DSC250: Advanced Data Mining

Graph Neural Networks

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Lecture 13, Feb 18, 2025

UC San Diego
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Outline

- Graph neural networks

- Presentation
  - Yuan Lu, Songyao Jin: "Auto-Encoding Variational Bayes"
  - Shweta Nalluri, Keertana Kappuram: "Multi-task retriever fine-tuning for domain-specific and efficient RAG"
  - Jingman Wang, Jiayue Xu: "LLM-Enhanced Data Management"
  - Shanglin Zeng, Tianle Wang: "Learning Concise and Descriptive Attributes for Visual Recognition"

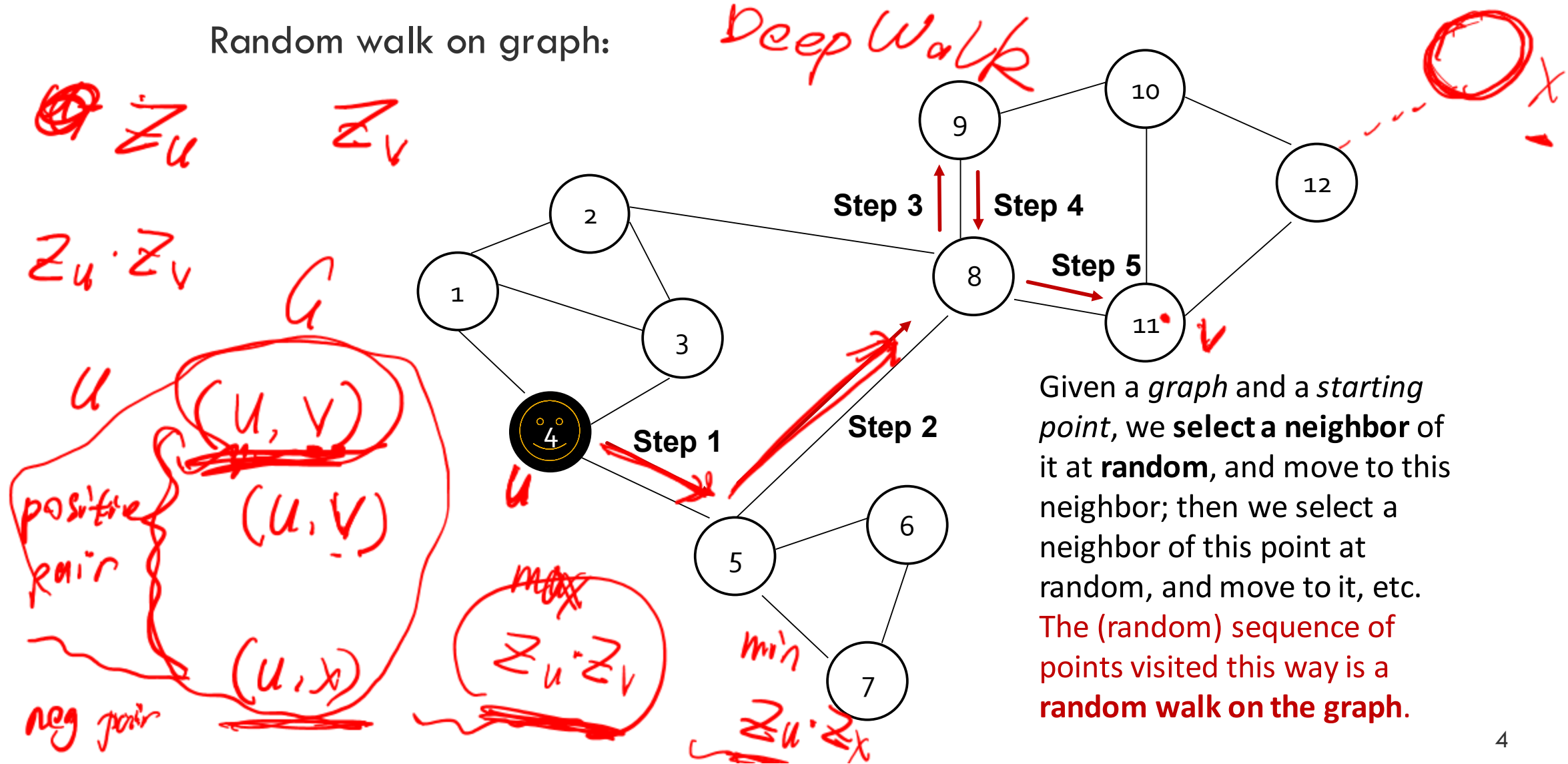
Recap: Summary

- **Encoder + Decoder Framework**
  - Shallow encoder: embedding lookup
  - Parameters to optimize: $\mathbf{Z}$ which contains node embeddings $\mathbf{z}_u$ for all nodes $u \in V$
  - We will cover deep encoders in the GNNs

  - **Decoder:** based on node similarity.
  - **Objective:** maximize $\mathbf{z}_v^{\mathrm{T}} \mathbf{z}_u$ for node pairs (u, v) that are **similar**

Recap: Similarity Function based on Random Walk

Random walk on graph:



Given a *graph* and a *starting point*, we **select a neighbor** of it at **random**, and move to this neighbor; then we select a neighbor of this point at random, and move to it, etc.
The (random) sequence of points visited this way is a **random walk on the graph**.

$$\text{similarity}(u, v) \approx \mathbf{z}_v^{\mathrm{T}} \mathbf{z}_u$$

Recap: Similarity Function based on Random Walk

$$\mathbf{z}_u^{\mathrm{T}} \mathbf{z}_v \approx$$

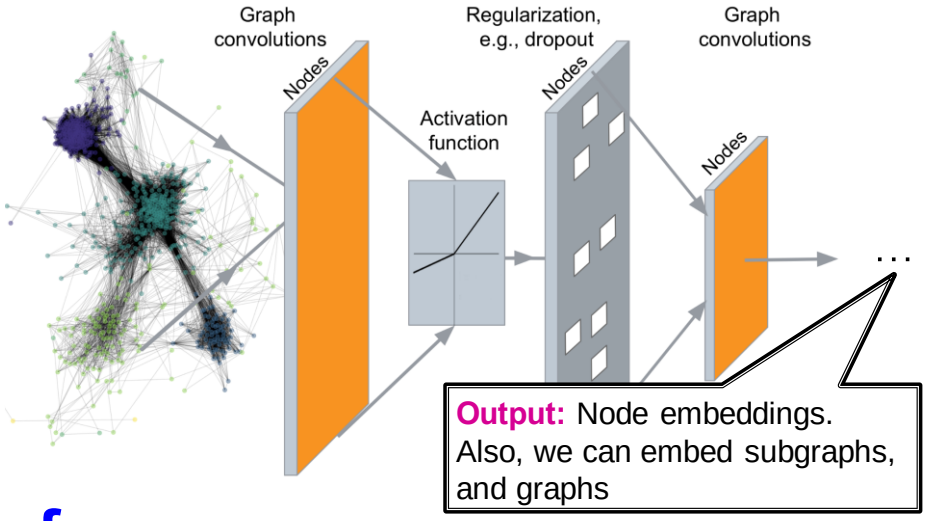
probability that **u** and **v** co-occur on a random walk over the graph

DeepWalk

node2vec

Recap: Deep Graph Encoders

- Encoding based on graph neural networks



$$\text{ENC}(v) =$$ **multiple layers of non-linear transformations based on graph structure**

