

DSC190: Machine Learning with Few Labels

Unsupervised Learning

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Lecture 18, November 8, 2024

Outline

Unsupervised learning: Variational Auto-Encoders

Presentations

- **Bobby Zhu:** Visualizing Data using t-SNE
- **Vivian Zhao:** Exploiting Audio-Visual Features with Pretrained AV-HuBERT for Multi-Modal Dysarthric Speech Reconstruction
- **Abhinav Sanisetty:** VideoPoet: A Large Language Model for Zero-Shot Video Generation
- **Zhiqing Wang:** Divide and Conquer: Leveraging Intermediate Feature Representations for Quantized Training of Neural Networks
- **Feiyang Jiang:** LoRA: Low-Rank Adaptation of Large Language Models

Recall: Black-box Variational Inference (BBVI)

- Probabilistic model: x -- observed variables, z -- latent variables
- Variational distribution $q_\lambda(z|x)$ with parameters λ , e.g.,
 - Gaussian mixture distribution:
 - “A Gaussian mixture model is a universal approximator of densities, in the sense that any smooth density can be approximated with any specific nonzero amount of error by a Gaussian mixture model with enough components.” (Deep Learning book, pp.65)
 - Deep neural networks
- ELBO to be maximized:
$$\mathcal{L}(\lambda) \triangleq \mathbb{E}_{q_\lambda(z)}[\log p(x, z) - \log q(z)]$$

$$\mathcal{L}(\lambda) = \mathbb{E}_{q(z|\lambda)}[\log p(x, z)] - \mathbb{E}_{q(z|\lambda)}[\log q(z|\lambda)]$$

- Want to compute the gradient w.r.t variational parameters λ

BBVI with the score gradient

$$\mathcal{L} = \mathbb{E}_{q_\lambda(\mathbf{z})}[f_\lambda(\mathbf{z})]$$

$$\nabla_\lambda \mathcal{L} = \mathbb{E}_{q_\lambda(\mathbf{z})}[f_\lambda(\mathbf{z}) \nabla_\lambda \log q_\lambda(\mathbf{z}) + \nabla_\lambda f_\lambda(\mathbf{z})]$$

- ELBO:

$$\mathcal{L}(\lambda) = \mathbb{E}_{q(\mathbf{z}|\lambda)}[\log p(x, \mathbf{z})] - \mathbb{E}_{q(\mathbf{z}|\lambda)}[\log q(\mathbf{z}|\lambda)]$$

- **Question:** what's the score gradient w.r.t. λ ?

$$\nabla_\lambda \mathcal{L} = \mathbb{E}_q[\nabla_\lambda \log q(z|\lambda)(\log p(x, z) - \log q(z|\lambda))]$$

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$$\nabla_\lambda \mathcal{L} = \mathbb{E}_q[\nabla_\lambda \log q(z|\lambda)(\log p(x, z) - \log q(z|\lambda))]$$

- Compute noisy unbiased gradients of the ELBO with Monte Carlo samples from the variational distribution

$$\nabla_\lambda \mathcal{L} \approx \frac{1}{S} \sum_{s=1}^S \nabla_\lambda \log q(z_s|\lambda)(\log p(x, z_s) - \log q(z_s|\lambda)),$$

where $z_s \sim q(z|\lambda)$.

BBVI with the reparameterization gradient

$$\mathcal{L} = \mathbb{E}_{q_\lambda(\mathbf{z})}[f_\lambda(\mathbf{z})]$$

$$\nabla_\lambda \mathcal{L} = \mathbb{E}_{\epsilon \sim s(\epsilon)}[\nabla_{\mathbf{z}} f_\lambda(\mathbf{z}) \nabla_\lambda t(\epsilon, \lambda)]$$

- ELBO:

$$\mathcal{L}(\lambda) = \mathbb{E}_{q(\mathbf{z}|\lambda)}[\log p(x, \mathbf{z})] - \mathbb{E}_{q(\mathbf{z}|\lambda)}[\log q(\mathbf{z}|\lambda)]$$

- **Question:** what's the reparamerization gradient w.r.t. λ ?

$$\begin{aligned}\epsilon &\sim s(\epsilon) \\ z &= t(\epsilon, \lambda)\end{aligned}\iff z \sim q(z|\lambda)$$

$$\nabla_\lambda \mathcal{L} = \mathbb{E}_{\epsilon \sim s(\epsilon)}[\nabla_z [\log p(x, z) - \log q(z)] \nabla_\lambda t(\epsilon, \lambda)]$$

Variational Autoencoders (VAEs)

Variational Auto-Encoders (VAEs)

VAEs are a combination of the following ideas:

- Variational Inference
 - ELBO
- Variational distribution parametrized as neural networks
- Reparameterization trick

Variational Auto-Encoders (VAEs)

- Model $p_{\theta}(x, z) = p_{\theta}(x|z)p(z)$
 - $p_{\theta}(x|z)$: a.k.a., generative model, generator, (probabilistic) decoder, ...
 - $p(z)$: prior, e.g., Gaussian
- Assume variational distribution $q_{\phi}(z|x)$
 - E.g., a Gaussian distribution parameterized as **deep neural networks**
 - a.k.a, recognition model, inference network, (probabilistic) encoder, ...
- ELBO:

$$\begin{aligned}\mathcal{L}(\theta, \phi; x) &= \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x, z)] + H(q_{\phi}(z|x)) \\ &= \mathbb{E}_{q_{\phi}(z|x)} [\log p_{\theta}(x|z)] - \text{KL}(q_{\phi}(z|x) || p(z))\end{aligned}$$

Reconstruction



Divergence from prior

(KL divergence between two Gaussians has
an analytic form)

