

# DSC291: Machine Learning with Few Labels

Reinforcement learning for text generation

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Lecture 19, February 24, 2023

**UC San Diego**

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# When (clean) supervised data is available

## Inspirational success

Language Modeling

Machine Translation

Summarization

Description Generation

Captioning

Speech Recognition

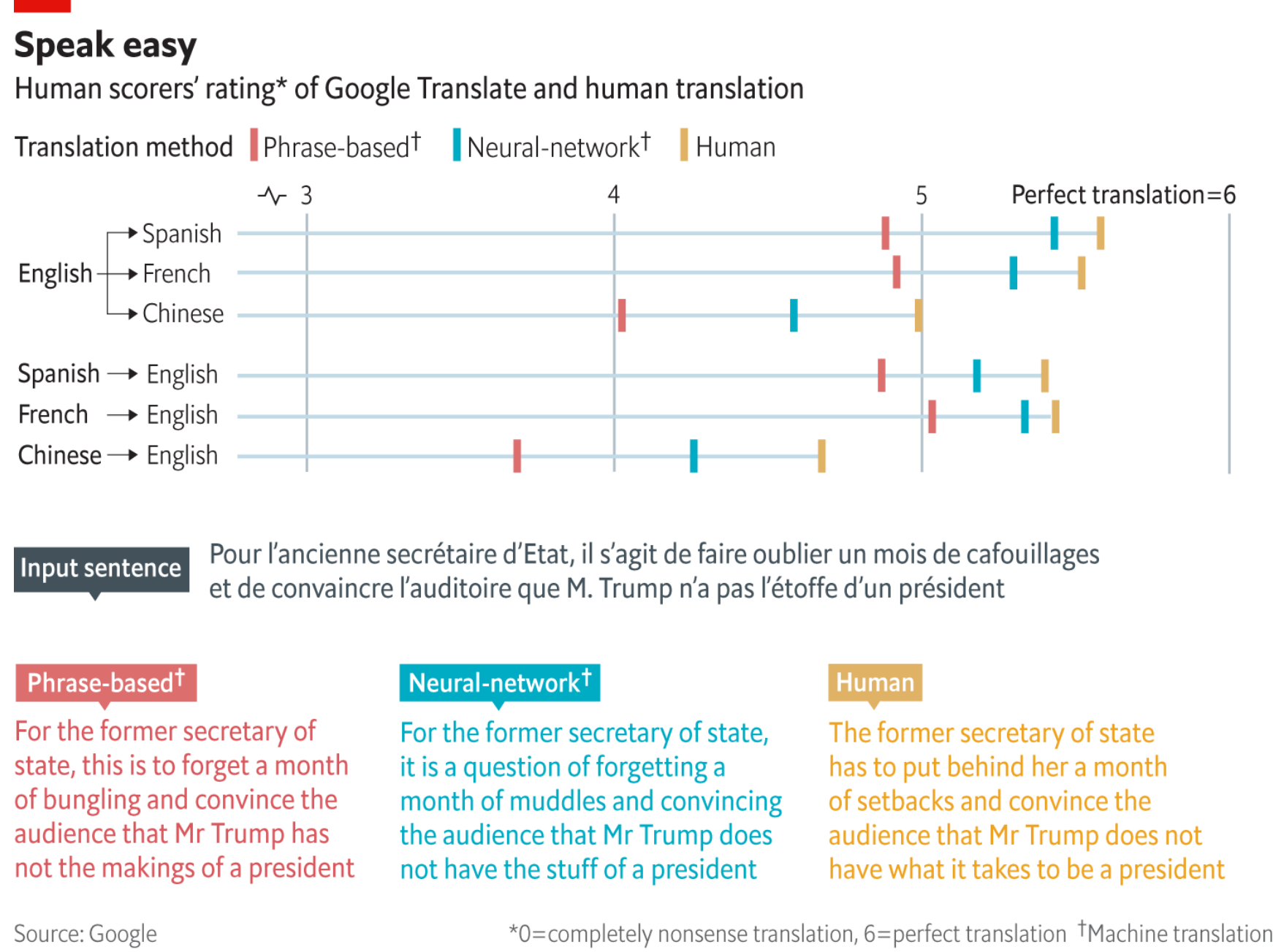
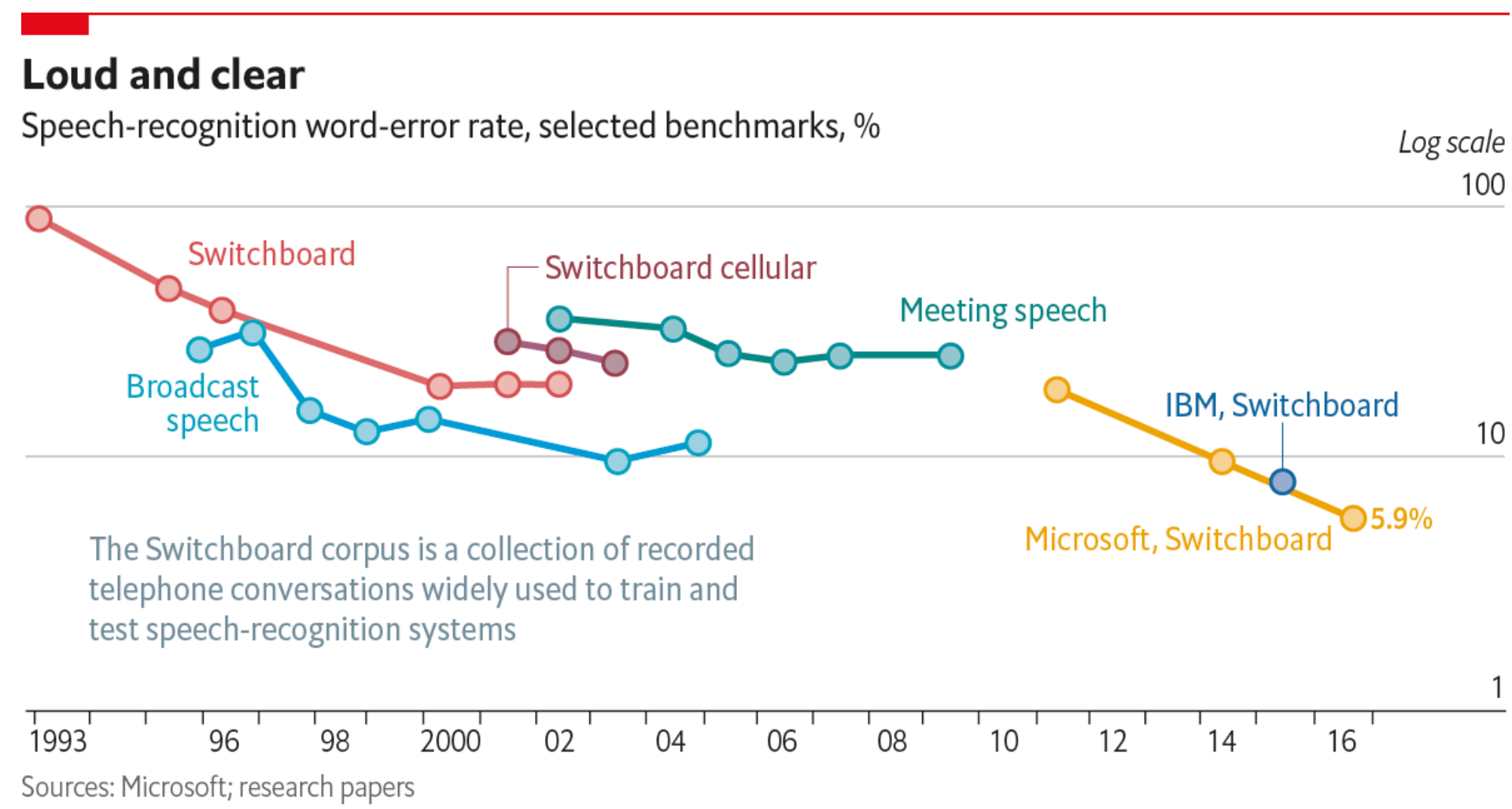
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TECH ARTIFICIAL INTELLIGENCE