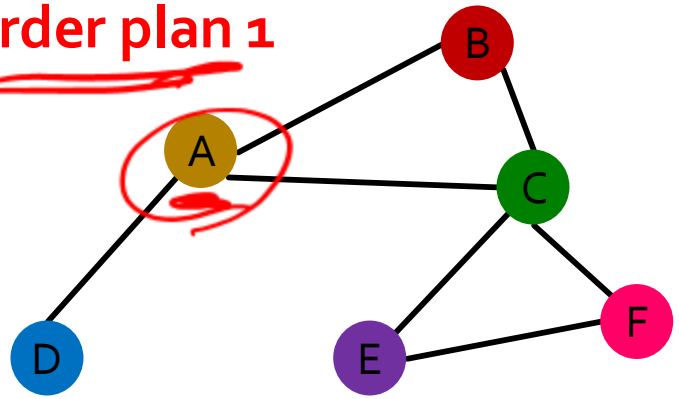
v.s. **Shallow Encoder:**

$$\text{ENC}(v) = \mathbf{z}_v = \mathbf{Z} \cdot v$$

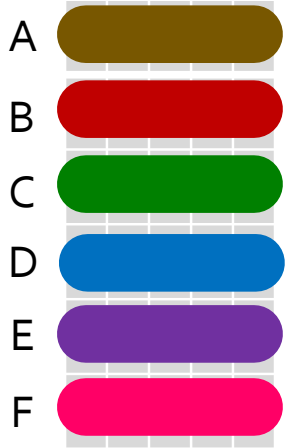
Recap: Permutation Invariance

- **Graph does not have a canonical order of the nodes!**

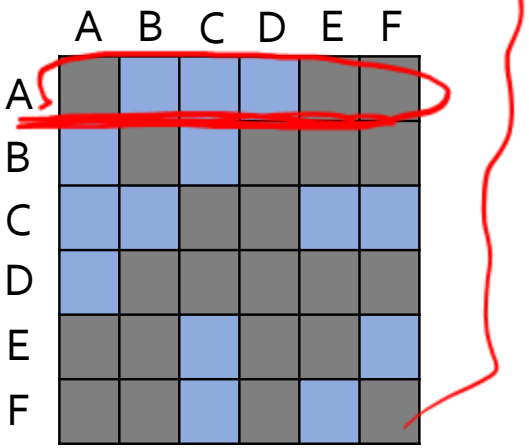
Order plan 1



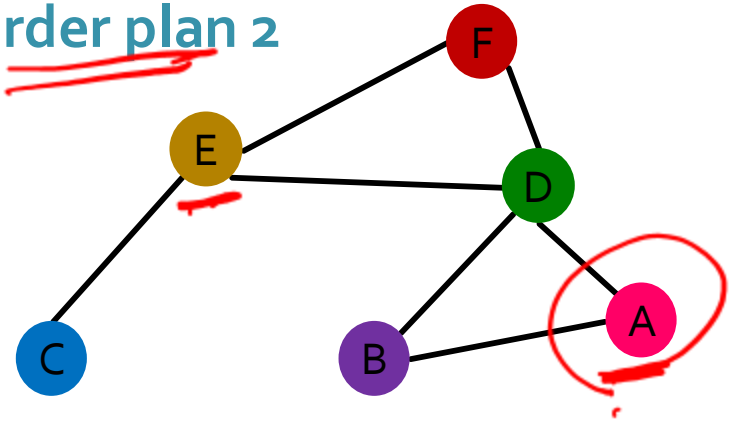
Node features X_1



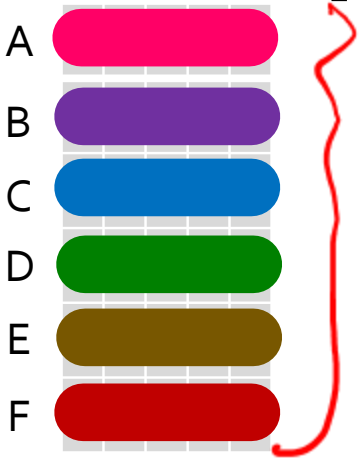
Adjacency matrix A_1



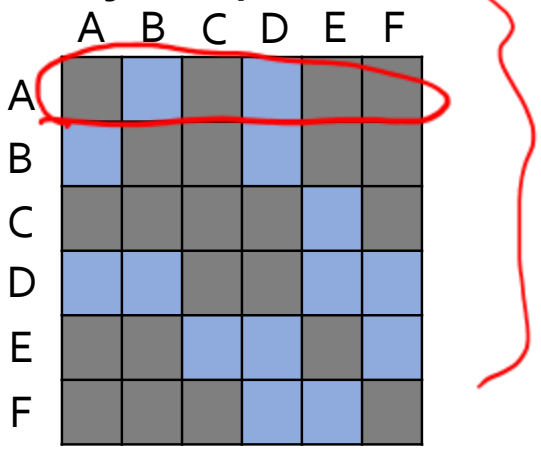
Order plan 2



Node features X_2



Adjacency matrix A_2



Recap: Permutation Invariance

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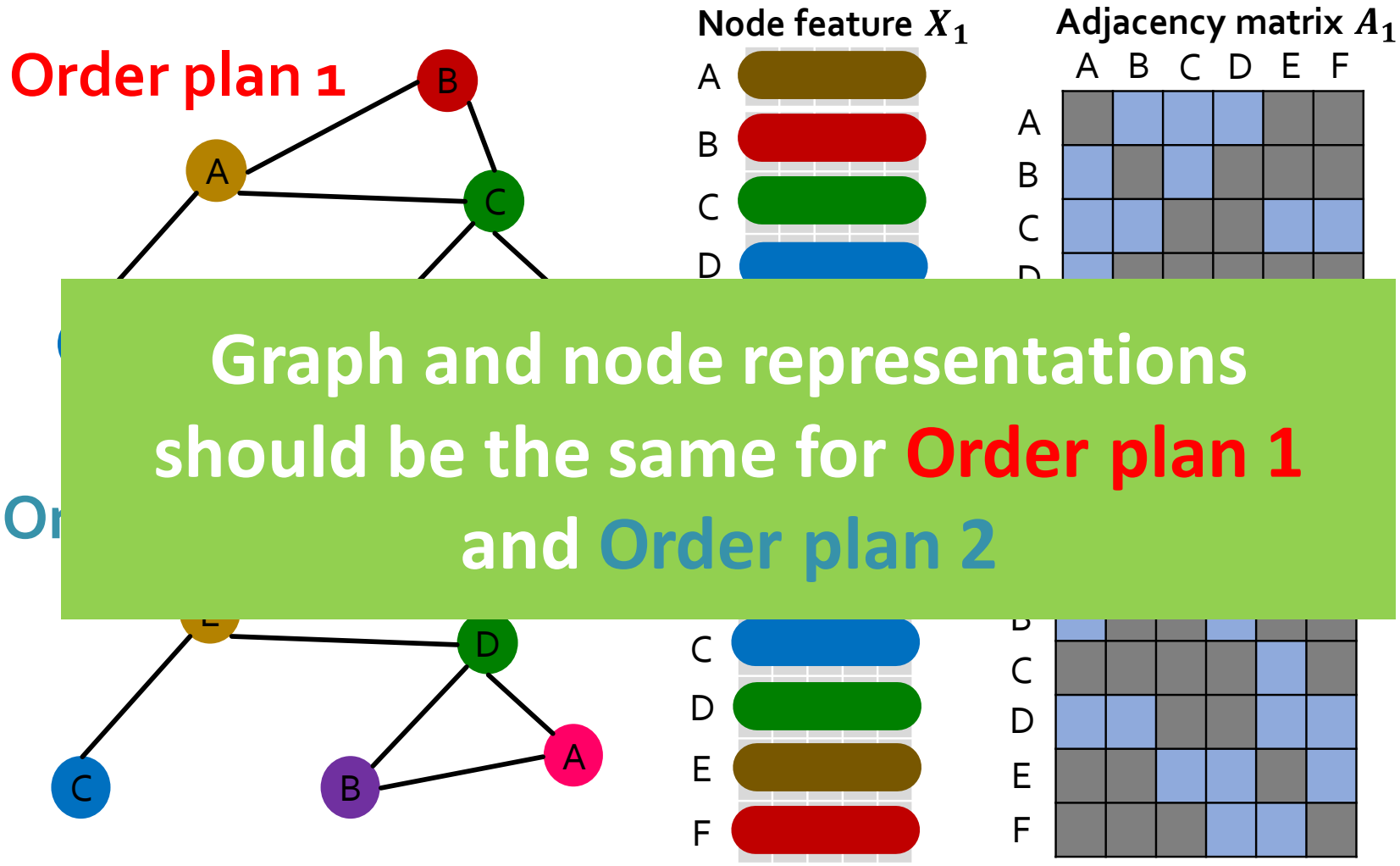


Recap: Permutation Invariance

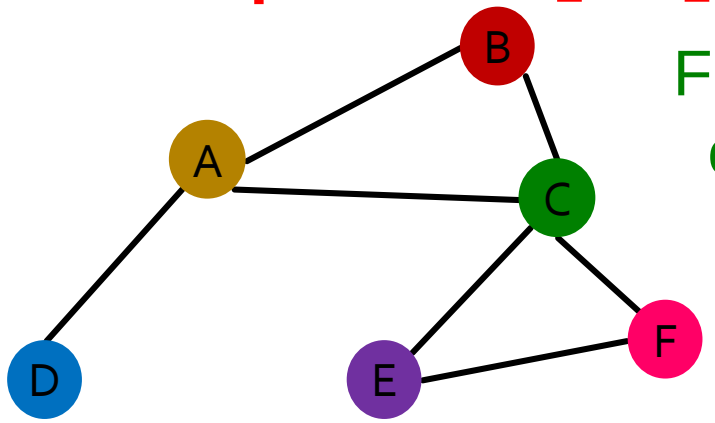
What does it mean by "graph representation is same for two order plans"?

- Consider we learn a function f that maps a graph $G = (\boldsymbol{A}, \boldsymbol{X})$ to a vector $\mathbb{R}^d$ then

$$f(\boldsymbol{A}_1, \boldsymbol{X}_1) = f(\boldsymbol{A}_2, \boldsymbol{X}_2)$$

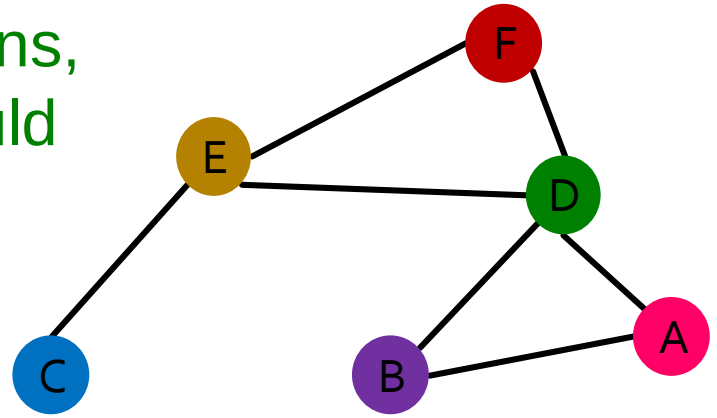
$\boldsymbol{A}$ is the adjacency matrix
$\boldsymbol{X}$ is the node feature matrix

Order plan 1: $\boldsymbol{A}_1, \boldsymbol{X}_1$



For two order plans, output of f should be the same!

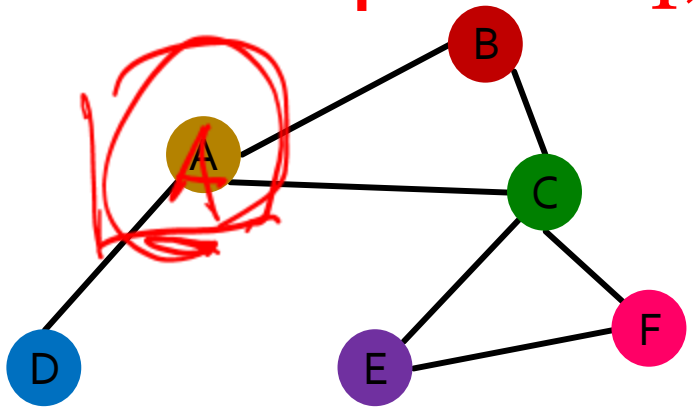
Order plan 2: $\boldsymbol{A}_2, \boldsymbol{X}_2$



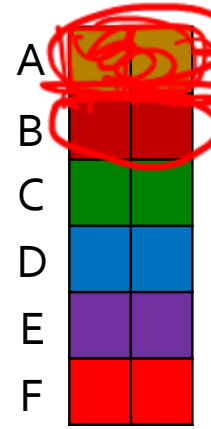
Recap: Permutation Equivariance

For node representation: We learn a function f that maps nodes of G to a matrix $\mathbb{R}^{m \times d}$.