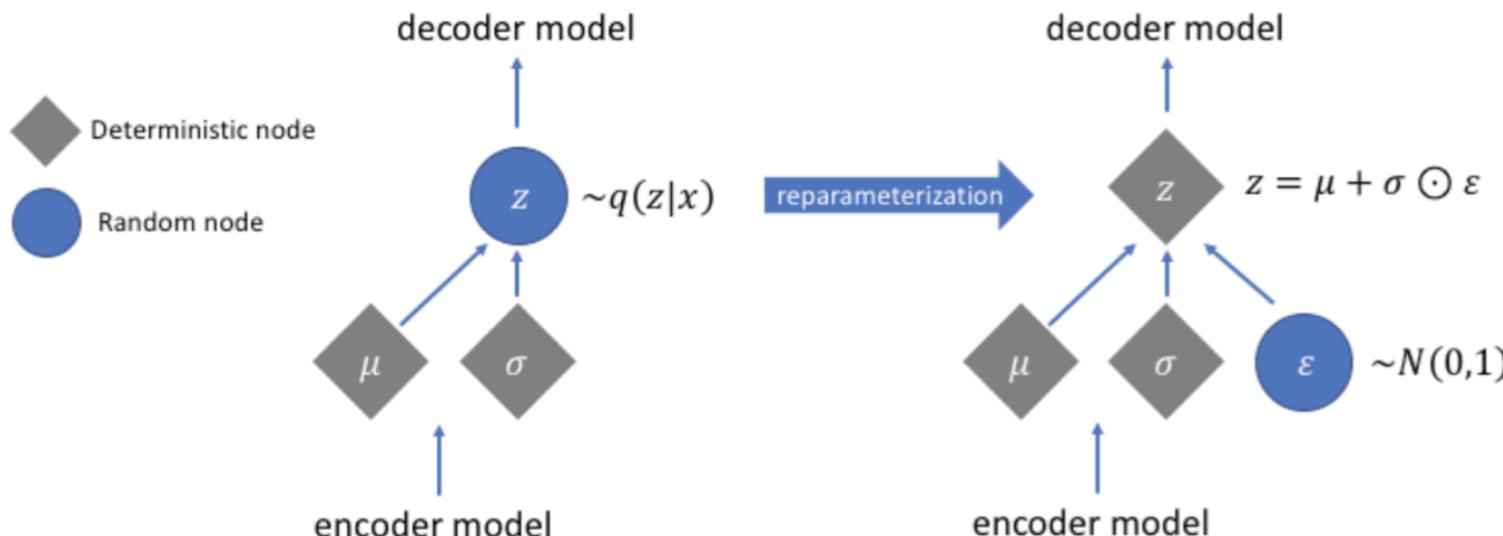
Variational Auto-Encoders (VAEs)

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- Reparameterization:

- $[\mu; \sigma] = f_\phi(x)$ (a neural network)
- $z = \mu + \sigma \odot \epsilon, \quad \epsilon \sim N(0, 1)$



Variational Auto-Encoders (VAEs)

- ELBO:

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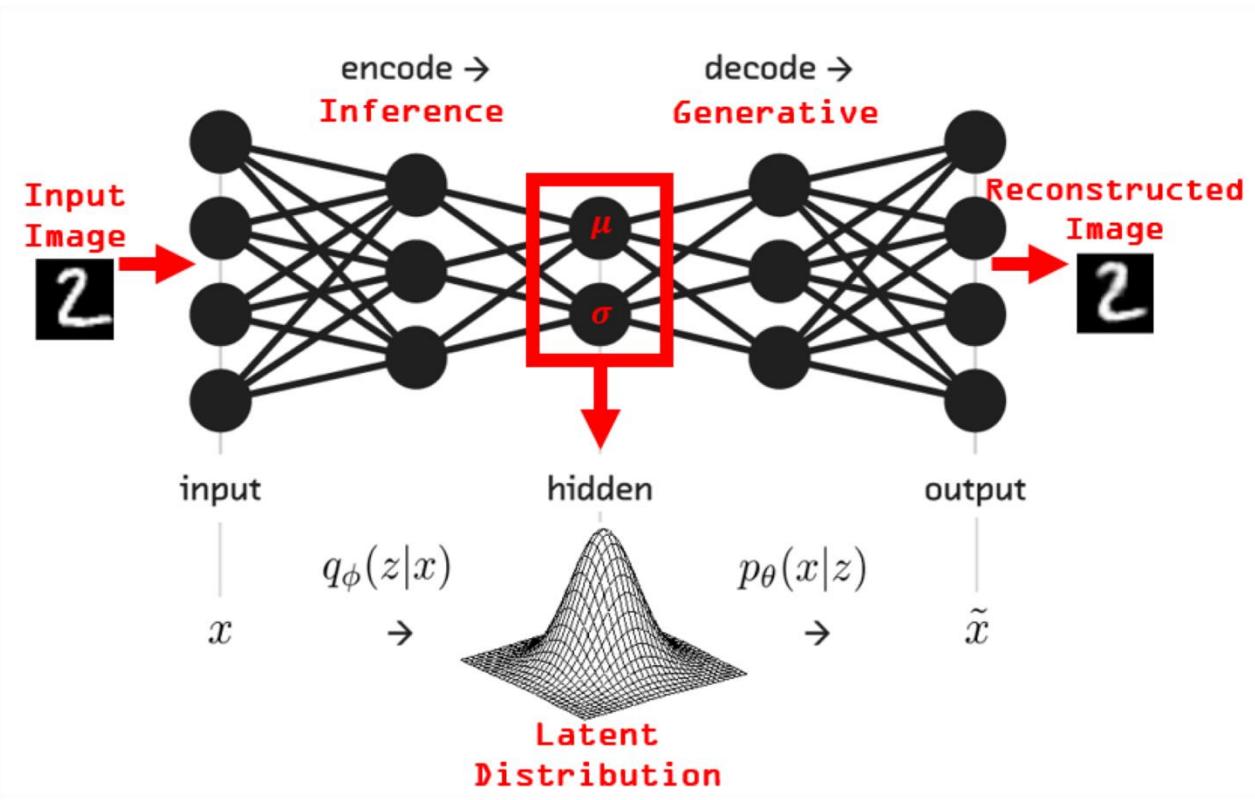
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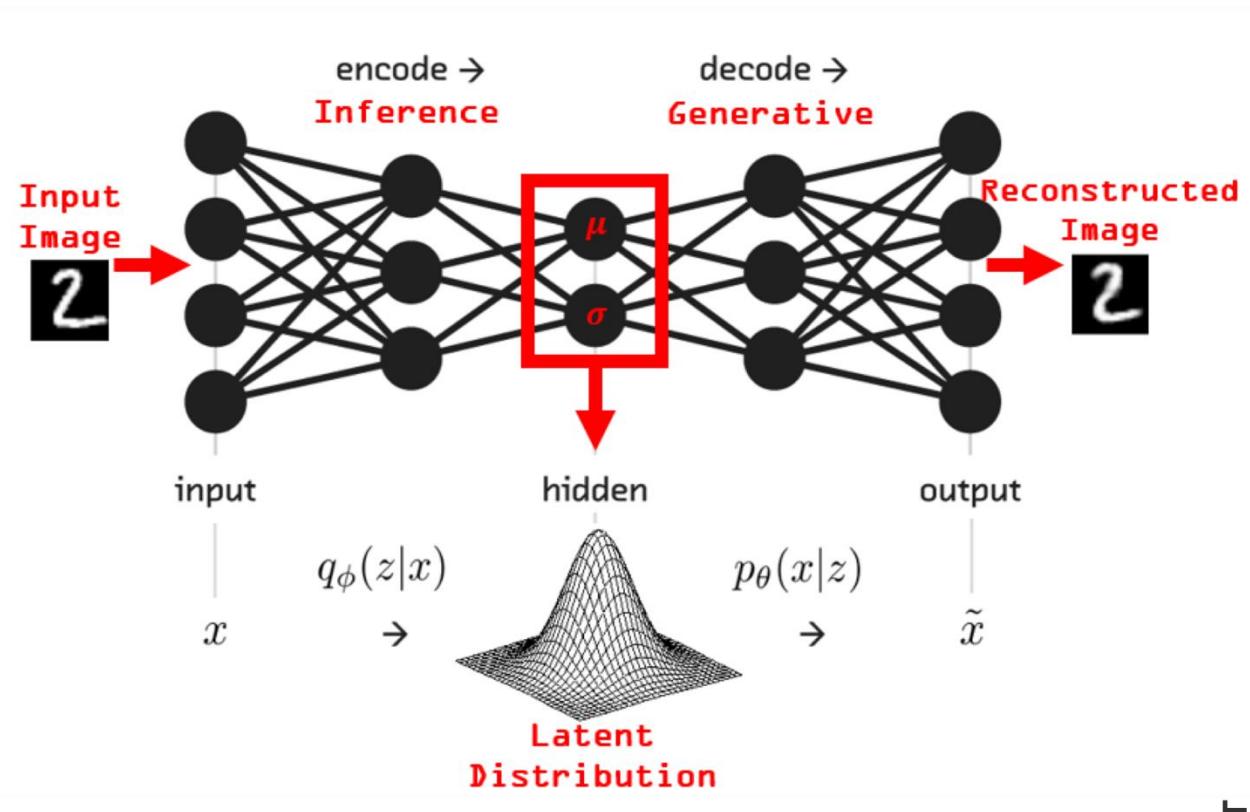
$$\nabla_\phi \mathcal{L} = \mathbb{E}_{\epsilon \sim N(0, 1)} [\nabla_z [\log p_\theta(x, z) - \log q_\phi(z|x)] \nabla_\phi z(\epsilon, \phi)]$$

