbf{x} \sim G(\mathbf{z}), \mathbf{z} \sim p(\mathbf{z})} [\log(1 - D(\mathbf{x}))].\end{aligned}$$

- Global optimality: p_g = p_{data}
- Proof:

Optimality of GANs

Proposition 1. *For G fixed, the optimal discriminator D is*

$$D_G^*(\mathbf{x}) = \frac{p_{data}(\mathbf{x})}{p_{data}(\mathbf{x}) + p_g(\mathbf{x})} \quad (2)$$

Optimality of GANs

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$$D_G^*(\mathbf{x}) = \frac{p_{\text{data}}(\mathbf{x})}{p_{\text{data}}(\mathbf{x}) + p_g(\mathbf{x})} \quad (2)$$

Proof. The training criterion for the discriminator D , given any generator G , is to maximize the quantity $V(G, D)$

$$\begin{aligned} V(G, D) &= \int_{\mathbf{x}} p_{\text{data}}(\mathbf{x}) \log(D(\mathbf{x})) d\mathbf{x} + \int_{\mathbf{z}} p_{\mathbf{z}}(\mathbf{z}) \log(1 - D(g(\mathbf{z}))) d\mathbf{z} \\ &= \int_{\mathbf{x}} p_{\text{data}}(\mathbf{x}) \log(D(\mathbf{x})) + p_g(\mathbf{x}) \log(1 - D(\mathbf{x})) d\mathbf{x} \end{aligned} \quad (3)$$

For any $(a, b) \in \mathbb{R}^2 \setminus \{0, 0\}$, the function $y \rightarrow a \log(y) + b \log(1 - y)$ achieves its maximum in $[0, 1]$ at $\frac{a}{a+b}$.

Optimality of GANs

- The minimax game can now be reformulated as

$$C(G) = \max_D V(G, D)$$

$$= \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} [\log \underline{D_G^*}(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z} [\log(1 - \underline{D_G^*}(G(\mathbf{z})))]$$

$$= \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} [\log D_G^*(\mathbf{x})] + \mathbb{E}_{\mathbf{x} \sim p_g} [\log(1 - D_G^*(\mathbf{x}))]$$

$$= \underline{\mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} \left[\log \frac{p_{\text{data}}(\mathbf{x})}{p_{\text{data}}(\mathbf{x}) + p_g(\mathbf{x})} \right]} + \mathbb{E}_{\mathbf{x} \sim p_g} \left[\log \frac{p_g(\mathbf{x})}{p_{\text{data}}(\mathbf{x}) + p_g(\mathbf{x})} \right]$$

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Theorem 1. *The global minimum of the virtual training criterion $C(G)$ is achieved if and only if $p_g = p_{\text{data}}$. At that point, $C(G)$ achieves the value $-\log 4$.*

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$$\begin{aligned} C(G) &= -\log(4) + \text{KL} \left(p_{\text{data}} \left\| \frac{p_{\text{data}} + p_g}{2} \right\| \right) + \text{KL} \left(p_g \left\| \frac{p_{\text{data}} + p_g}{2} \right\| \right) \\ &= -\log(4) + 2 \cdot \text{JSD}(p_{\text{data}} \| p_g) \end{aligned}$$

VSD

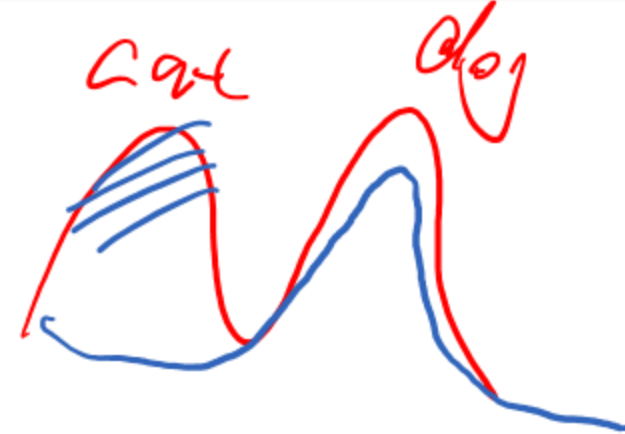
Jensen-Shannon Divergence

Question: in practice, we're unlikely to get the optimal D^* . In this case, what is the minimax game truly optimizing?