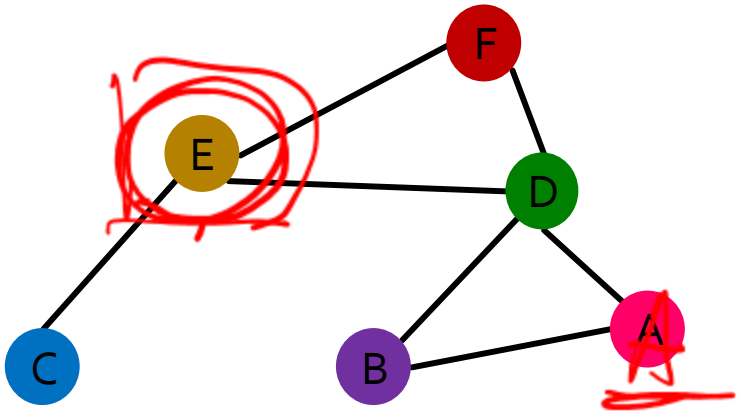
Order plan 1: A_1, X_1



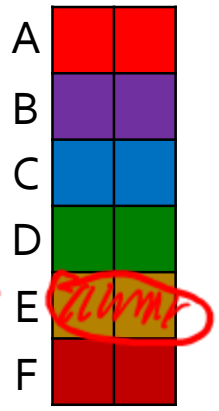
$$f(A_1, X_1) =$$



Order plan 2: A_2, X_2

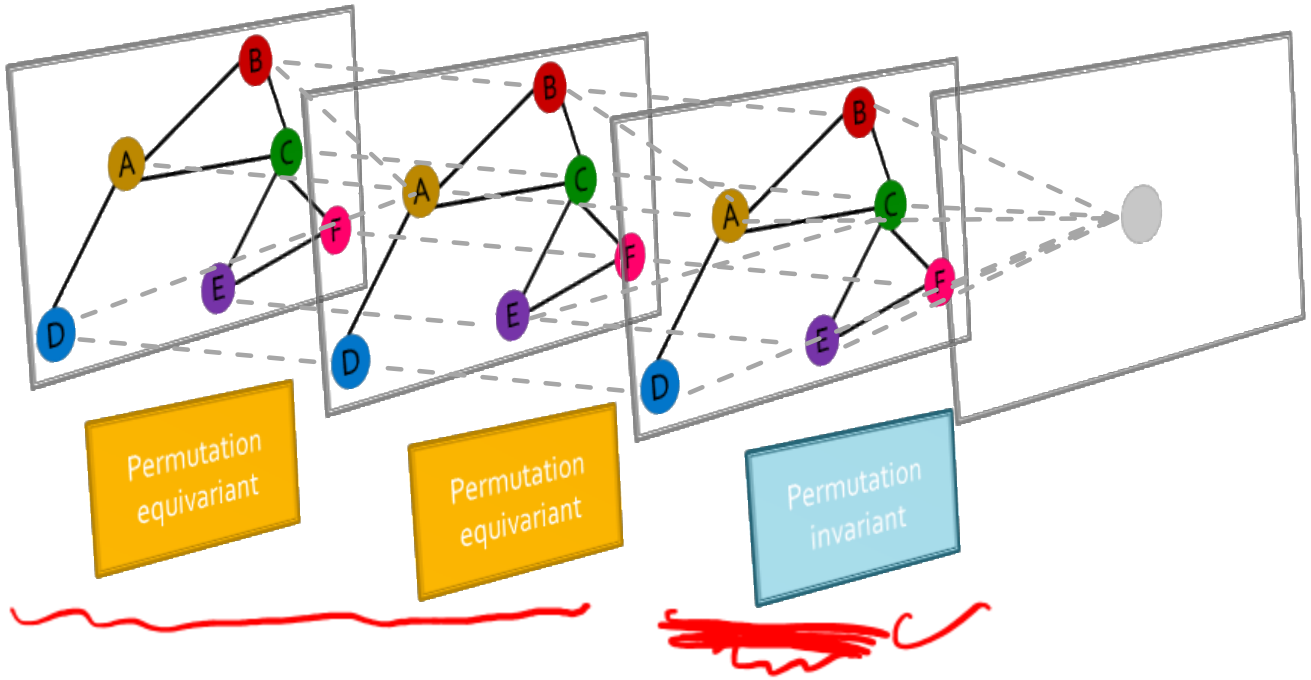


$$f(A_2, X_2) =$$



Recap: Graph Neural Networks Overview

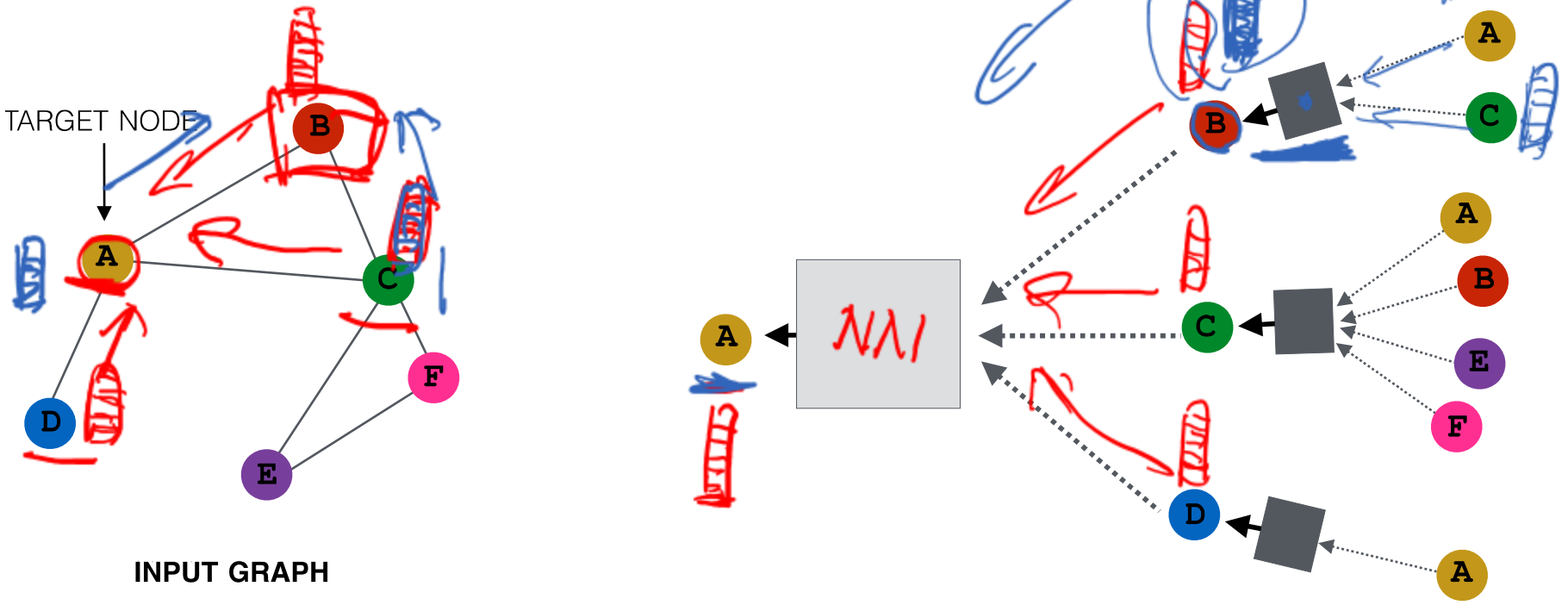
- GNNs consist of multiple permutation equivariant / invariant functions



- Next: Design GNNs that are permutation equivariant / invariant by **passing and aggregating information from neighbors**

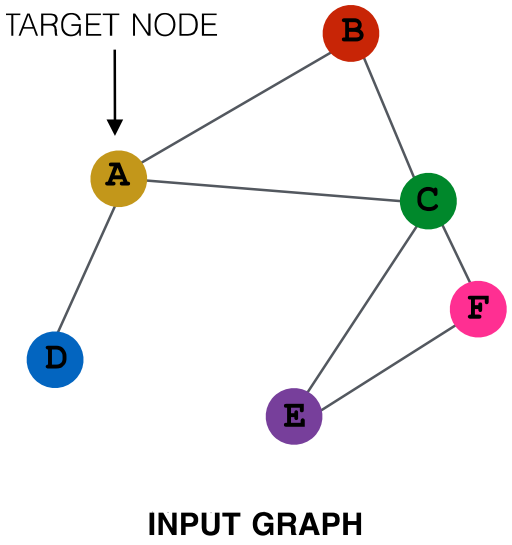
Idea: Aggregate Neighbors

- **Key idea:** Generate node embeddings based on **local network neighborhoods**

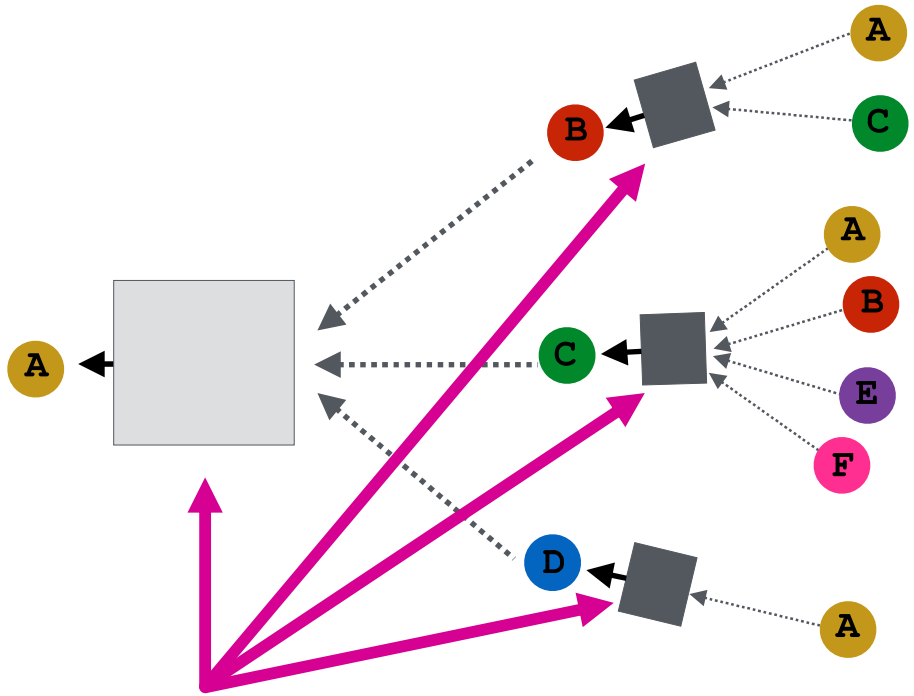


Idea: Aggregate Neighbors

- **Intuition:** Nodes aggregate information from their neighbors using neural networks