$$\nabla_\theta \mathcal{L} = \mathbb{E}_{q_\phi(z|x)} [\nabla_\theta \log p_\theta(x, z)]$$

Example: VAEs for images



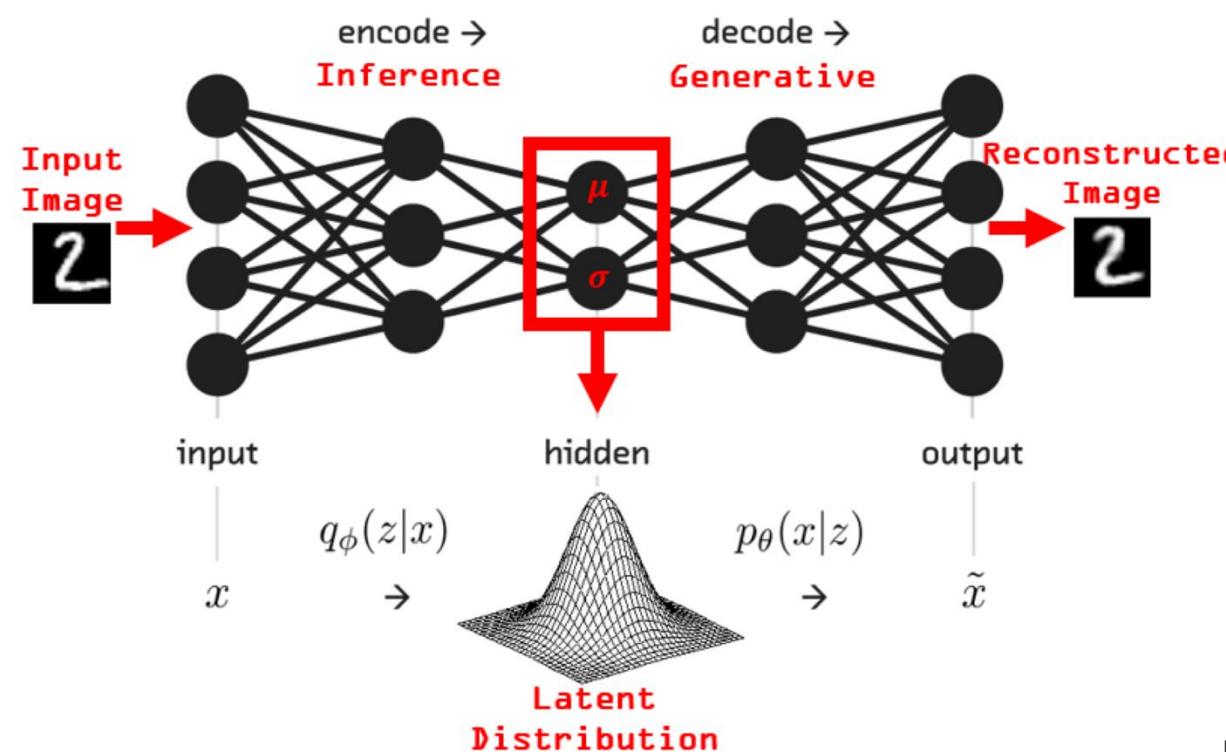
Example: VAEs for images



Input Data

x

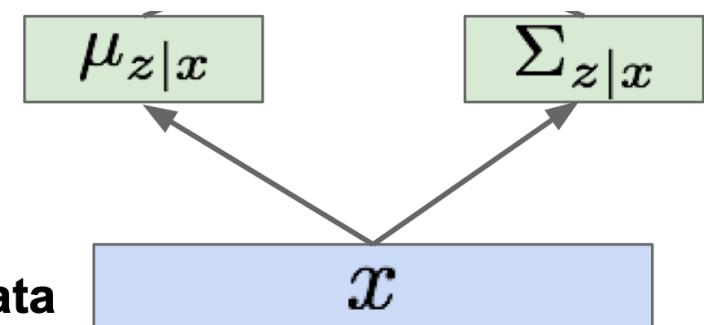
Example: VAEs for images



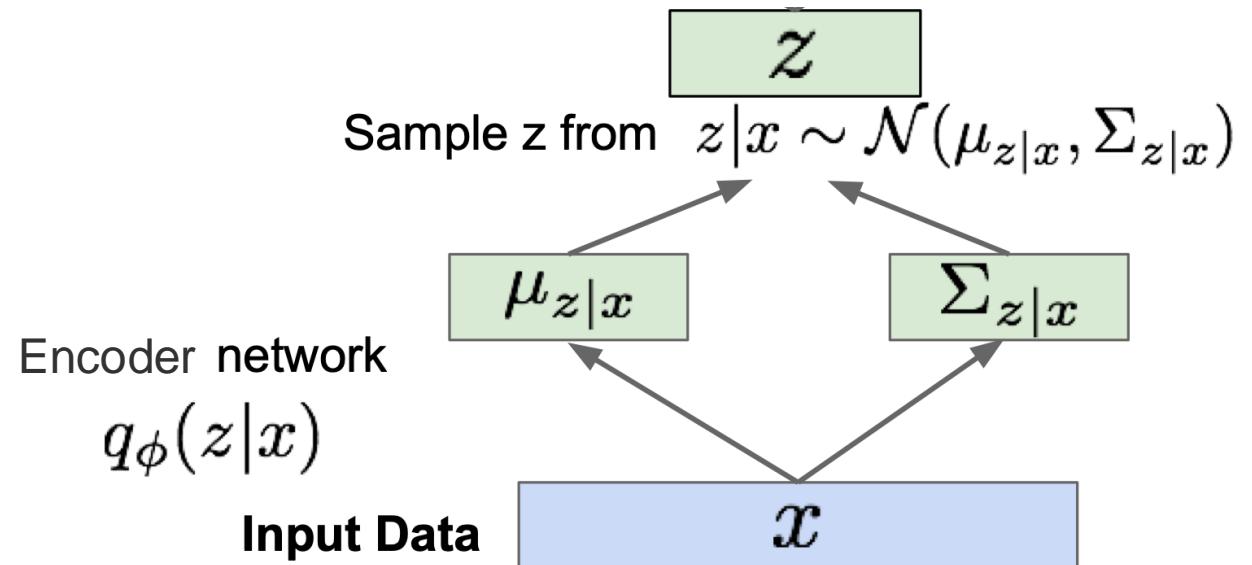
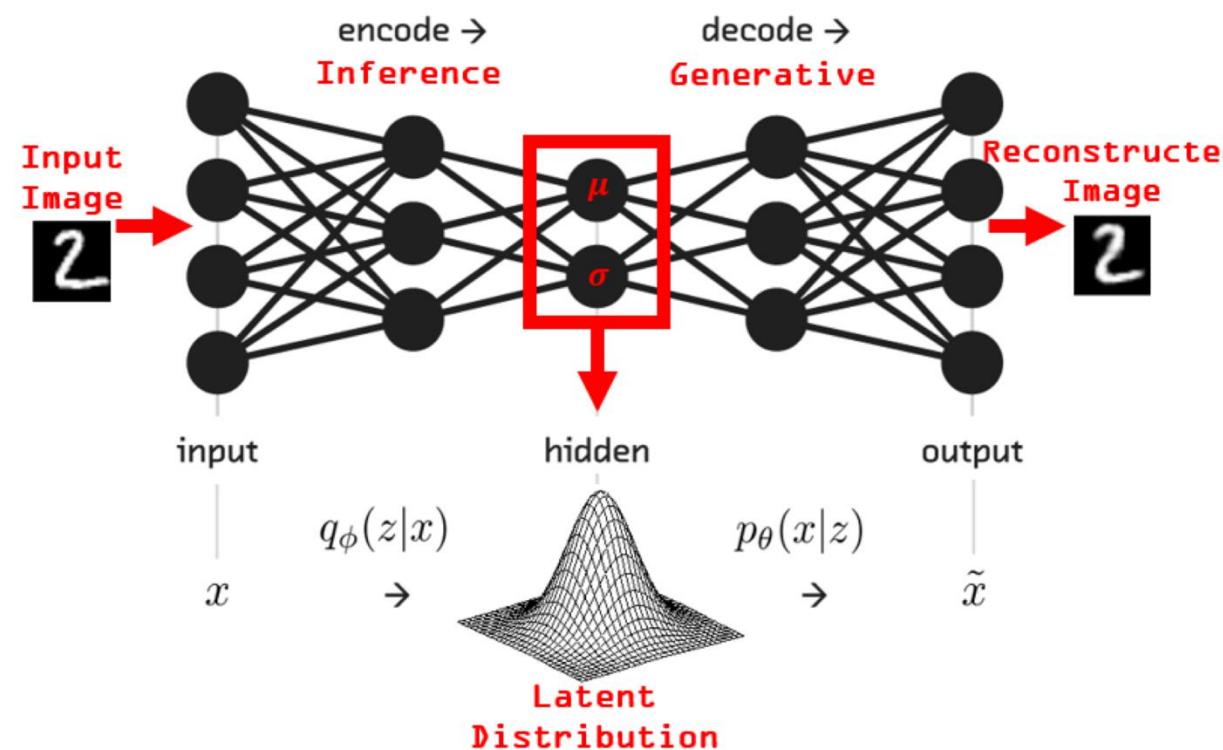
Encoder network