### OpenAI's text-generating system GPT-3 is now spewing out 4.5 billion words a day

*Robot-generated writing looks set to be the next big thing*

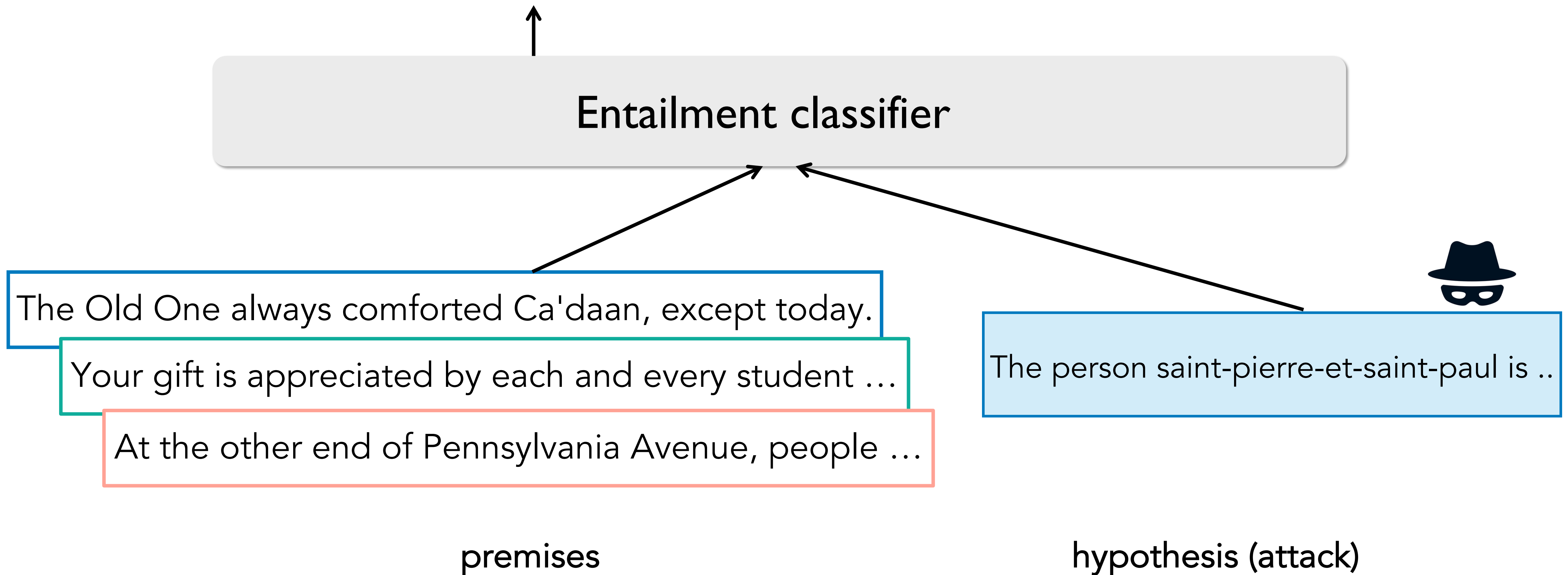
By James Vincent | Mar 29, 2021, 8:24am EDT



# When no (good) data is available?

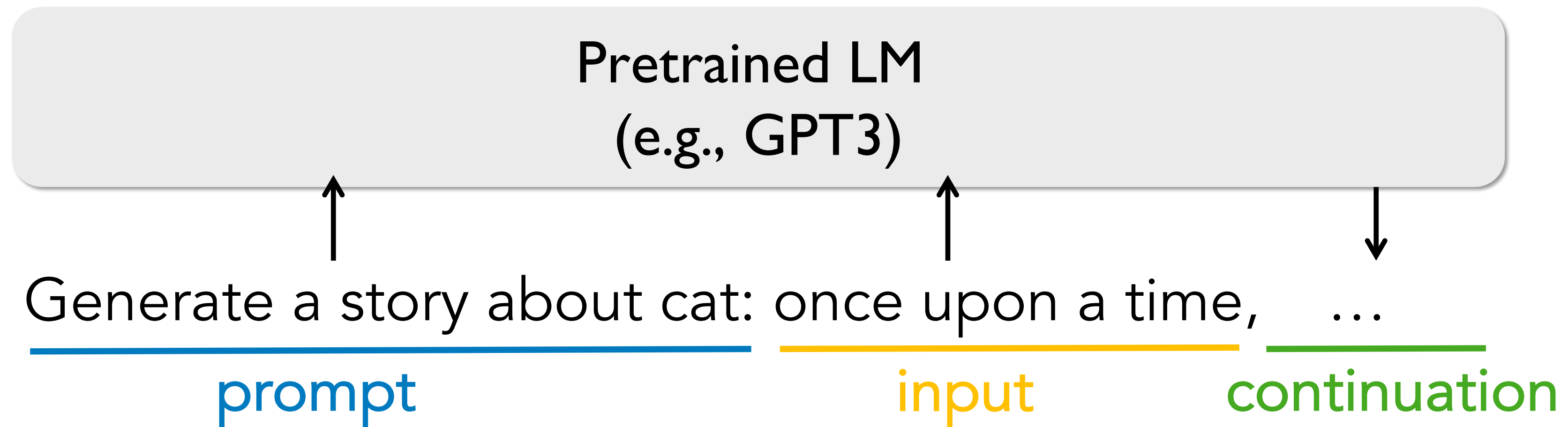
## Ex1: Adversarial attacks

"entailment" "neutral" "contradiction"



# When no (good) data is available?

## Ex2: Prompt generation



Automatically generating prompts to steer pretrained LMs

# When no (good) data is available?

## Ex3: Controllable generation

### Controlling sentiment

**Pos** The film is *full of imagination!*



**Neg** The film is *strictly routine!*

### Controlling writing style

**Plain** LeBron James *contributed* 26 points, 8 rebounds, 7 assists.



**Elaborate** LeBron James *rounded out the box score with an all around impressive performance, scoring* 26 points, *grabbing* 8 rebounds and *dishing out* 7 assists.