INPUT GRAPH

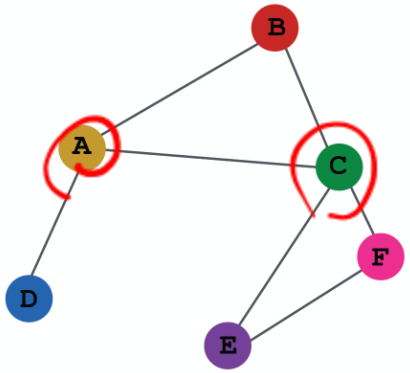


Neural networks

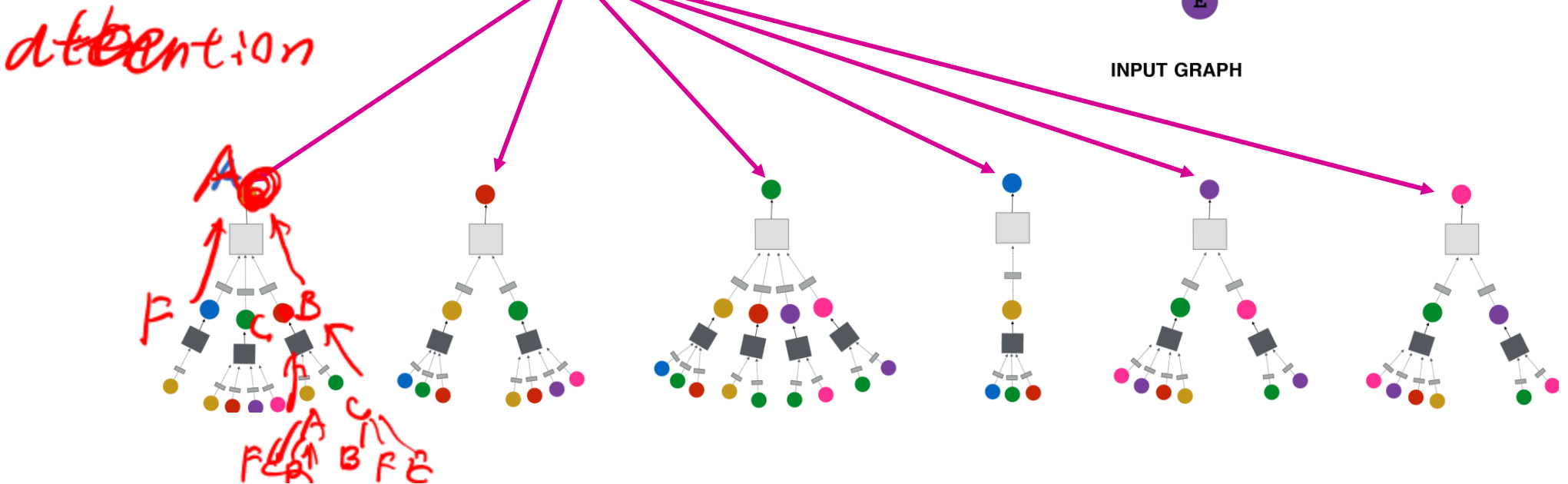
Idea: Aggregate Neighbors

- **Intuition:** Network neighborhood defines a computation graph

Every node defines a computation graph based on its neighborhood!

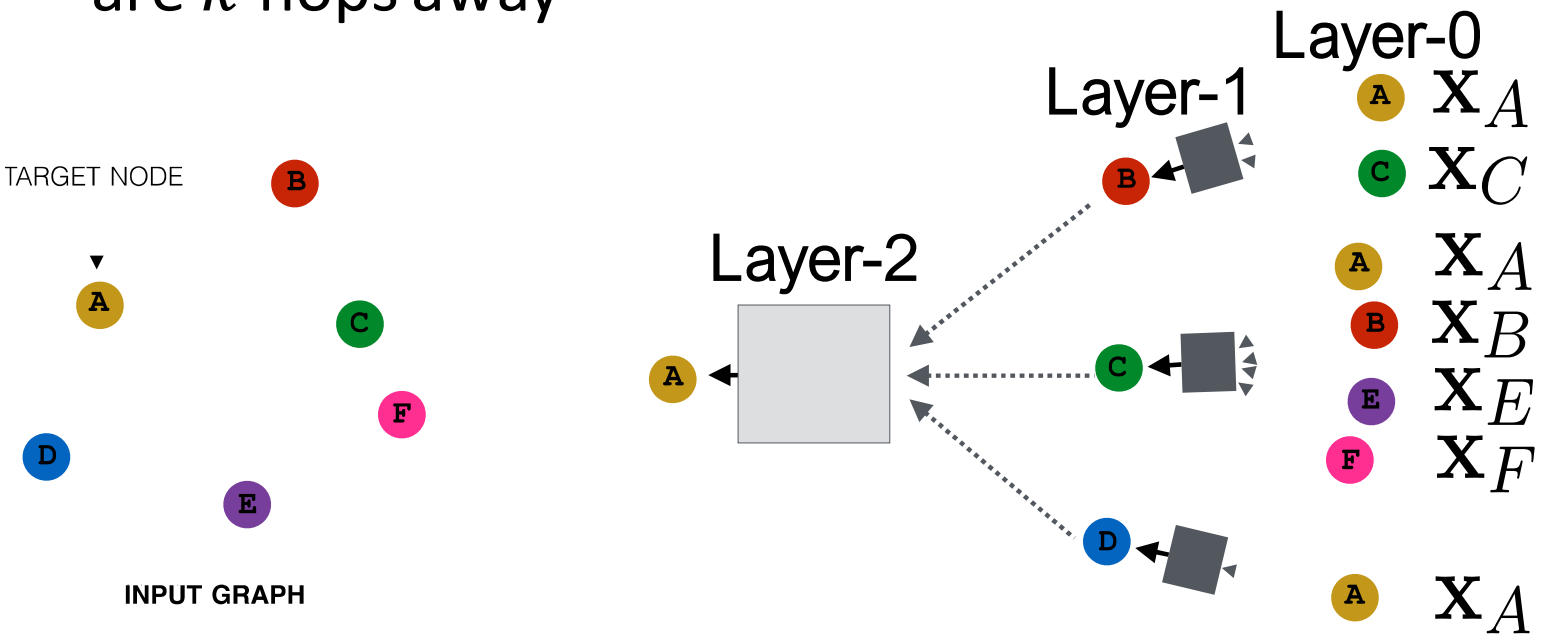


INPUT GRAPH



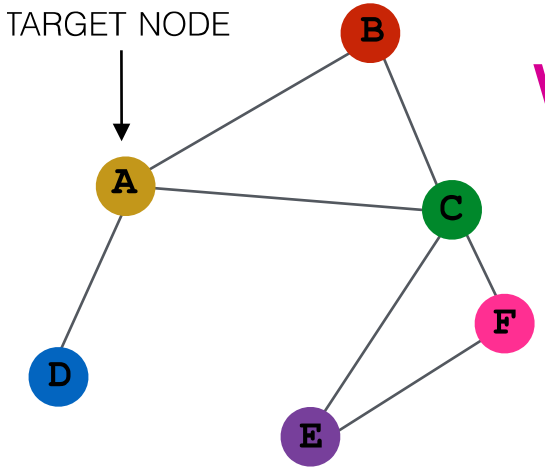
Deep Model: Many Layers

- Model can be of arbitrary depth:
  - Nodes have embeddings at each layer
  - Layer-0 embedding of node v is its input feature, x_v
  - Layer-k embedding gets information from nodes that are k hops away

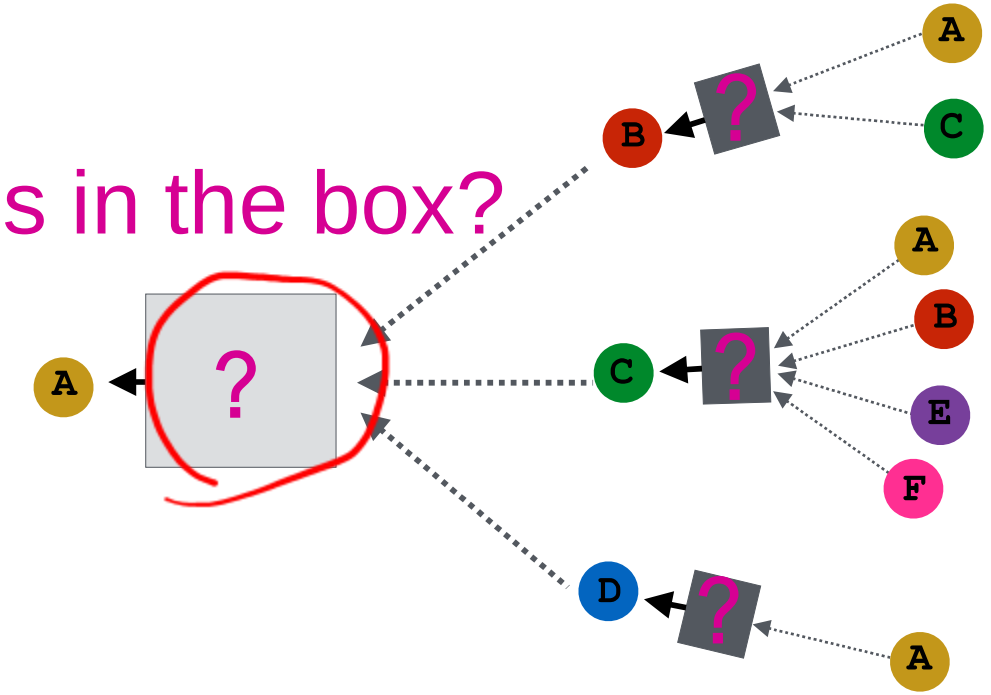


Neighborhood Aggregation

- **Neighborhood aggregation:** Key distinctions are in how different approaches aggregate information across the layers