$$q_\phi(z|x)$$

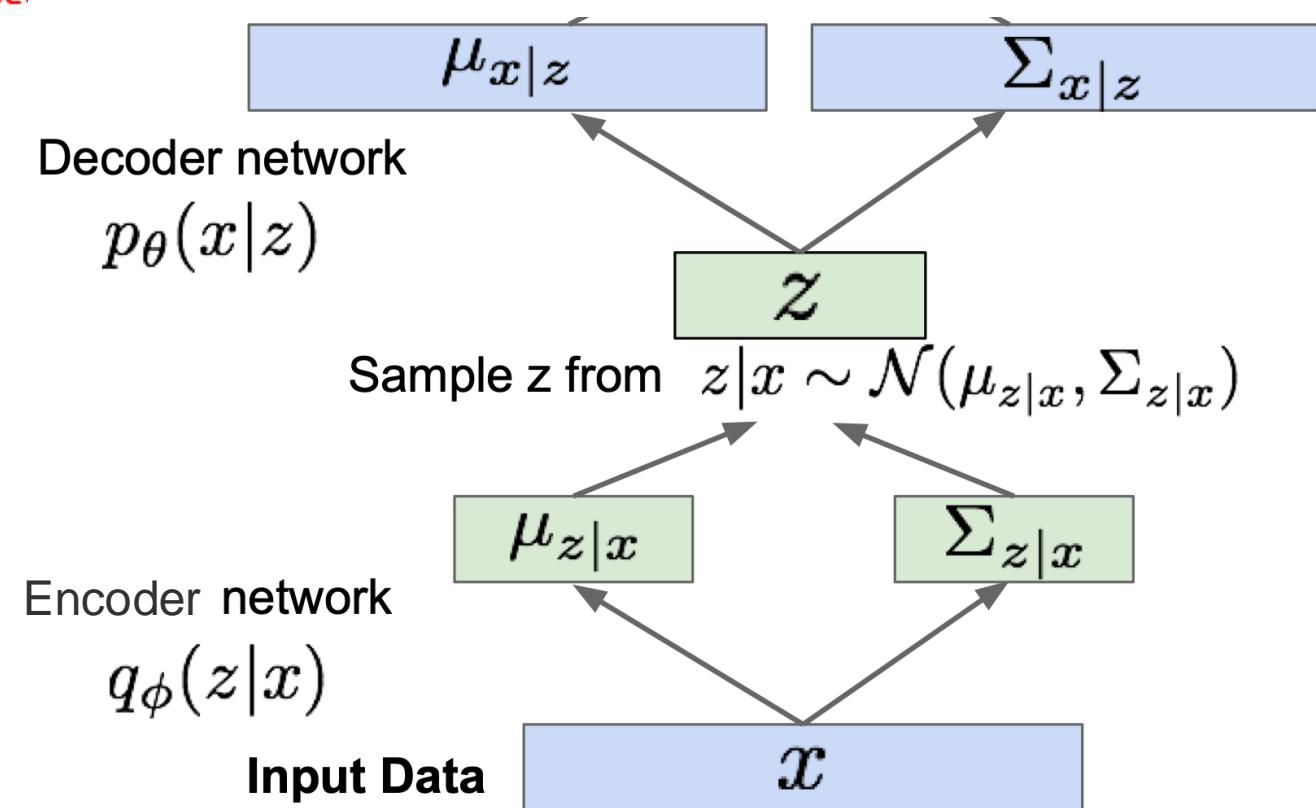
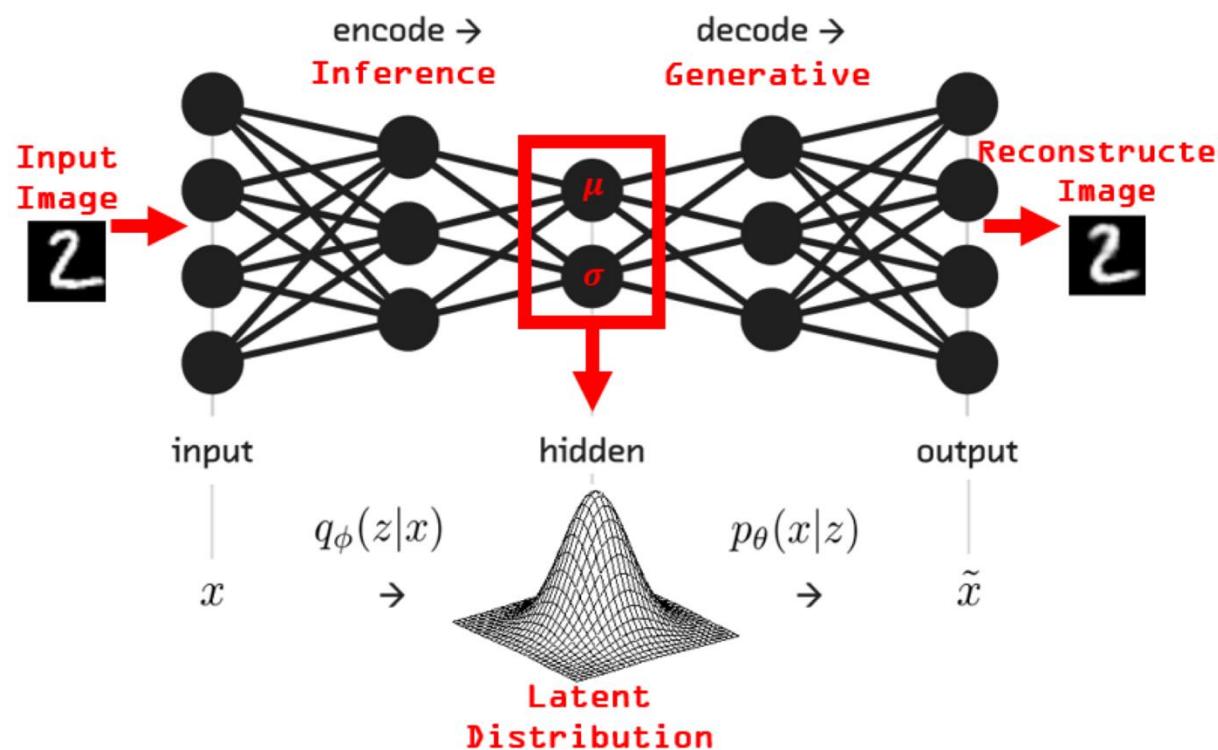
Input Data