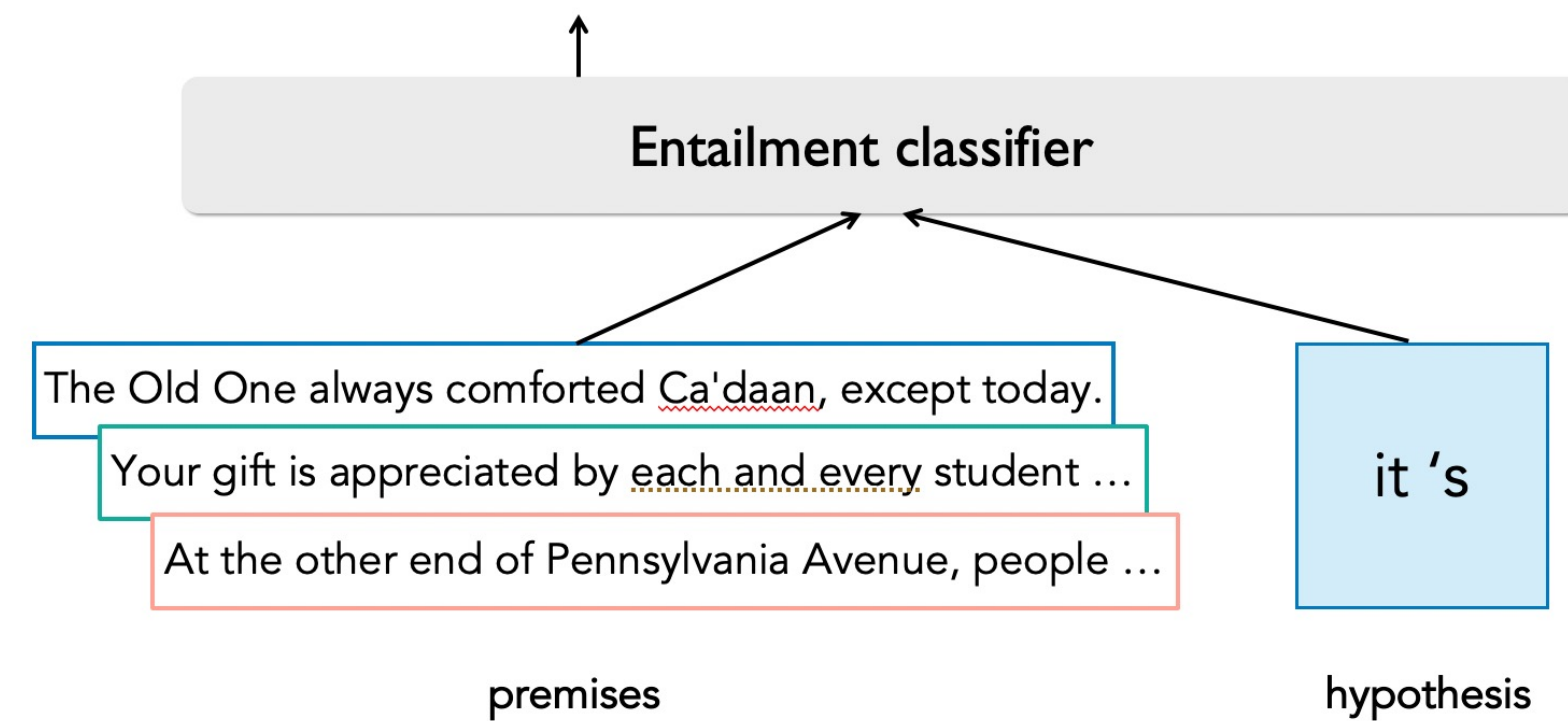
[Hu et al., 2017; Shen et al., 2017]

[Lin et al., 2020]

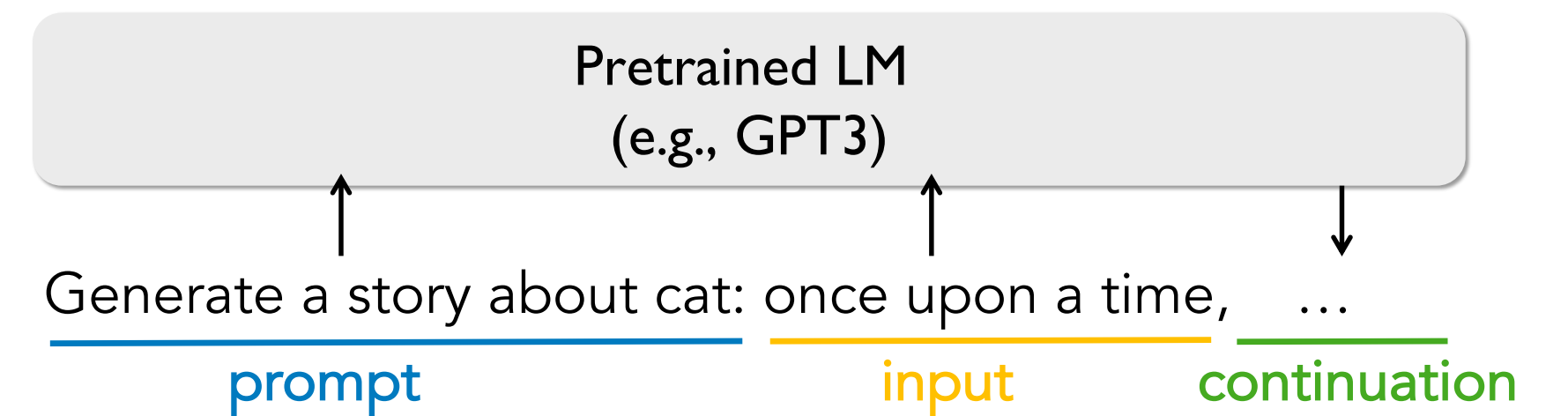


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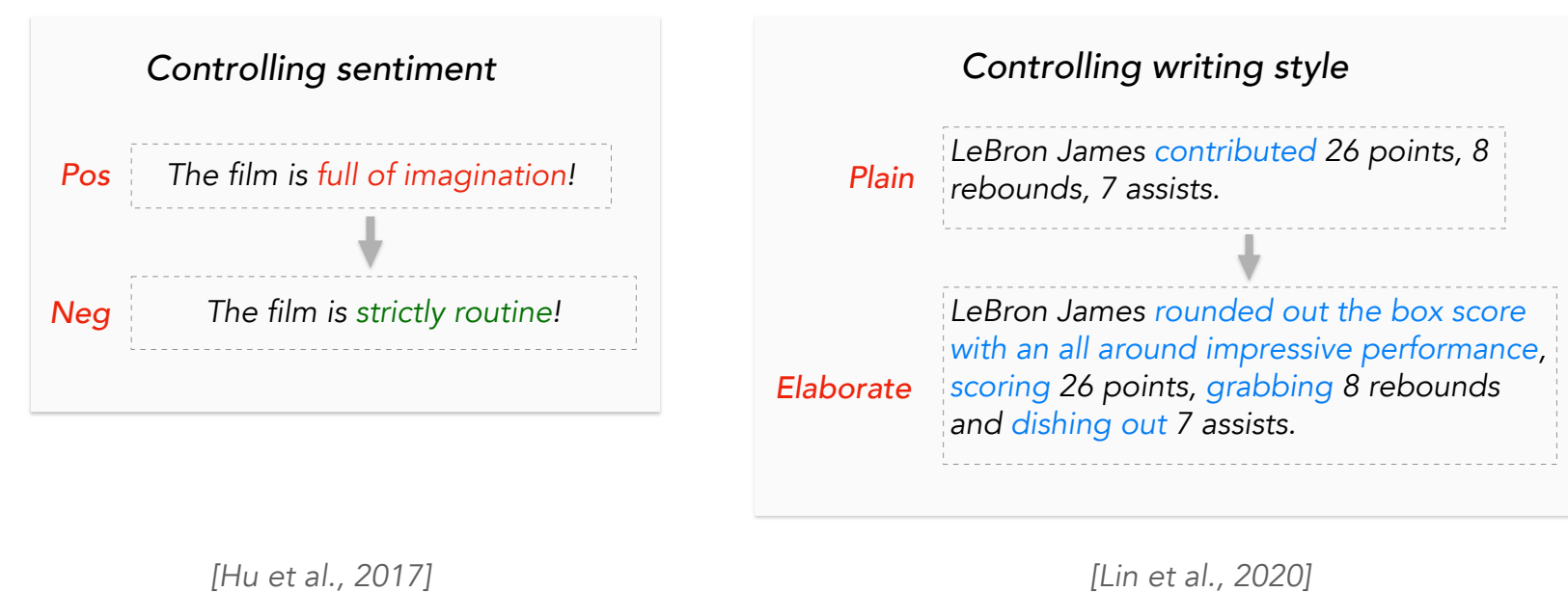
## Adversarial attacks



## Prompt generation



## Controllable generation



# Learning Text Generation from Reward

## Adversarial attacks

Compose **Reward-1** + **Reward-2**, and run Reinforcement Learning

**Reward-1**: success rate of attack

**"entailment"** "neutral" "contradiction"

Entailment classifier

The Old One always comforted Ca'daan, except today.

Your gift is appreciated by each and every student ...