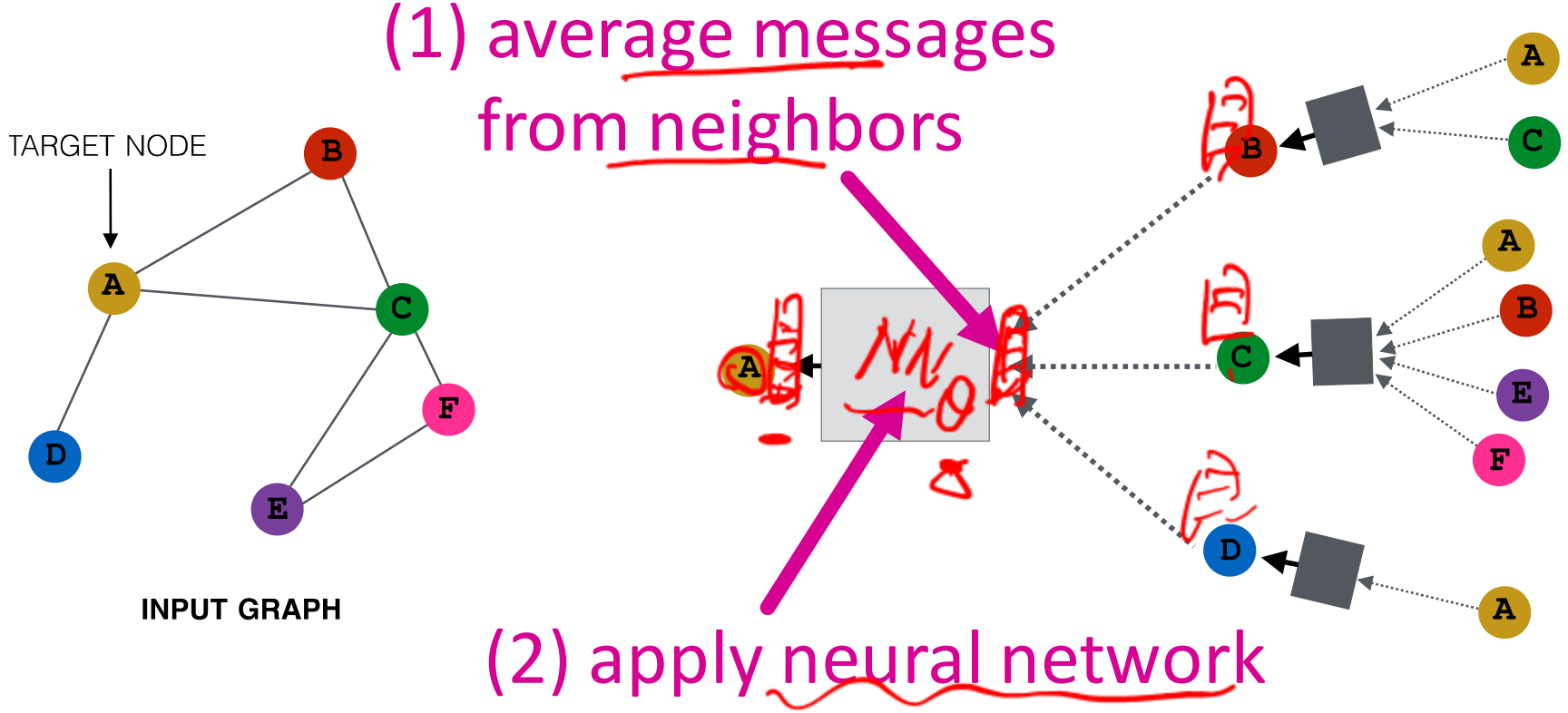


What is in the box?



Neighborhood Aggregation

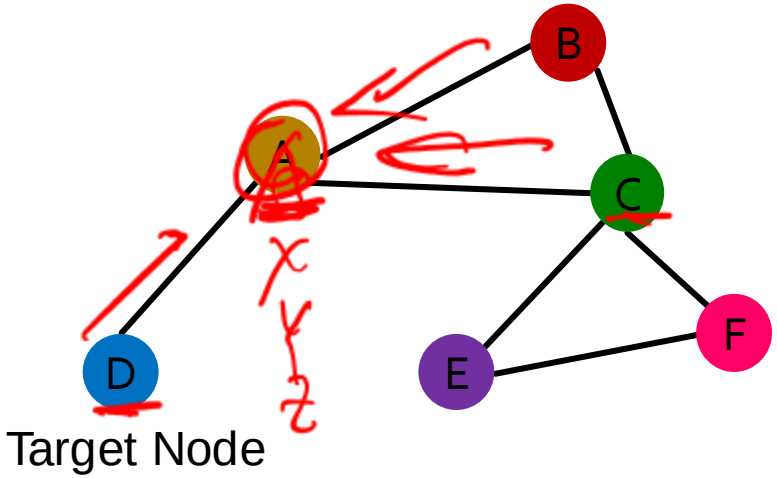
- **Basic approach:** Average information from neighbors and apply a neural network

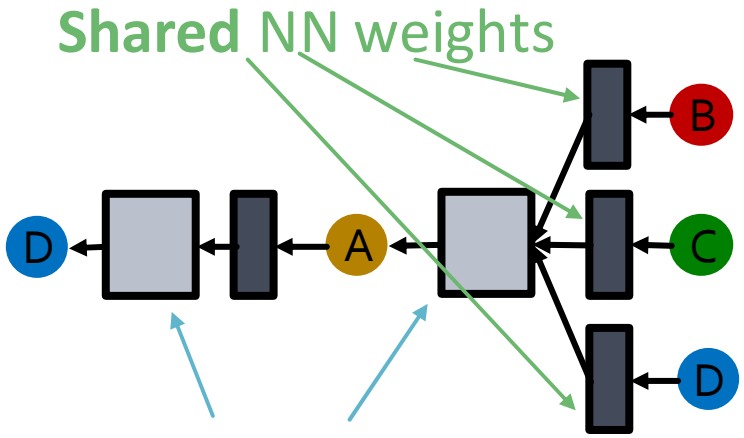


GCN (Graph Convolutional Net): Invariance and Equivariance

What are the invariance and equivariance properties for a GCN?

- **Given a node**, the GCN that computes its embedding is **permutation invariant**

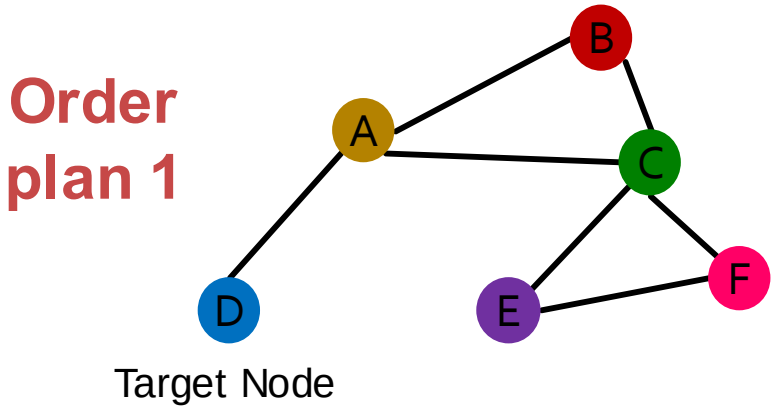


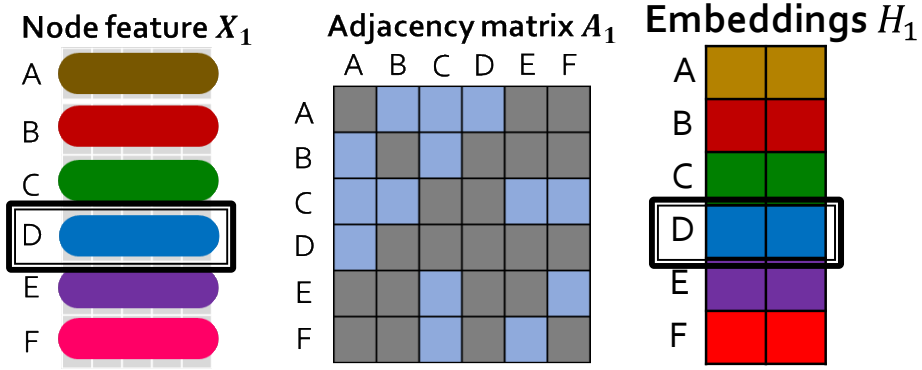


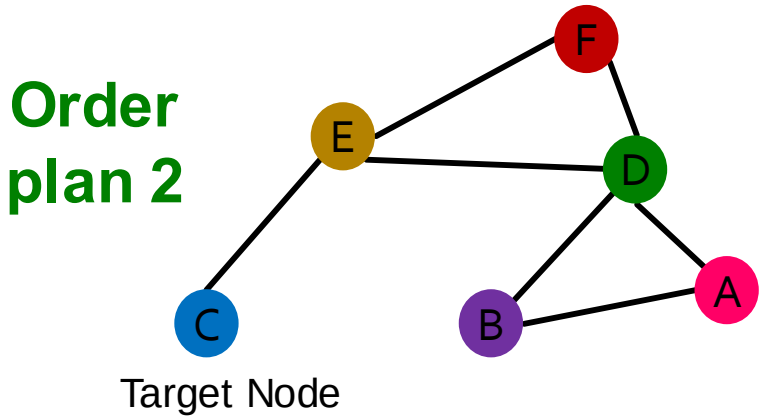
Average of neighbor's previous layer embeddings - **Permutation invariant**

GCN: Invariance and Equivariance

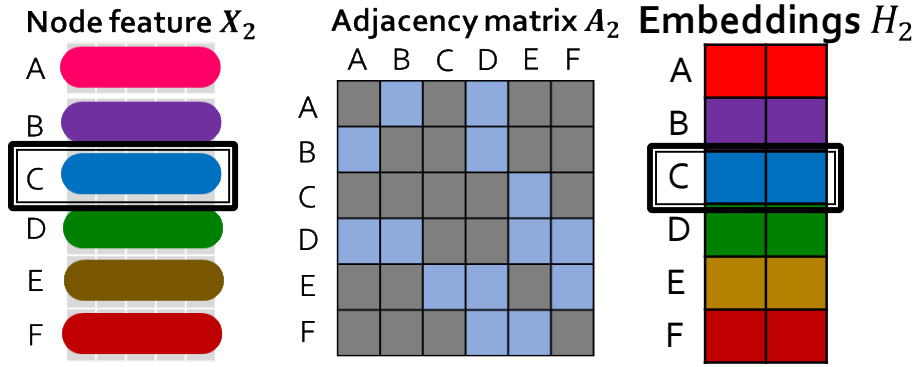
- **Considering all nodes in a graph**, GCN computation is **permutation equivariant**







Permute the input, the output also permutes accordingly - permutation equivariant



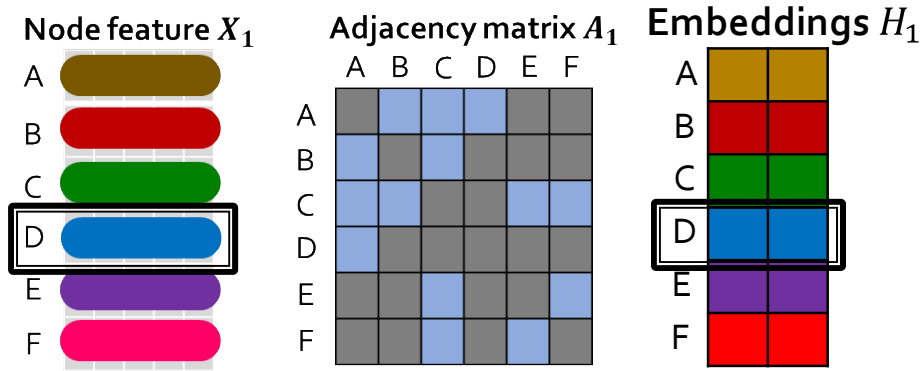
GCN: Invariance and Equivariance

- **Considering all nodes in a graph**, GCN computation is **permutation equivariant**