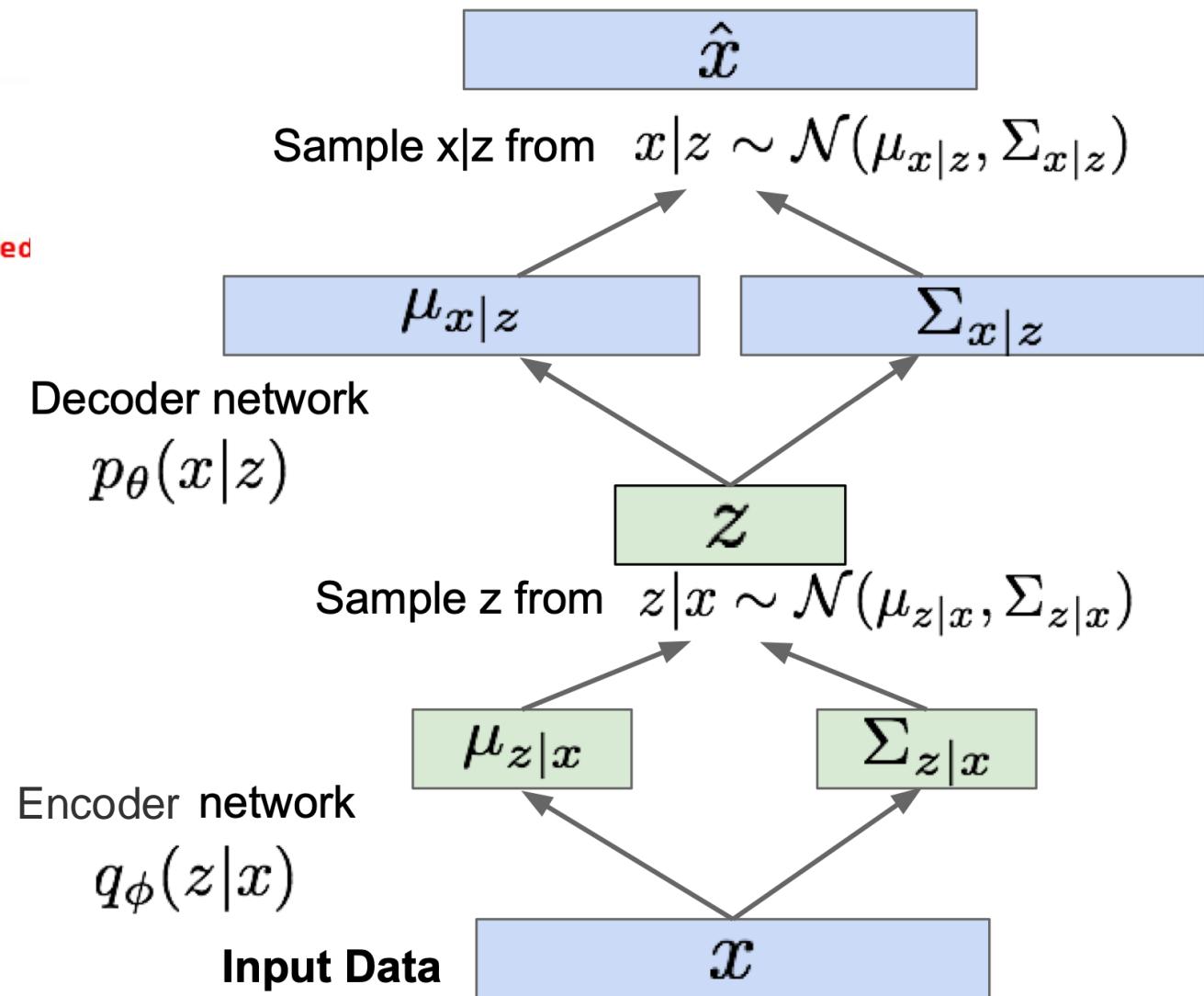
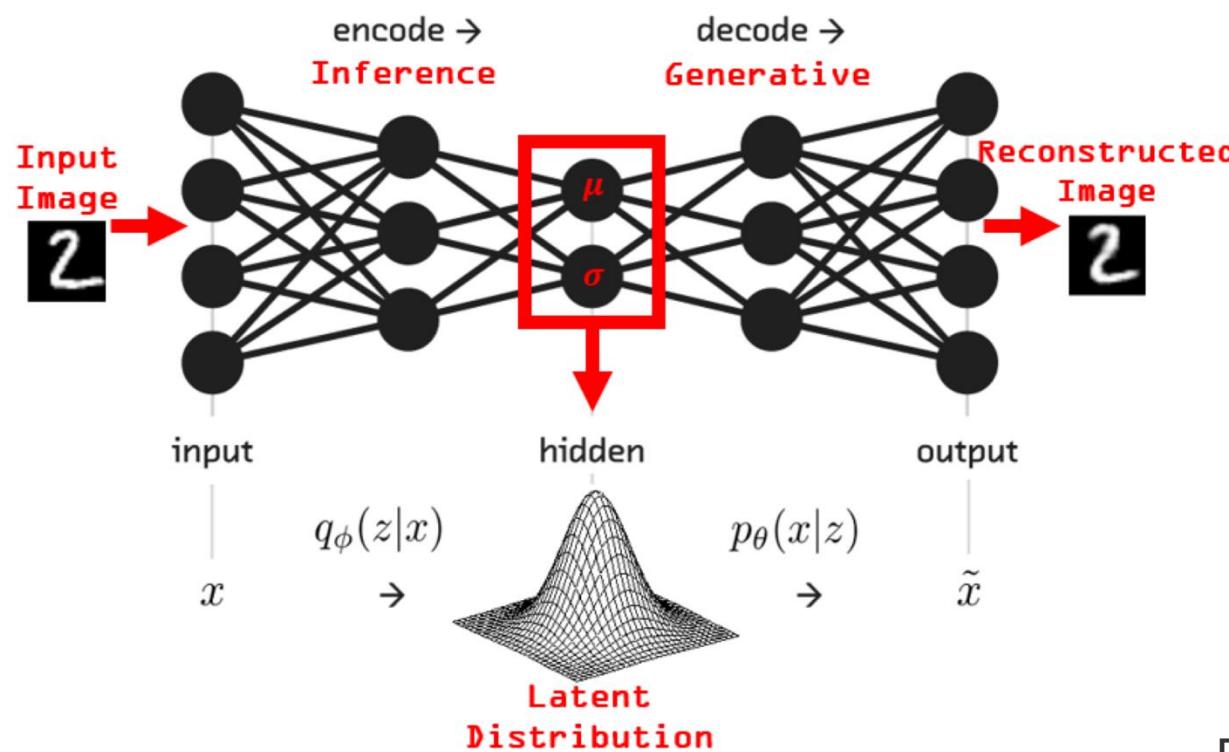
Example: VAEs for images