At the other end of Pennsylvania Avenue, people ...

premises

The person saint-pierre-et-saint-paul is ..

hypothesis (attack)

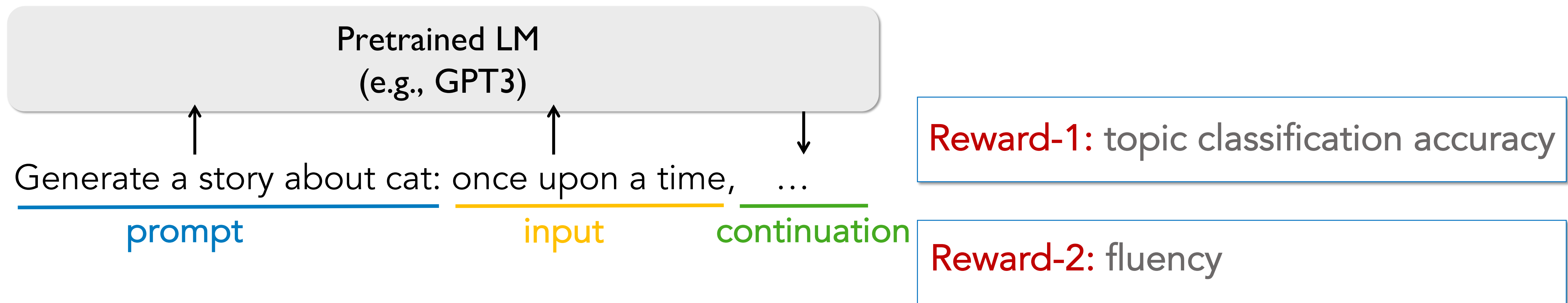


**Reward-2**: fluency

# Learning Text Generation from **Reward**

## Prompt generation

Compose **Reward-1** + **Reward-2**, and run Reinforcement Learning

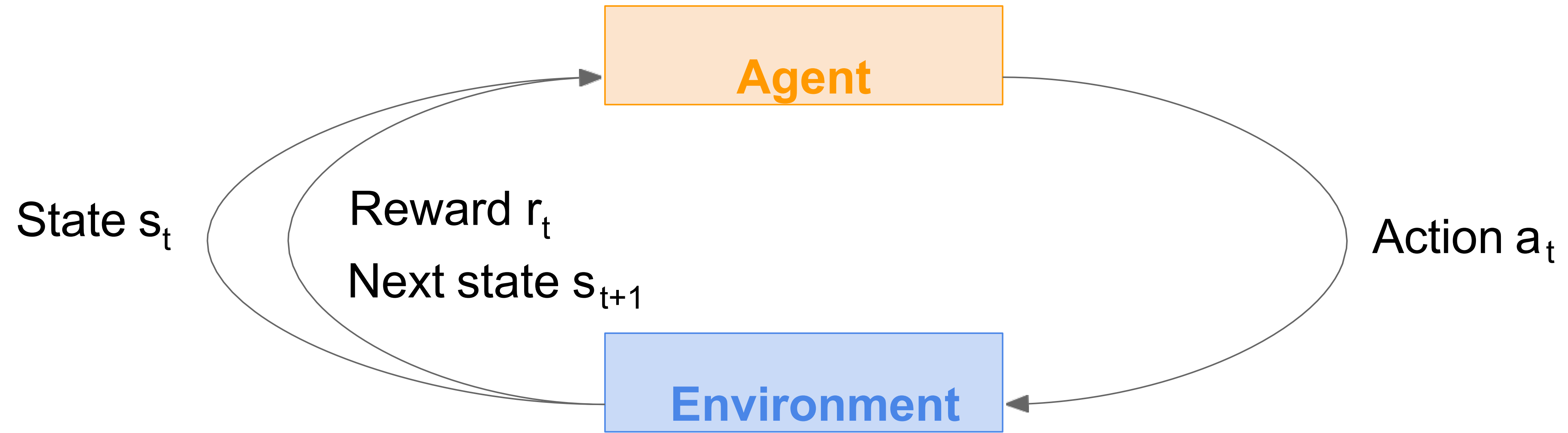


Automatically generating prompts to steer pretrained LMs



# Reinforcement Learning (RL)

- Plug in arbitrary reward functions to drive learning
- Fertile research area for robotic and game control



# Reinforcement Learning (RL)

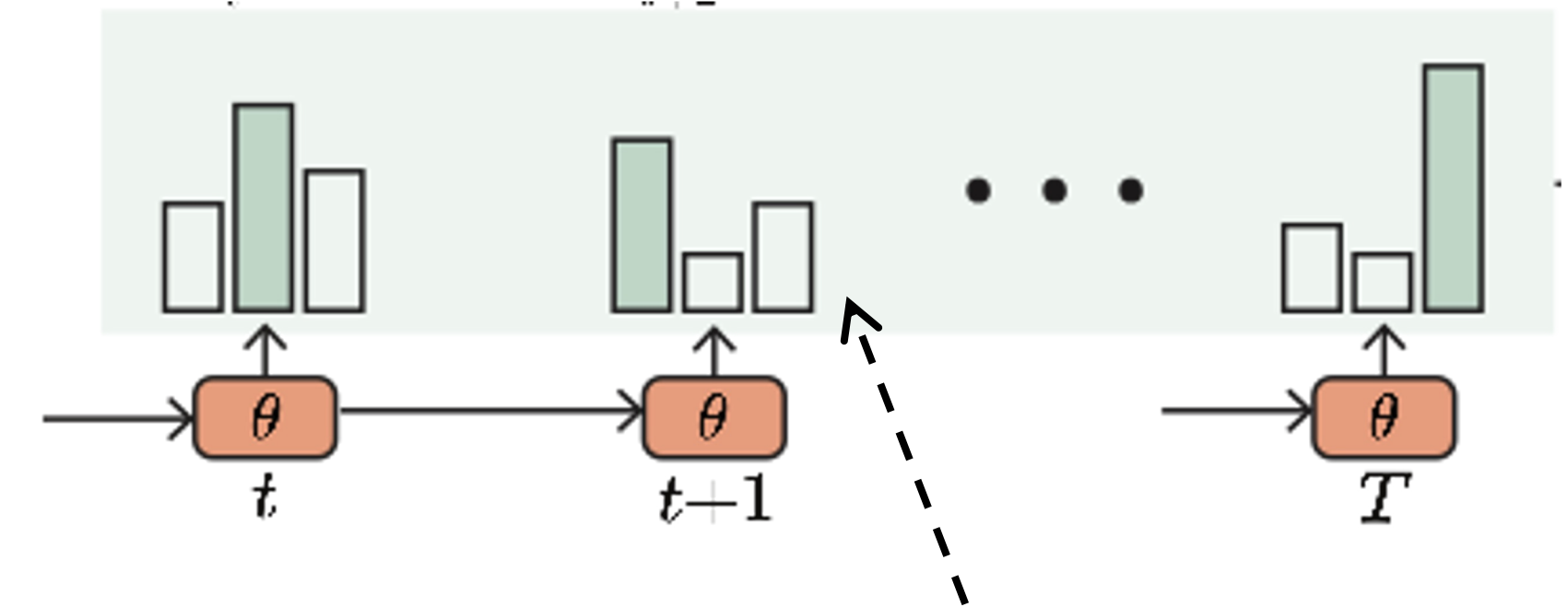
- Plug in arbitrary reward functions to drive learning
- Fertile research area for robotic and game control

**But ...** limited success for training text generation

- Challenges:
  - **Extremely large sequence space:**  $(\text{vocab-size})^{\text{text-length}} \sim (10^4)^{20}$
  - **Sparse reward:** only after seeing the whole text sequence

# RL for Text Generation: Formulation

- (Autoregressive) text generation model:



Sentence  $\mathbf{y} = (y_0, \dots, y_T)$

$$\pi_{\theta}(y_t | \mathbf{y}_{<t}) = \text{softmax}(f_{\theta}(y_t | \mathbf{y}_{<t}))$$

logits

In RL terms:

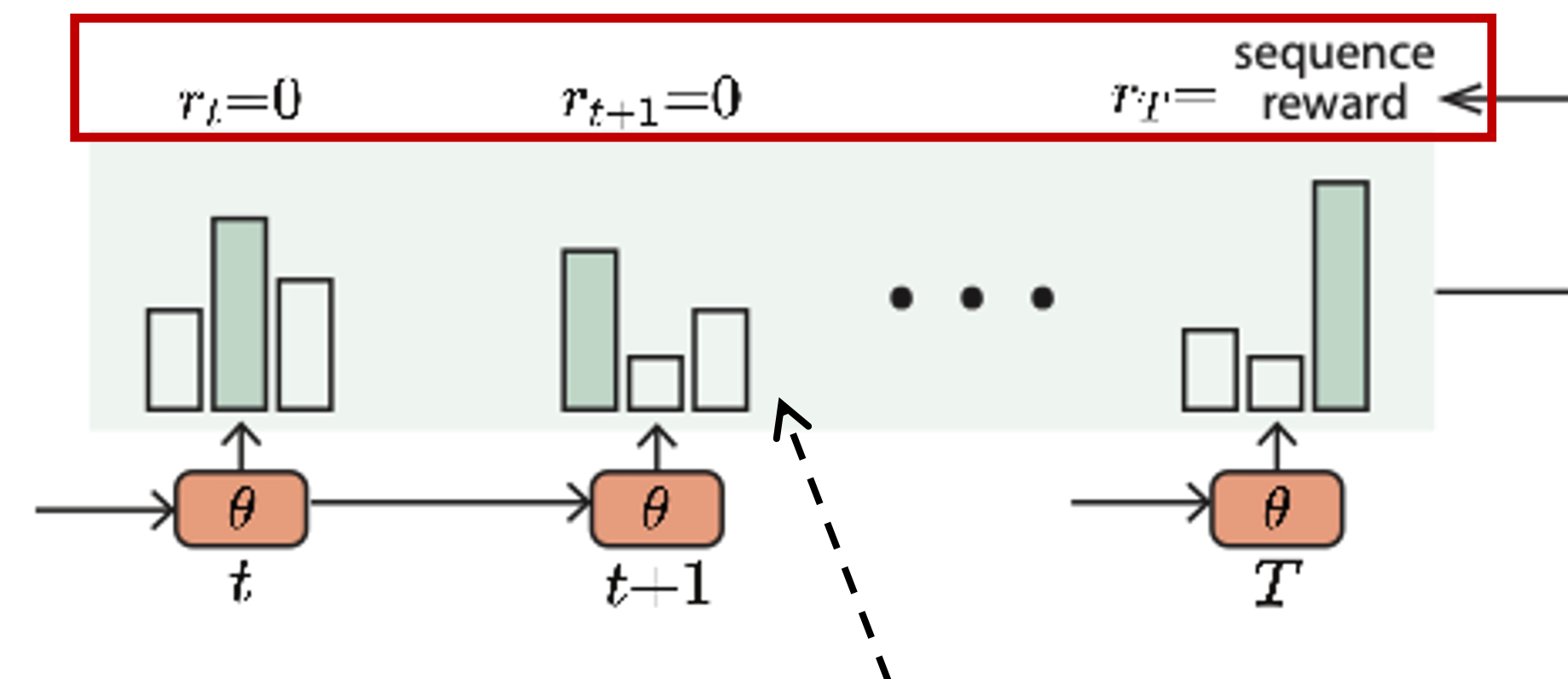
trajectory,  $\tau$

action,  $a_t$

state,  $s_t$

policy  $\pi_{\theta}(a_t | s_t)$

# RL for Text Generation: Formulation



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logits

In RL terms:

trajectory,  $\tau$

action,  $a_t$

state,  $\mathbf{s}_t$

policy  $\pi_{\theta}(a_t | \mathbf{s}_t)$

- Reward  $r_t = r(\mathbf{s}_t, a_t)$ 
  - Often **sparse**:  $r_t = 0$  for  $t < T$
- The general RL objective: maximize cumulative reward  $J(\pi) = \mathbb{E}_{\tau \sim \pi} \left[ \sum_{t=0}^T \gamma^t r_t \right]$
- $Q$ -function: **expected future reward** of taking action  $a_t$  in state  $\mathbf{s}_t$

$$Q^{\pi}(\mathbf{s}_t, a_t) = \mathbb{E}_{\pi} \left[ \sum_{t'=t}^T \gamma^{t'} r_{t'} \mid \mathbf{s}_t, a_t \right]$$

# RL for Text Generation: Formulation

- On-policy RL
  - Most popular, e.g., *Policy Gradient (PG)*

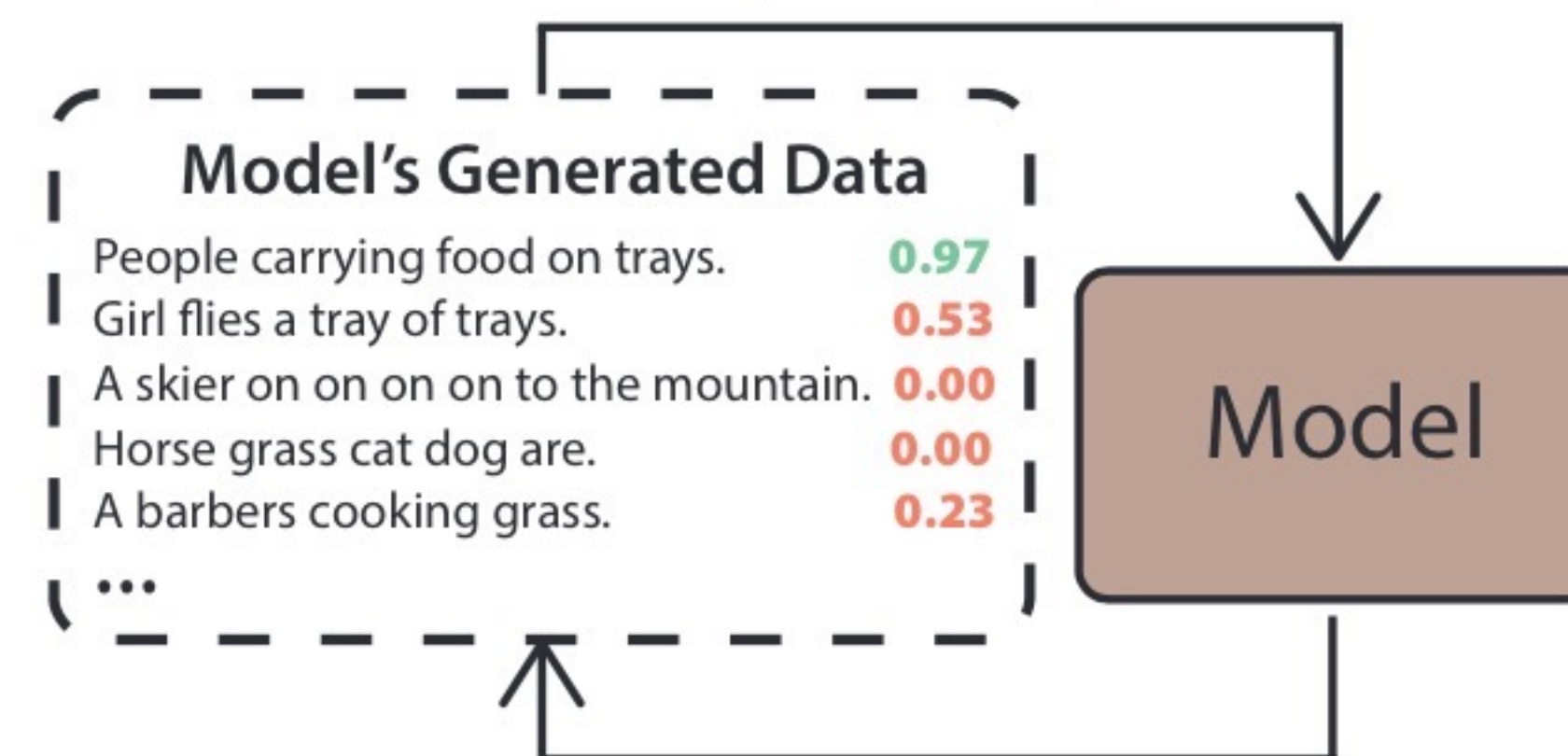
$$\nabla_{\theta} J(\pi_{\theta}) = -\mathbb{E}_{\tau \sim \pi_{\theta}} \left[ \sum_{t=0}^T \hat{Q}(\mathbf{s}_t, a_t) \nabla_{\theta} \log \pi_{\theta}(a_t | \mathbf{s}_t) \right]$$