Detailed reasoning:

1. The rows of **input node features** and **output embeddings** are **aligned**
2. We know computing the embedding of **a given node** with GCN is **invariant.**
3. So, after permutation, the **location** of **a given node** in the **input node feature** matrix is changed, and the **the output embedding of a given node stays the same** (the colors of node feature and embedding are **matched**)

This is permutation equivariant



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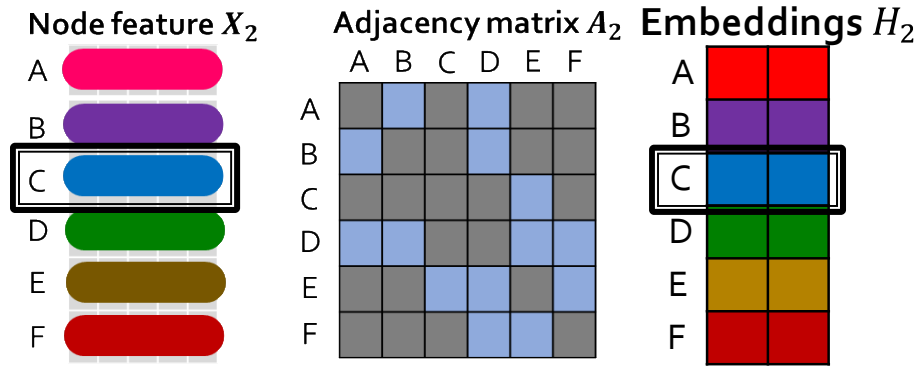
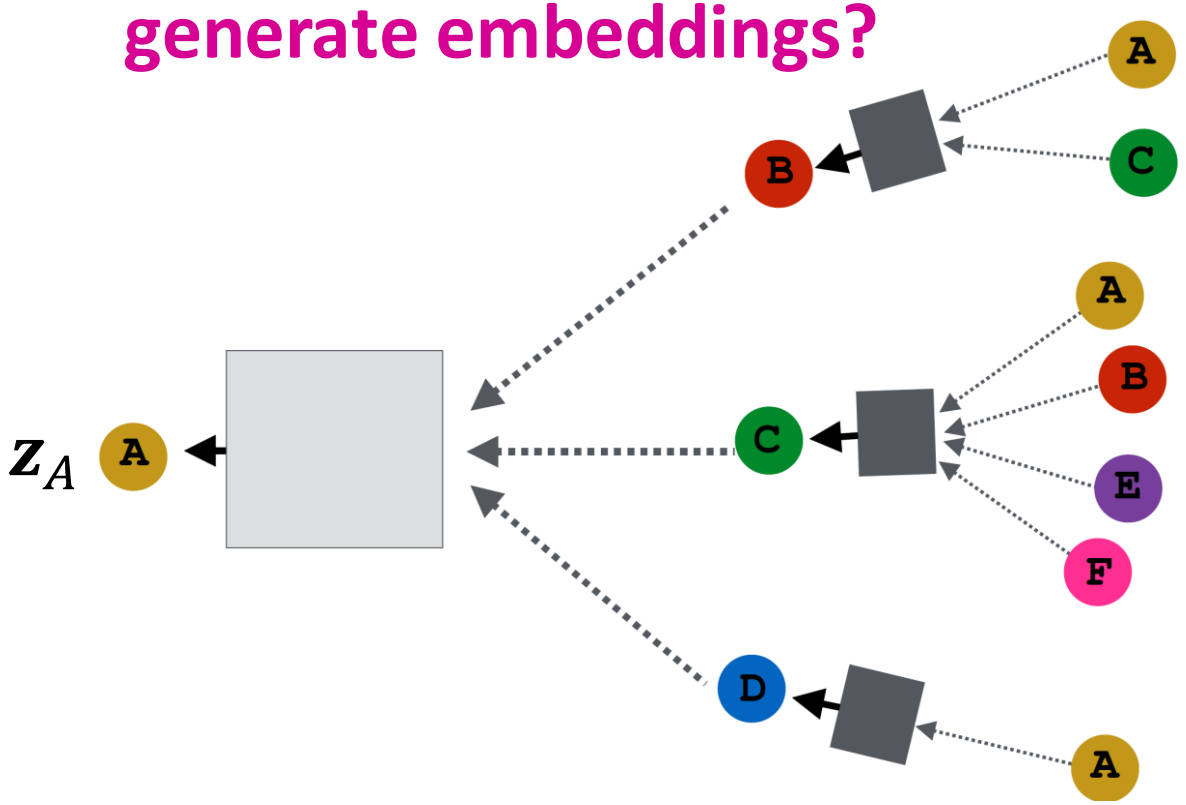


How to Train A GNN

How do we train the GCN to generate embeddings?



Need to define a loss function on the embeddings.

How to Train A GNN

- Node embedding $\boldsymbol{z}_v$ is a function of input graph
- **Supervised setting**: we want to minimize the loss $\mathcal{L}$ (see also Slide 15):

$$\min_{\Theta} \mathcal{L}(\boldsymbol{y}, f(\boldsymbol{z}_v))$$

  - $\boldsymbol{y}$: node label
  - $\mathcal{L}$ could be L2 if $\boldsymbol{y}$ is real number, or cross entropy if $\boldsymbol{y}$ is categorical

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- **Unsupervised setting:**
  - No node label available
  - **Use the graph structure as the supervision!**

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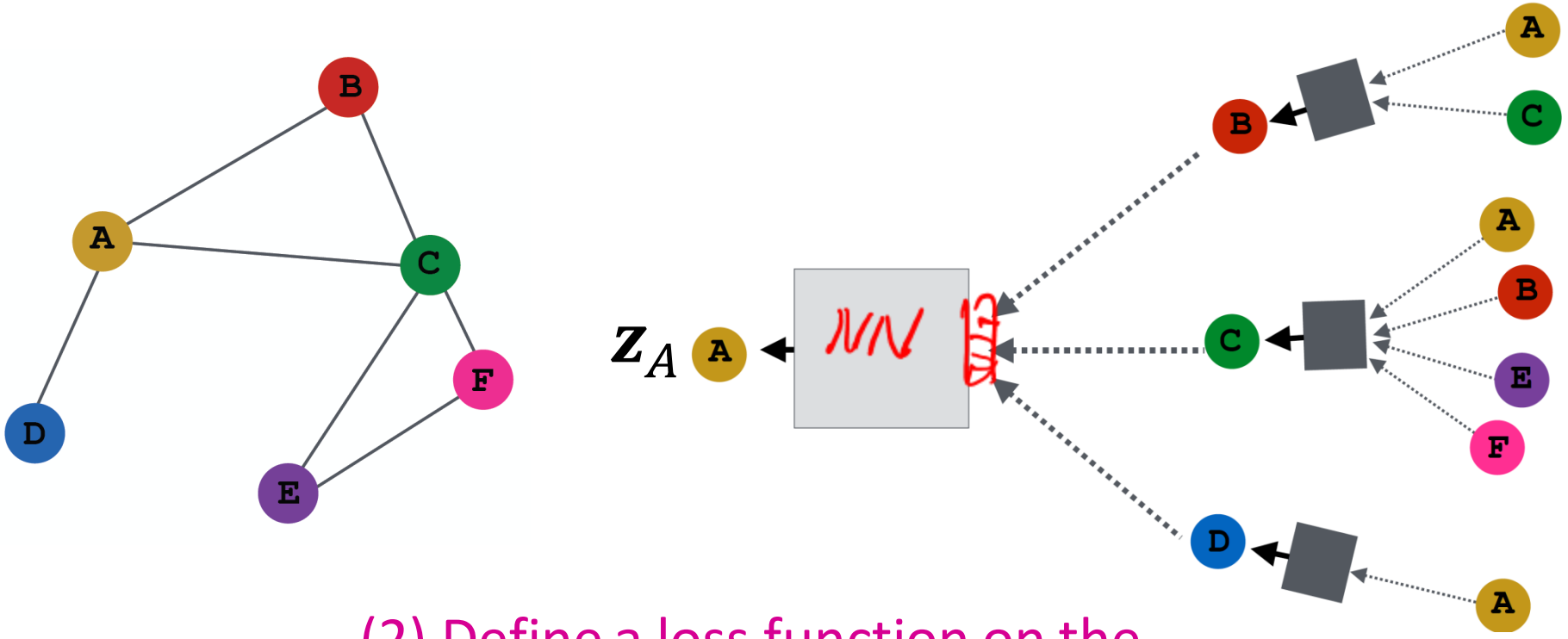
"Similar" nodes have similar embeddings (discussed in last lecture)