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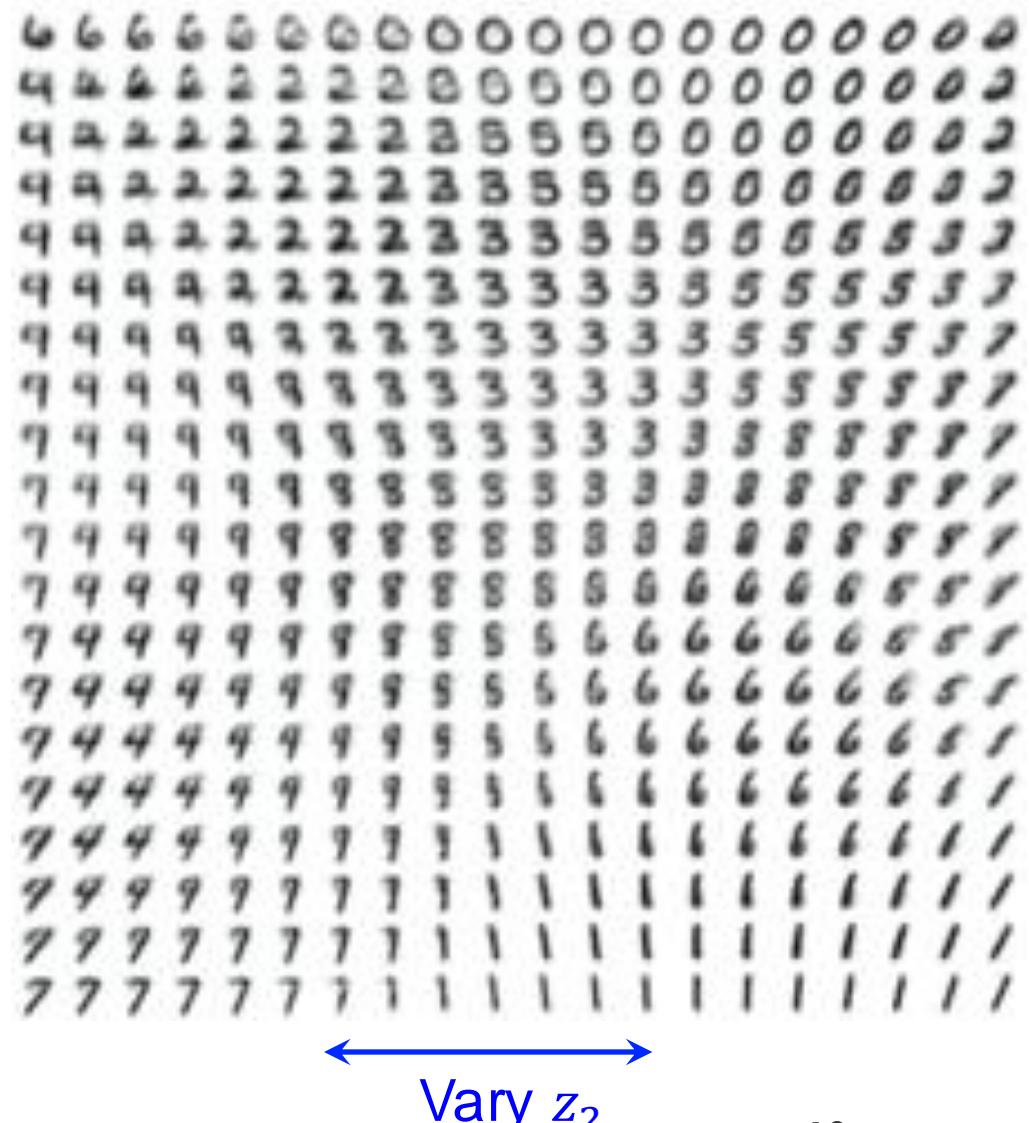
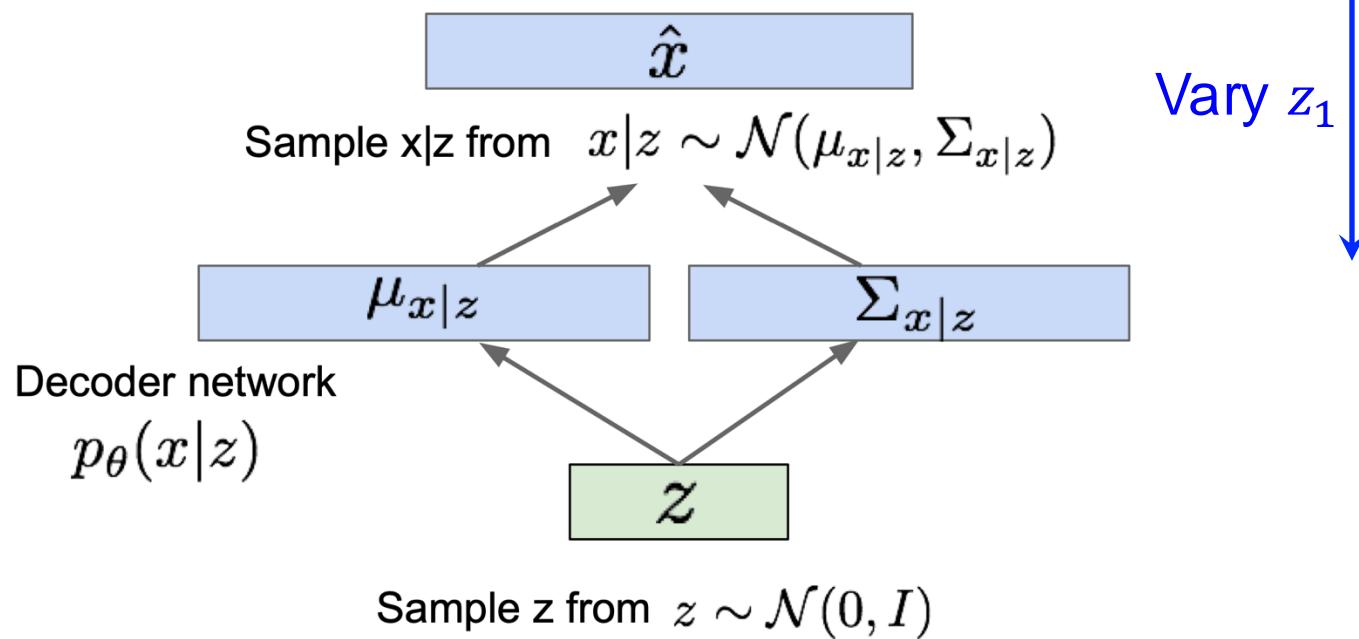


Example: VAEs for images

Data manifold for 2-d z

Generating samples:

- Use decoder network. Now sample z from prior!