Generate text samples from the current policy  $\pi_{\theta}$  itself



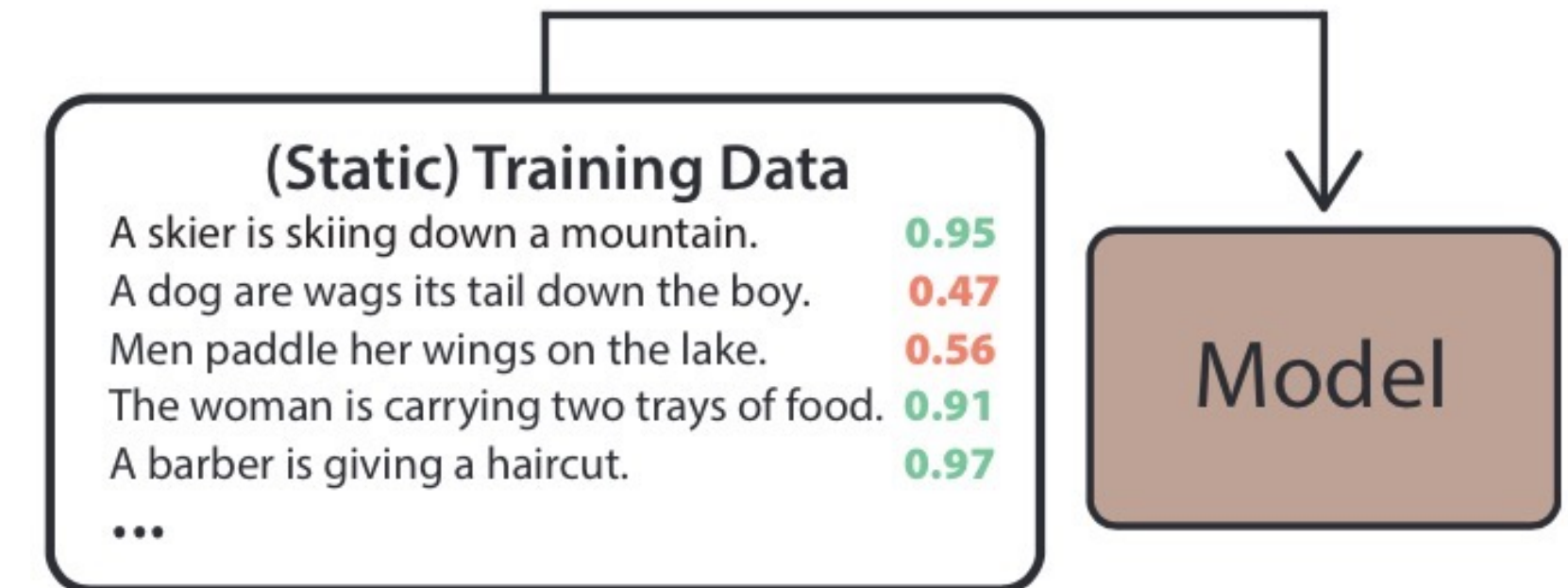
**Extremely low data efficiency:** most samples from  $\pi_{\theta}$  are gibberish with zero reward

## On-policy RL





# Off-policy RL



## RL for Text Generation: Formulation

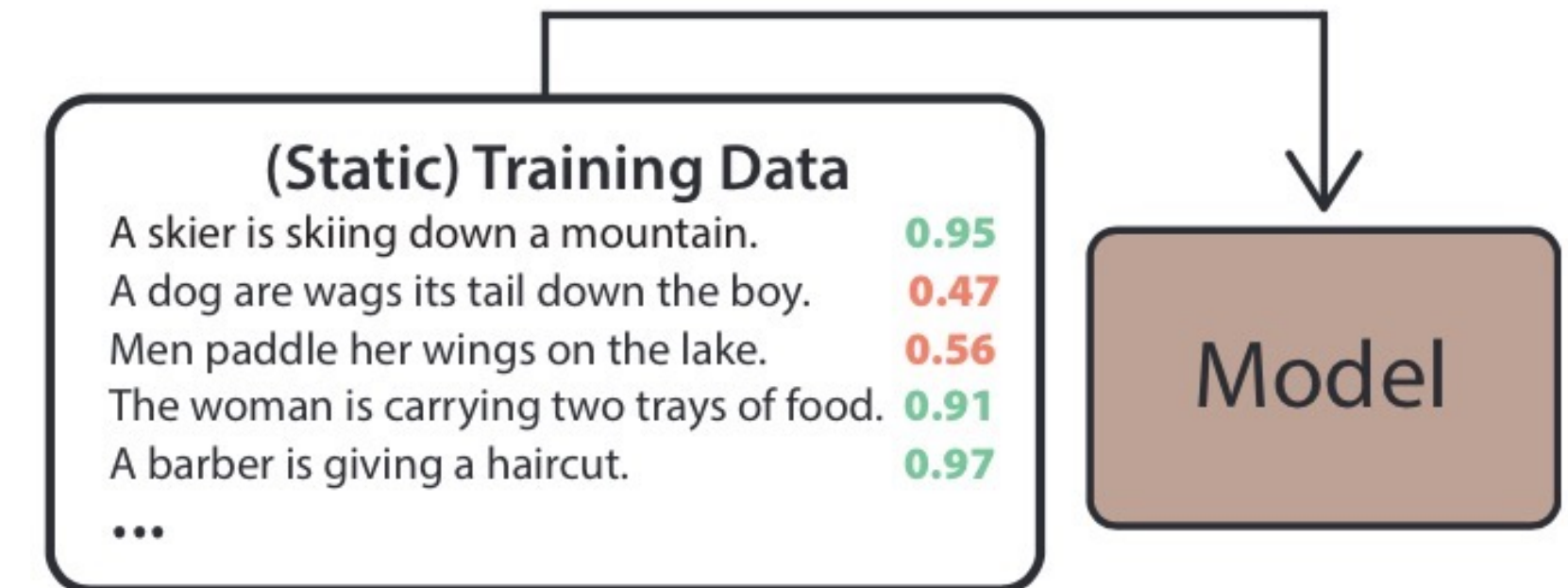
- Off-policy RL
  - e.g., *Q-learning*
  - Implicitly learns the policy  $\pi$  by approximating the  $Q^\pi(\mathbf{s}_t, a_t)$
  - Bellman temporal consistency:  $Q^*(\mathbf{s}_t, a_t) = r_t + \gamma \max_{a_{t+1}} Q^*(\mathbf{s}_{t+1}, a_{t+1})$
  - Learns  $Q_\theta$  with the regression objective:

$$\mathcal{L}(\theta) = \mathbb{E}_{\pi'} \left[ \frac{1}{2} \left( r_t + \gamma \max_{a_{t+1}} Q_{\bar{\theta}}(\mathbf{s}_{t+1}, a_{t+1}) - Q_\theta(\mathbf{s}_t, a_t) \right)^2 \right]$$

Arbitrary policy

- After learning, induces the policy as  $a_t = \operatorname{argmax}_a Q_{\theta^*}(\mathbf{s}_t, a)$





## RL for Text Generation: Formulation

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Arbitrary policy



Regression target is **unstable**

- Bootstrapped  $Q_{\bar{\theta}}$
- Sparse reward  $r_t = 0$  ( $t < T$ ): no "true" training signal