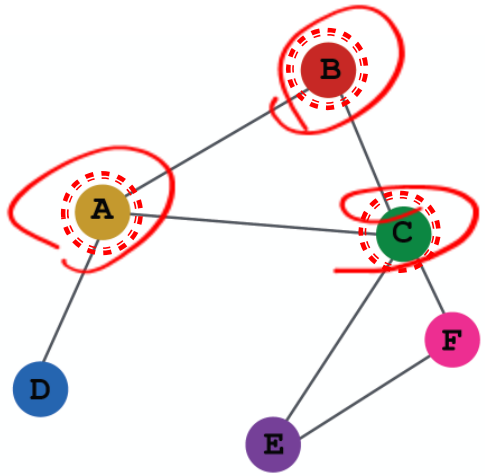
Model Design: Overview

(1) Define a neighborhood aggregation function

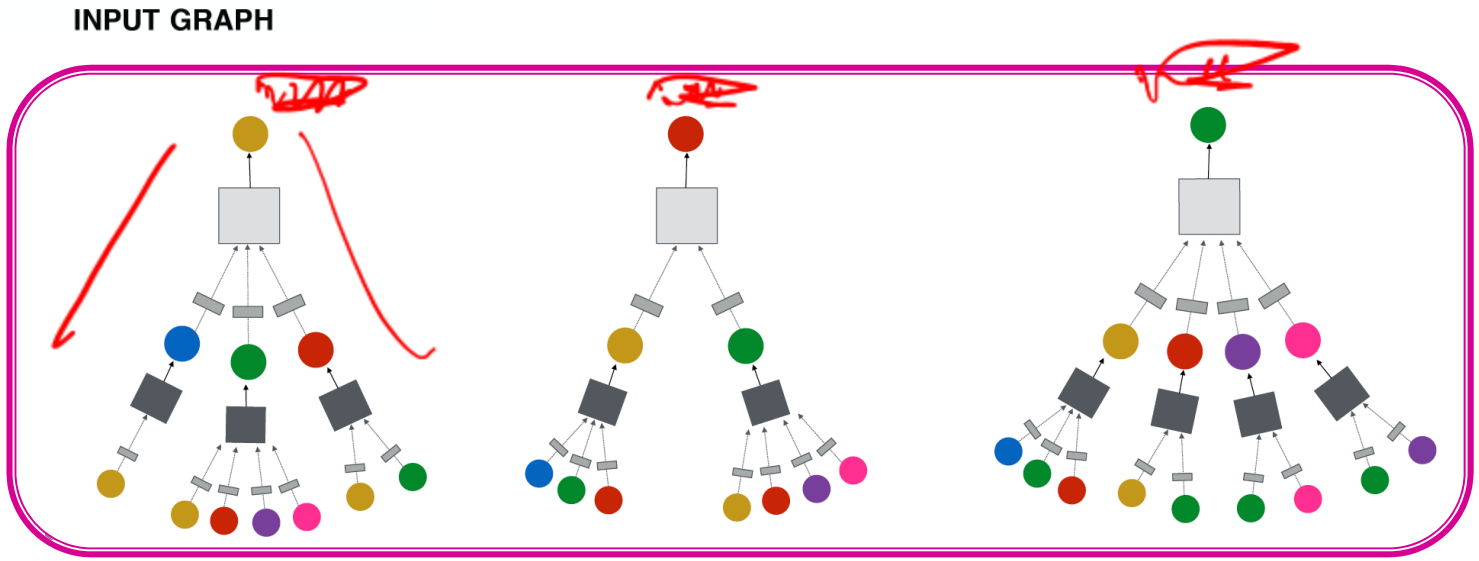


(2) Define a loss function on the embeddings

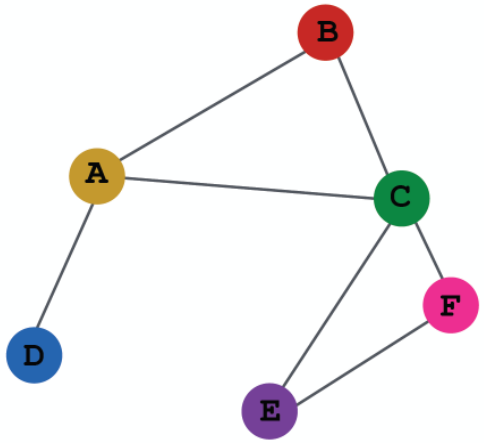
Model Design: Overview



(3) Train on a set of nodes, i.e., a batch of compute graphs



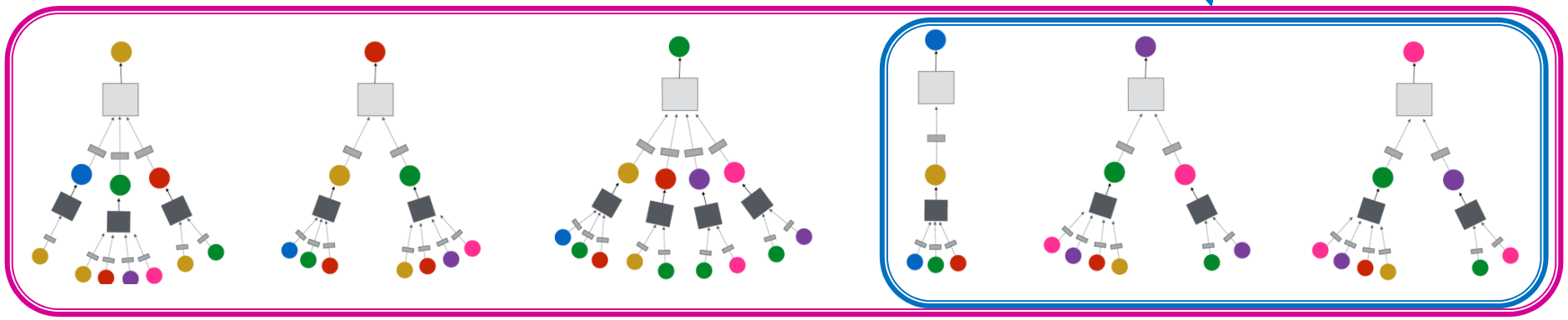
Model Design: Overview



INPUT GRAPH

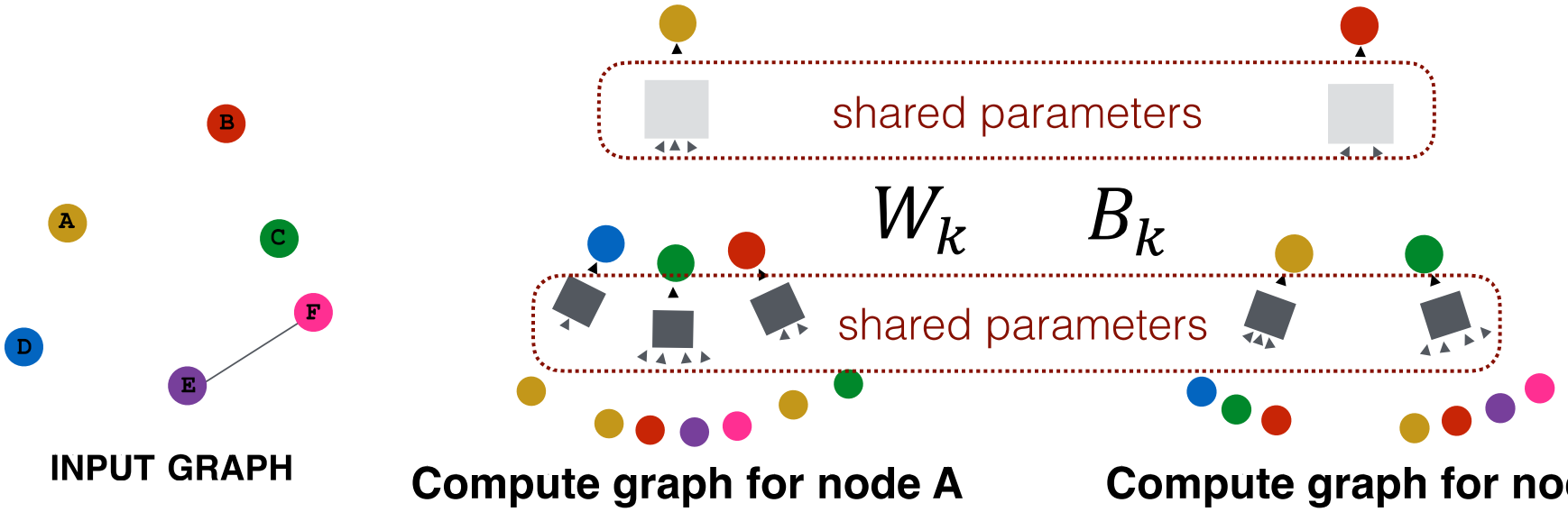
(4) Generate embeddings for nodes as needed

Even for nodes we never trained on!

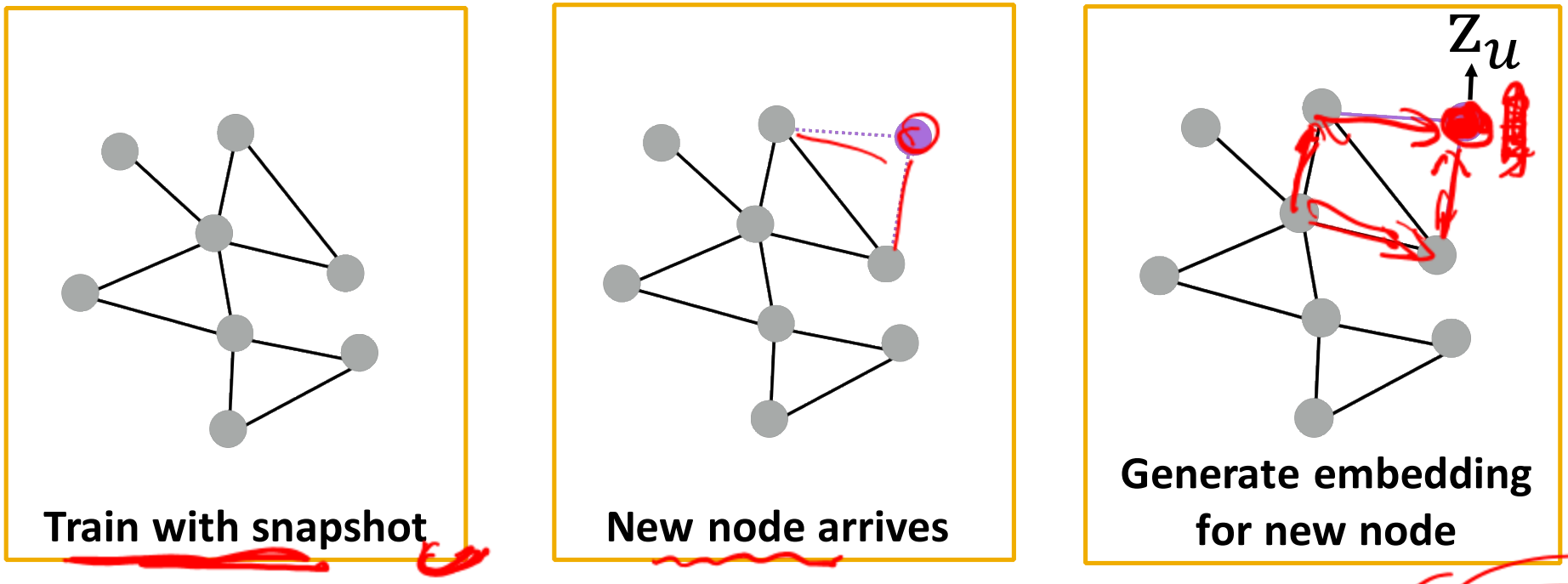


Inductive Capability

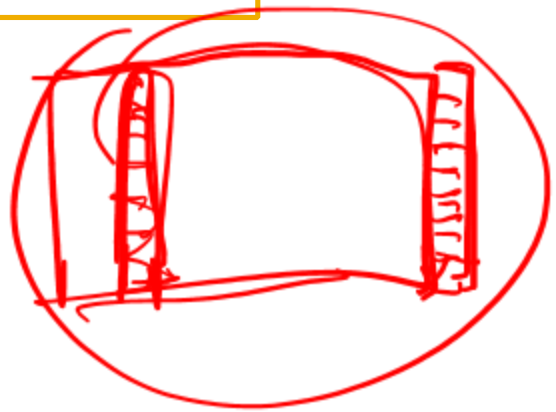
- **The same aggregation parameters are shared for all nodes:**
  - The number of model parameters is sublinear in $|V|$ and we can **generalize to unseen nodes**!