Optimality of GANs

- The minimax game can now be reformulated as

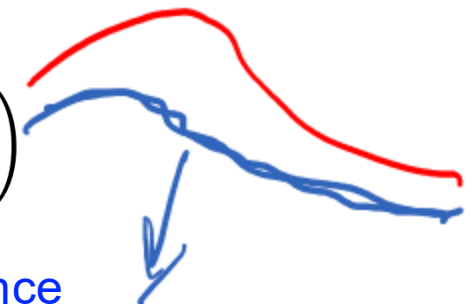
$$\begin{aligned}
 \min_G C(G) &\stackrel{\text{min}}{=} \max_D V(G, D) \\
 &= \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} [\log D_G^*(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z} [\log(1 - D_G^*(G(\mathbf{z})))] \\
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Theorem 1. The global minimum of the virtual training criterion $C(G)$ is achieved if and only if $p_g = p_{\text{data}}$. At that point, $C(G)$ achieves the value $-\log 4$.

$$\begin{aligned}
 C(G) &= -\log(4) + KL \left(p_{\text{data}} \left\| \frac{p_{\text{data}} + p_g}{2} \right\| \right) + KL \left(p_g \left\| \frac{p_{\text{data}} + p_g}{2} \right\| \right) \\
 &= -\log(4) + 2 \cdot JSD(p_{\text{data}} \| p_g)
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Jensen-Shannon Divergence



Wasserstein GAN (WGAN)

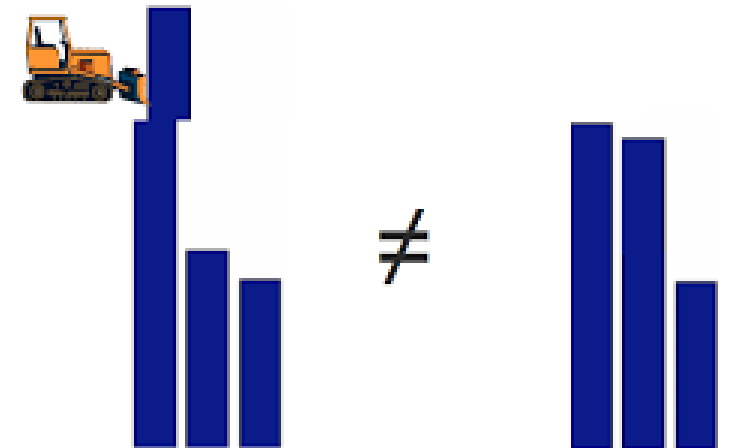
- If our data are on a **low-dimensional** manifold of a high dimensional space, the model's manifold and the true data manifold can have a **negligible intersection in practice**

Wasserstein GAN (WGAN)

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- The loss function and gradients may not be continuous and well behaved

Wasserstein GAN (WGAN)

- If our data are on a **low-dimensional** manifold of a high dimensional space, the model's manifold and the true data manifold can have a **negligible intersection in practice**
- The loss function and gradients may not be continuous and well behaved
- The **Wasserstein Distance** is well defined
 - Earth Mover's Distance
 - Minimum transportation cost for making one pile of dirt in the shape of one probability distribution to the shape of the other distribution



Wasserstein GAN (WGAN)

- Objective

$$W(p_{data}, p_g) = \frac{1}{K} \sup_{\|D\|_L \leq K} \mathbb{E}_{x \sim p_{data}} [D(x)] - \mathbb{E}_{x \sim p_g} [D(x)]$$

- $\|D\|_L \leq K$: K- Lipschitz continuous
- Use gradient-clipping to ensure D has the Lipschitz continuity