- After learning, induces the policy as  $a_t = \operatorname{argmax}_a Q_{\theta^*}(\mathbf{s}_t, a)$

# RL for Text Generation: Formulation

- On-policy RL, e.g., *Policy Gradient (PG)*
  - Exploration to maximize reward directly

👹 Extremely low data efficiency

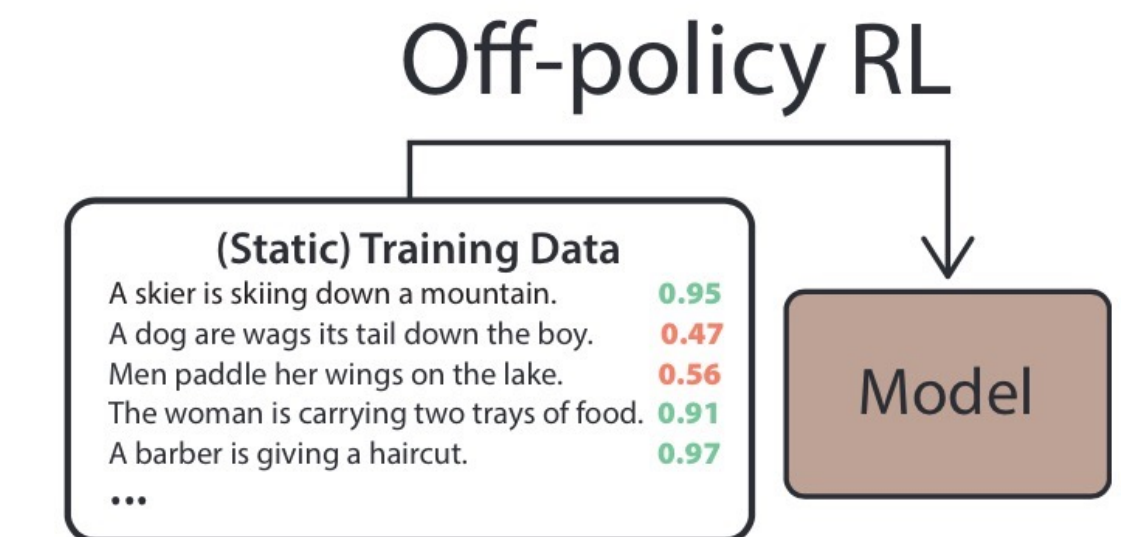
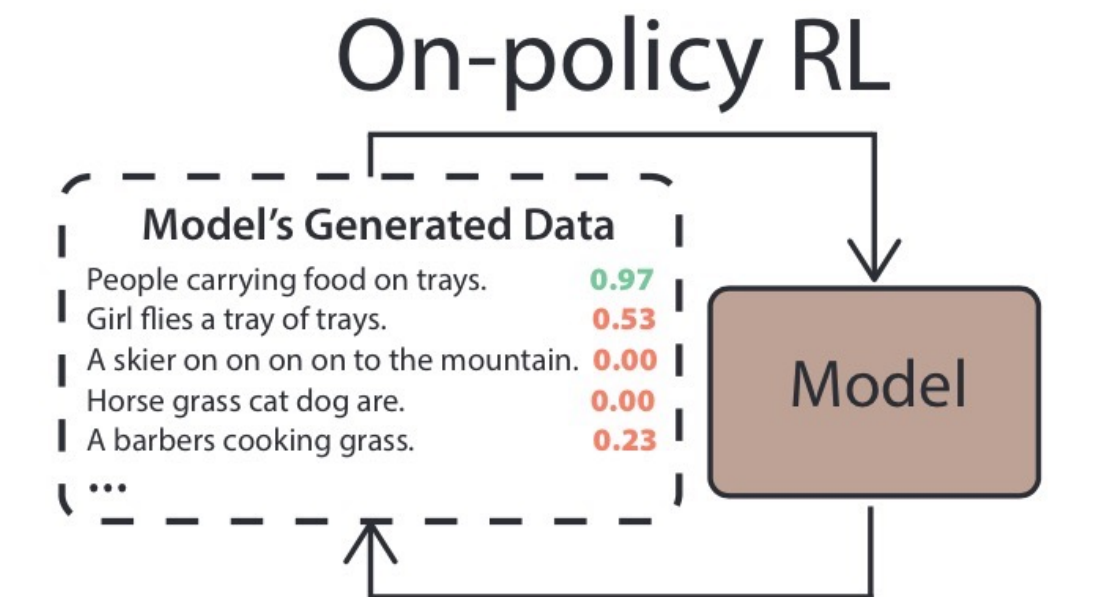
- Off-policy RL, e.g., *Q-learning*

👹 Unstable training due to bootstrapping & sparse reward

👹 Slow updates due to large action space

👹 Sensitive to off-policy data quality

... Limited success for training text generation



# New RL for Text Generation: Soft $Q$ -Learning (SQL)

(Hard)  $Q$ -learning

- Goal

$$J(\pi) = \mathbb{E}_{\tau \sim \pi} \left[ \sum_{t=0}^T \gamma^t r_t \right]$$

- Induced policy

$$a_t = \operatorname{argmax}_a Q_{\theta^*}(\mathbf{s}_t, a)$$

SQL

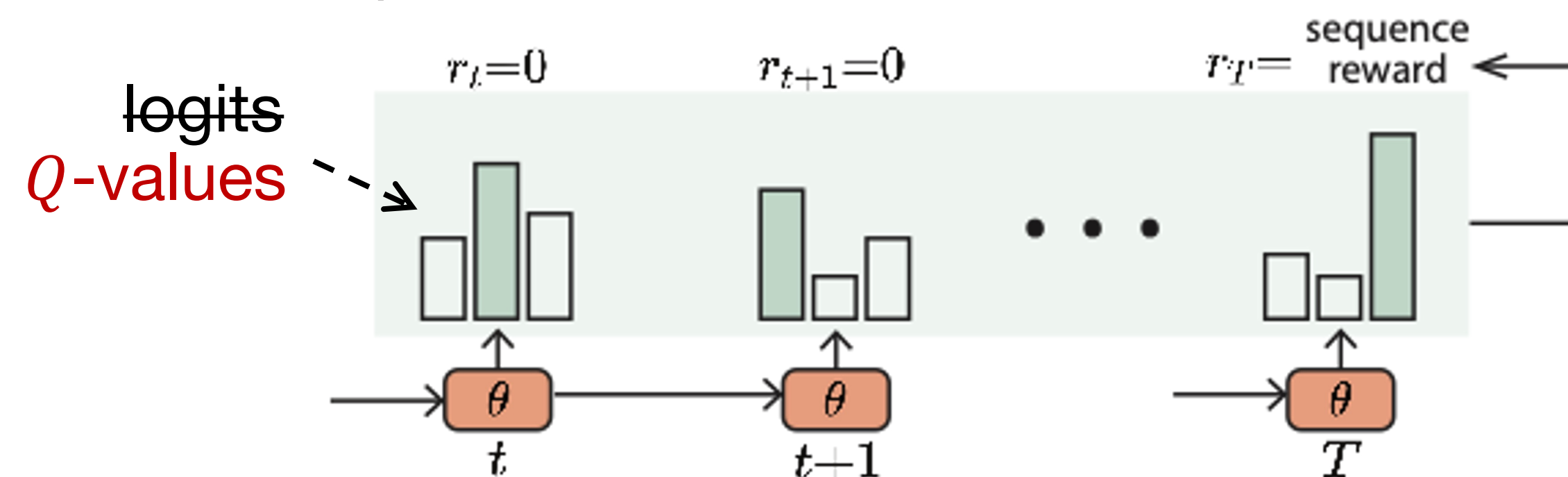
- Goal: entropy regularized

$$J_{\text{MaxEnt}}(\pi) = \mathbb{E}_{\tau \sim \pi} \left[ \sum_{t=0}^T \gamma^t r_t + \alpha \mathcal{H}(\pi(\cdot | \mathbf{s}_t)) \right]$$

- Induced policy

$$\pi_{\theta^*}(a_t | \mathbf{s}_t) = \operatorname{softmax}(Q_{\theta^*}(a_t | \mathbf{s}_t))$$

Generation model's "logits" now act as  $Q$ -values !