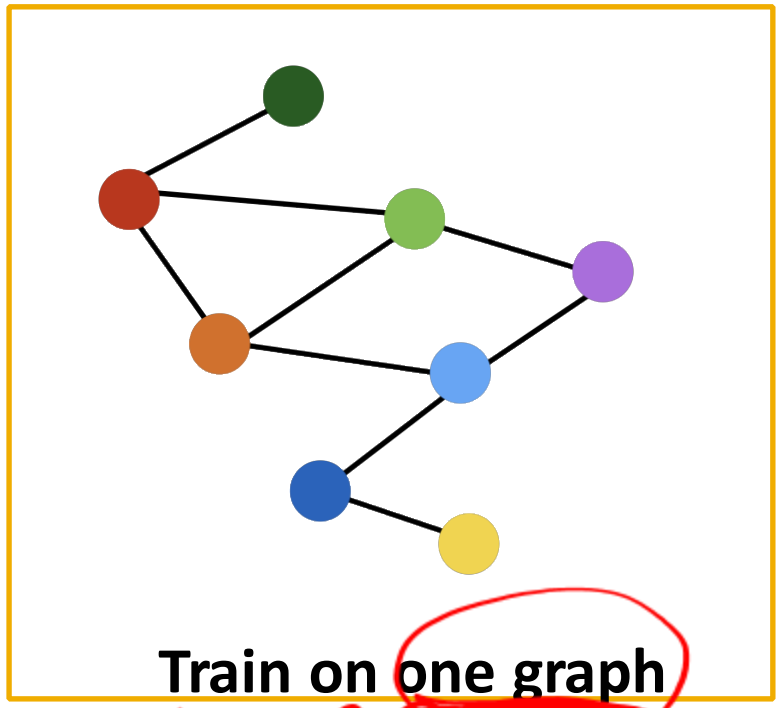
Inductive Capability: New Nodes

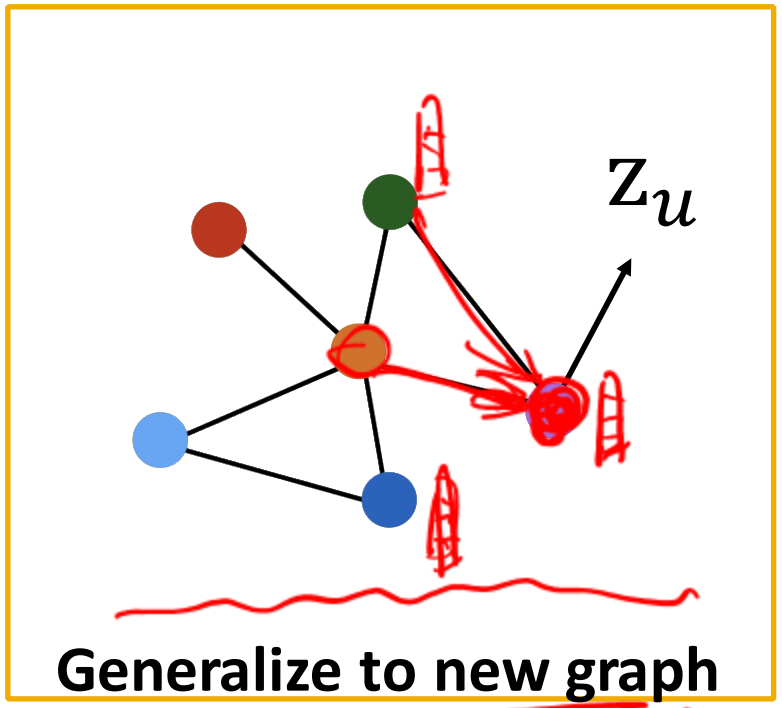


- Many application settings constantly encounter previously unseen nodes:
  - E.g., Reddit, YouTube, Google Scholar
- Need to generate new embeddings "on the fly"



Inductive Capability: New Graphs

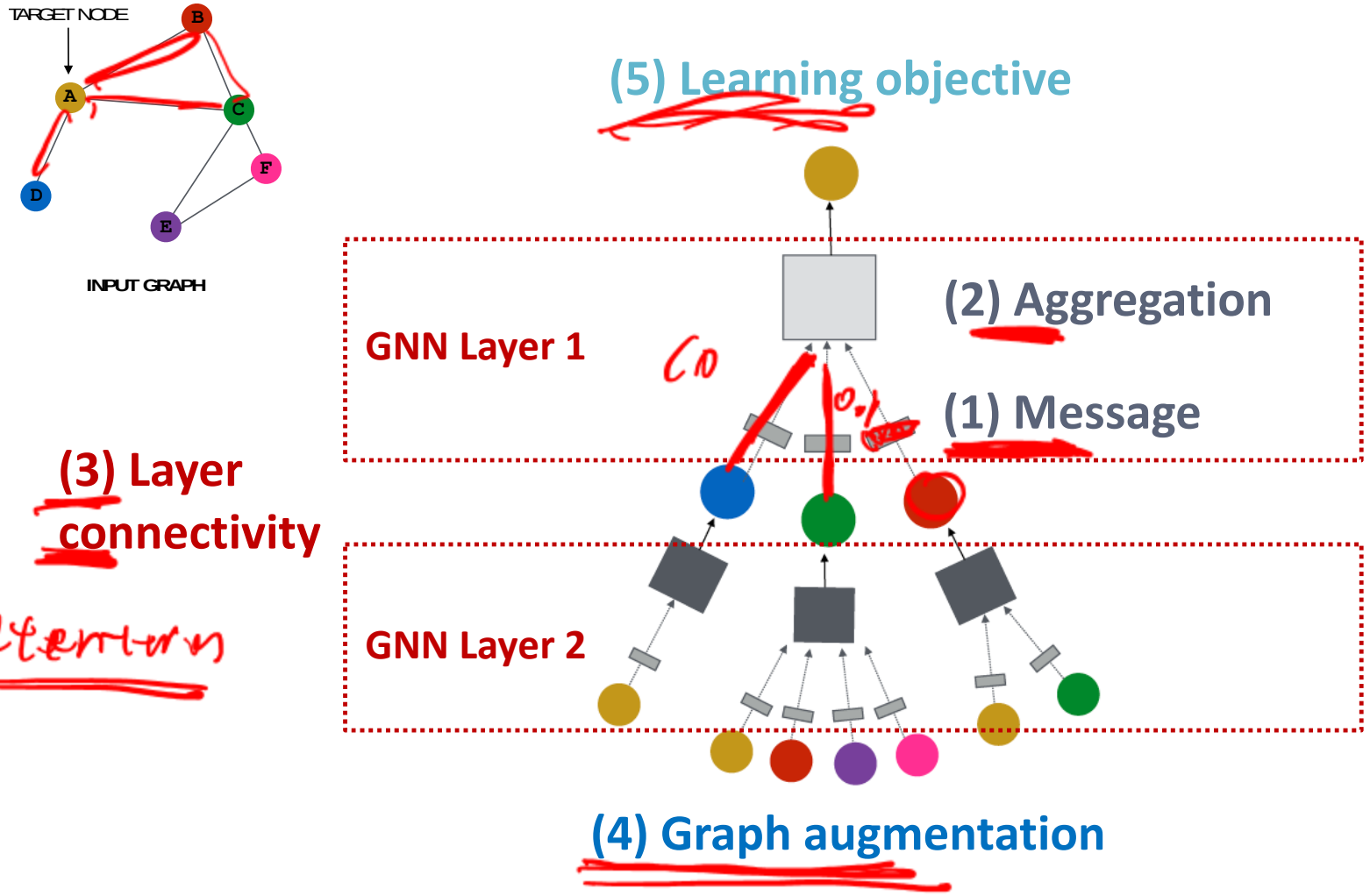




Inductive node embedding → Generalize to entirely unseen graphs

E.g., train on protein interaction graph from model organism A and generate embeddings on newly collected data about organism B

Discussion: Design Space of GNNs



Ex1: Connectivity

Our assumption so far has been

- **Raw input graph = computational graph**

Reasons for breaking this assumption

- **Feature level:**
  - The input graph **lacks features** → feature augmentation
- **Structure level:**
  - The graph is **too sparse** à inefficient message passing
  - The graph is **too dense** à message passing is too costly
  - The graph is **too large** à cannot fit the computational graph into a GPU
- It's just **unlikely that the input graph happens to be the optimal computation graph** for embeddings

Ex1: Connectivity

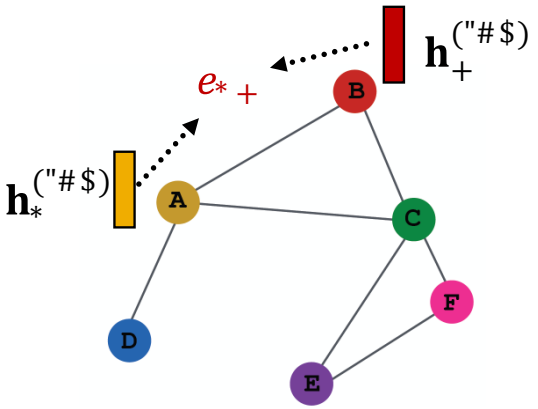
- **Graph Feature manipulation**
  - The input graph **lacks features** → **feature augmentation**
- **Graph Structure manipulation**
  - The graph is **too sparse** → **Add virtual nodes / edges**
  - The graph is **too dense** → **Sample neighbors when doing message passing**
  - The graph is **too large** → **Sample subgraphs to compute embeddings**
    - Will cover later in lecture: Scaling up GNNs

Ex2: Graph Attention Network (GAT)

- In GCN
  - $\alpha_{vu} = \frac{1}{|N(v)|}$ is the **weighting factor (importance)** of node u's message to node v
  - $\Longrightarrow$ α_{vu} is defined **explicitly** based on the structural properties of the graph (node degree)
  - $\Longrightarrow$ All neighbors $u \in N(v)$ are equally important to node v

Not all node's neighbors are equally important

- Query, Key, Value
- Alignment $\boldsymbol{e}$
- $\boldsymbol{a} = \mathrm{softmax}(\boldsymbol{e})$



Questions?