Progressive GAN

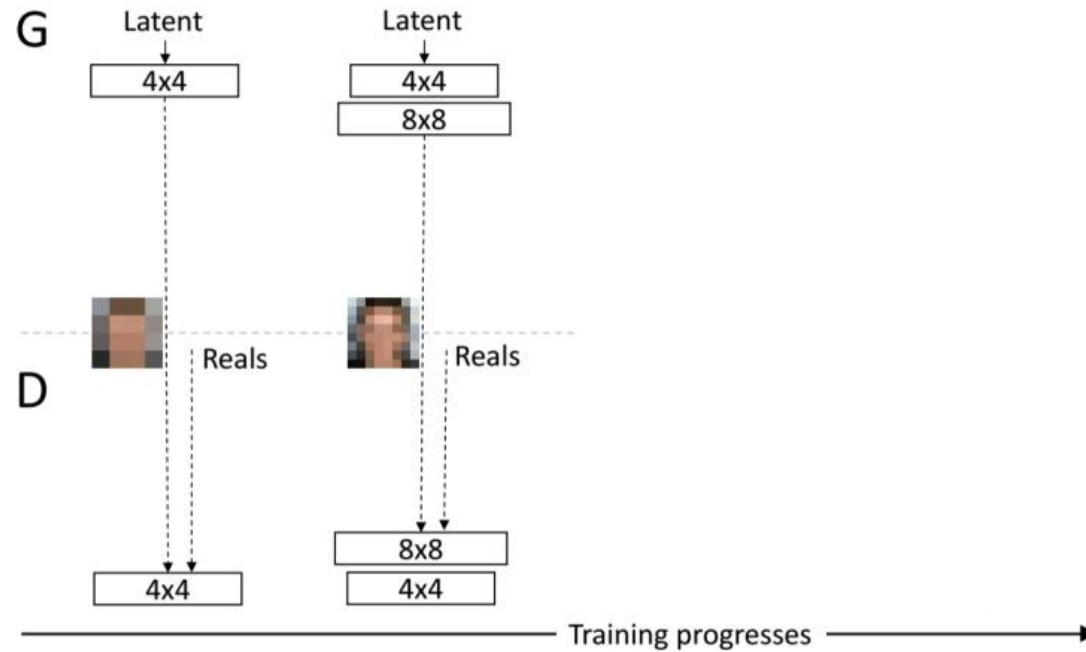
Low resolution images



Progressive GAN

Low resolution images

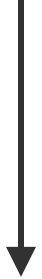
add in
additional
layers



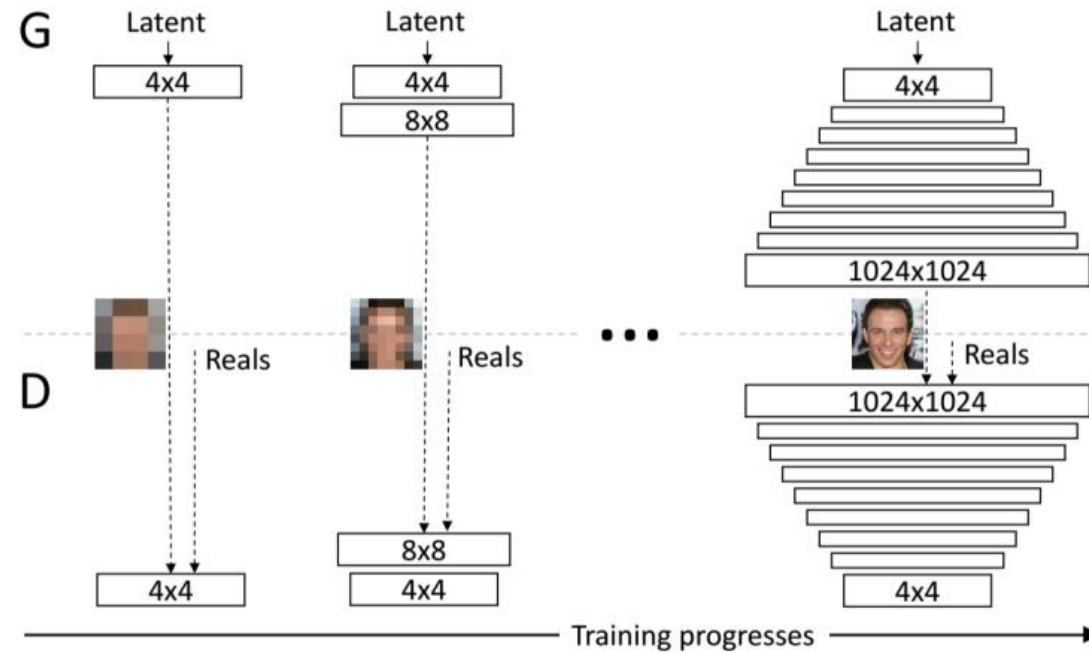
Progressive GAN

Low resolution images

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High resolution images



BigGAN

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- GANs benefit dramatically from **scaling**

BigGAN

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- 2x – 4x more parameters
- 8x larger batch size
- Simple architecture changes that improve scalability

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BigGAN

- GANs benefit dramatically from **scaling**
- 2x → 4x more parameters
- 8x
- Sim



Key Takeaways

- Deep Generative Models: brief history
- GANs:
 - Implicit generative model
 - Minimax formulation
 - Wasserstein GAN

Questions?