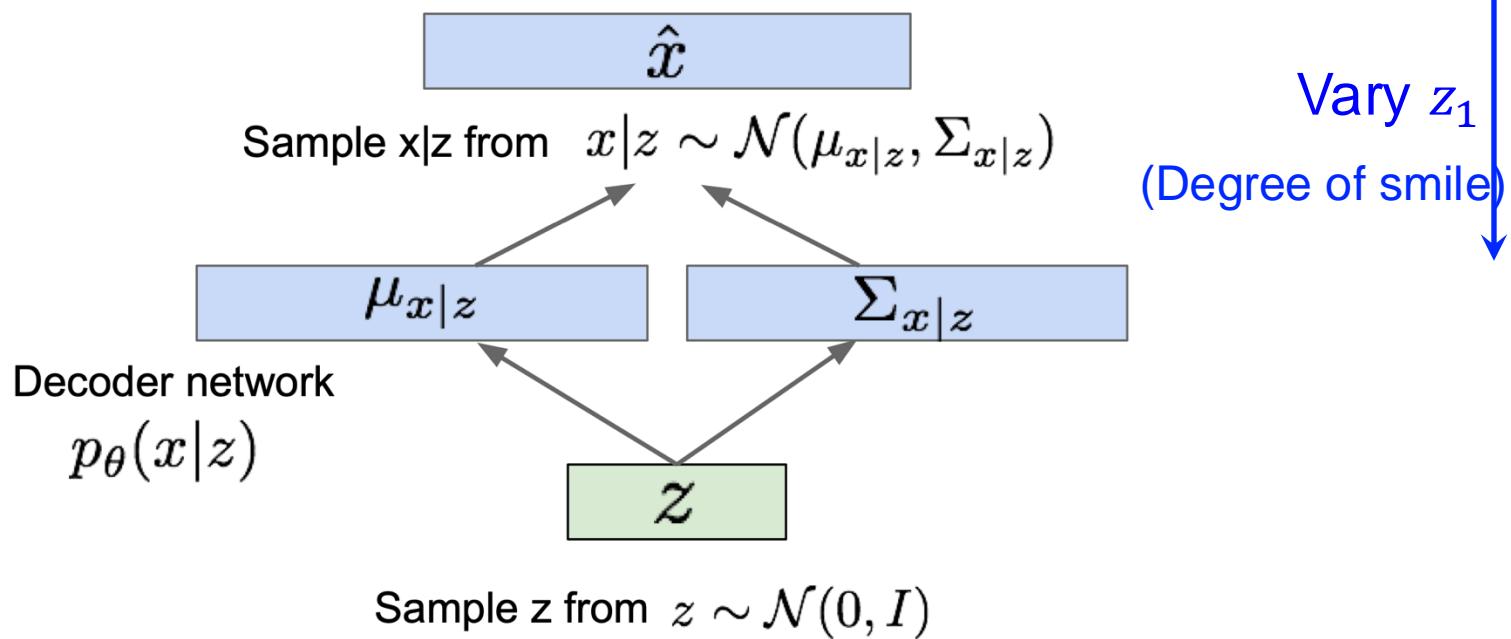


Example: VAEs for images

Data manifold for 2-d z

Generating samples:

- Use decoder network. Now sample z from prior!



Vary z_2 (head pose)
19

Example: VAEs for text

- Latent code interpolation and sentences generation from VAEs [Bowman et al., 2015].

“ i want to talk to you . ”

“*i want to be with you .* ”

“*i do n’t want to be with you .* ”

i do n’t want to be with you .

she did n’t want to be with him .

Note: Amortized Variational Inference

- Variational distribution as an **inference model** $q_\phi(\mathbf{z}|\mathbf{x})$ with parameters $\boldsymbol{\phi}$ (which was traditionally factored over samples)
- Amortize the cost of inference by learning a **single** data-dependent inference model
- The trained inference model can be used for quick inference on new data

Variational Auto-encoders: Summary

- A combination of the following ideas:
 - Variational Inference: ELBO
 - Variational distribution parametrized as neural networks
 - Reparameterization trick

$$\mathcal{L}(\theta, \phi; x) = [\log p_\theta(x|z)] - \text{KL}(q_\phi(z|x) || p(z))$$

Reconstruction



Divergence from prior

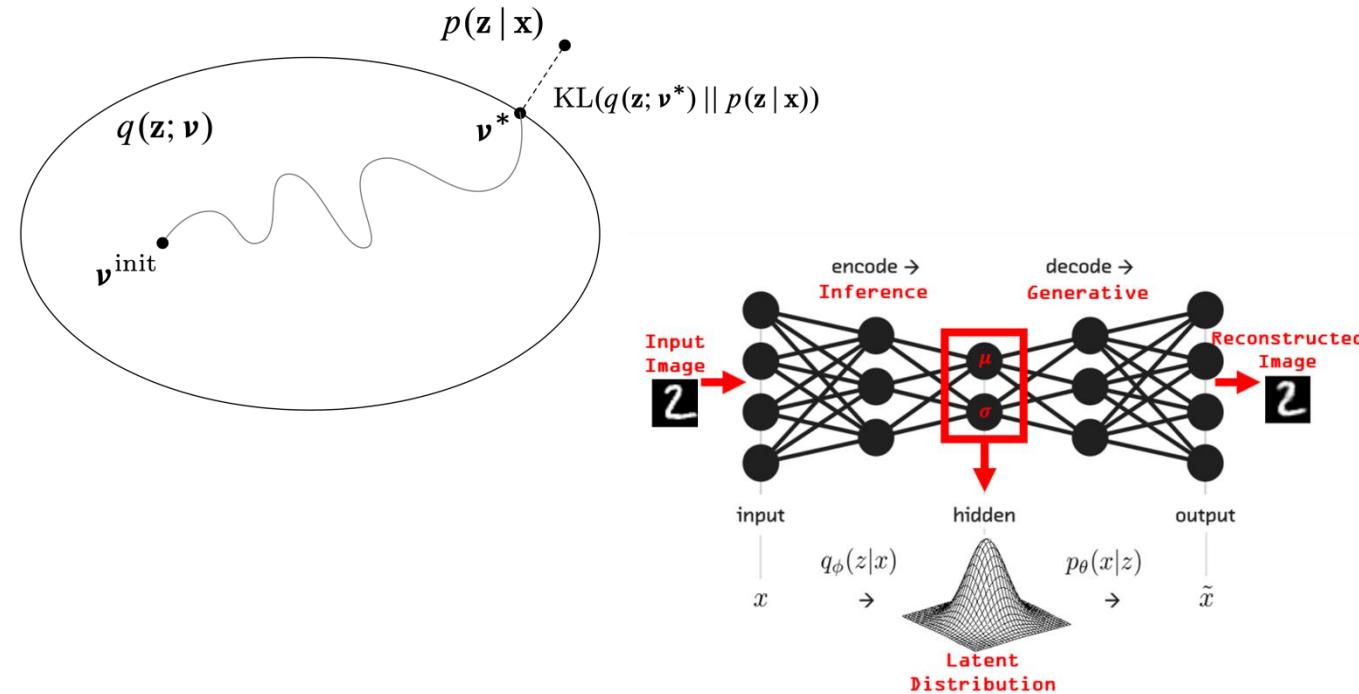


(Razavi et al., 2019)

- Pros:
 - Principled approach to generative models
 - Allows inference of $q(z|x)$, can be useful feature representation for other tasks
- Cons:
 - Samples blurrier and lower quality compared to GANs
 - Tend to collapse on text data

Summary: Supervised / Unsupervised Learning

- Supervised Learning
 - Maximum likelihood estimation (MLE)
- Unsupervised learning
 - Maximum likelihood estimation (MLE) with latent variables
 - Marginal log-likelihood
 - EM algorithm for MLE
 - ELBO / Variational free energy
 - Variational Inference
 - ELBO / Variational free energy
 - Variational distributions
 - Factorized (mean-field VI)
 - Mixture of Gaussians (Black-box VI)
 - Neural-based (VAEs)



Presentations

Questions?