# New RL for Text Generation: Soft $Q$ -Learning (SQL)

## (Hard) $Q$ -learning

- Goal

$$J(\pi) = \mathbb{E}_{\tau \sim \pi} \left[ \sum_{t=0}^T \gamma^t r_t \right]$$

- Induced policy

$$a_t = \operatorname{argmax}_a Q_{\theta^*}(\mathbf{s}_t, a)$$

- Training objective:

- Based on temporal consistency

 Unstable training / slow updates

## SQL

- Goal: entropy regularized


$$J_{\text{MaxEnt}}(\pi) = \mathbb{E}_{\tau \sim \pi} \left[ \sum_{t=0}^T \gamma^t r_t + \alpha \mathcal{H}(\pi(\cdot | \mathbf{s}_t)) \right]$$

- Induced policy

$$\pi_{\theta^*}(a_t | \mathbf{s}_t) = \operatorname{softmax}(Q_{\theta^*}(a_t | \mathbf{s}_t))$$

- Training objective:

- Based on **path consistency**

 Stable / efficient



# Efficient Training via Path Consistency

$$V^*(\mathbf{s}) = \log \sum_{a'} \exp Q^*(\mathbf{s}, a')$$

$$\pi^*(a | \mathbf{s}) = \text{softmax}(Q^*(a | \mathbf{s}))$$

- (Multi-step) path consistency

$$V^*(\mathbf{s}_t) - \gamma^{T-t} V^*(\mathbf{s}_{T+1}) = \sum_{l=0}^{T-t} \gamma^l (r_{t+l} - \log \pi^*(a_{t+l} | \mathbf{s}_{t+l}))$$



**Stable** updates: Non-zero reward signal  $r_T$  as regression target

- Objective

$$\mathcal{L}_{\text{SQL, PCL-ms}}(\boldsymbol{\theta}) = \mathbb{E}_{\pi'} \left[ \frac{1}{2} \left( -V_{\bar{\theta}}(\mathbf{s}_t) + \gamma^{T-t} r_T - \sum_{l=0}^{T-t} \gamma^l \log \pi_{\theta}(a_{t+l} | \mathbf{s}_{t+l}) \right)^2 \right]$$



**Fast** updates: gradient involves  $Q_{\theta}$  values of *all* tokens in the vocab

# Implementation is easy

```
model = TransformerLM(...)

for iter in range(max_iters):
    if mode == "off-policy":
        batch = dataset.sample_batch()
        sample_ids = batch.text_ids

    if mode == "on-policy":
        sample_ids = model.decode()

    Q_values = model.forward(sample_ids)
    Q_values_target = target_model.forward(sample_ids)

    rewards = compute_rewards(sample_ids)

    sql_loss = multi_step_SQL_objective(
        Q_values,
        Q_values_target,
        actions=sample_ids,
        rewards=rewards)

    # gradient descent over sql_loss
    # ...
```

```
def multi_step_SQL_objective(
    Q_values, Q_values_target, actions, rewards):

    V = Q_values.logsumexp(dim=-1)
    A = Q_values[actions] - V

    V_target = Q_values_target.logsumexp(dim=-1)

    A2 = masked_reverse_cumsum(
        A, lengths=actions.sequence_length,
        dim=-1)

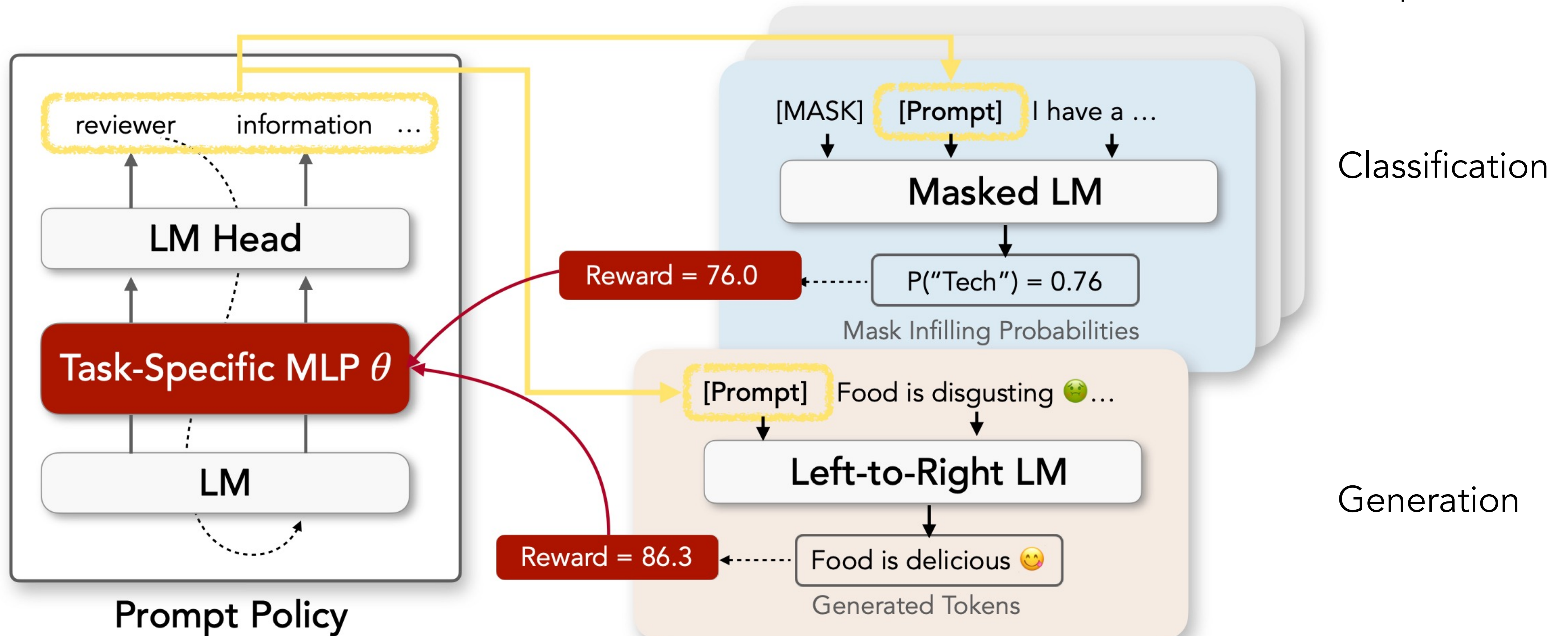
    return F.mse_loss(
        A2, rewards.view(-1, 1) - V_target,
        reduction="none")
```



# Applications & Experiments

# Application (I): Prompt Optimization for Controlling LMs

- Optimize **discrete** prompts to steer pretrained LMs to produce desired outputs



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Methods	Frozen LMs	Automated	Gradient-free	Guided Optimize	Few-shot	Zero-shot	Transferrable b/w LMs	Interpret.
Finetuning	✗	✓	✗	✓	✗	✗	✗	✗
In-context Demo.	✓	✓	✓	✗	✓	✗	✓	✓
Instructions	✓	✗	✓	✗	✓	✓	✓	✓
Manual Prompt	✓	✗	✓	✗	✓	✓	✓	✓
Soft Prompt Tuning	✓	✓	✗	✓	✓	✗	✗	✗
Discrete Prompt Enum.	✓	✓	✓	✗	✓	✓	✓	✓
AutoPrompt	✓	✓	✗	✓	✓	✗	✓	✓
RLPrompt ( <b>Ours</b> )	✓	✓	✓	✓	✓	✓	✓	✓

Comparison of different (prompting) paradigms for using pretrained LMs on downstream tasks, in terms of a number of desirable properties.



# Application (I): Prompt Optimization for Controlling LMs

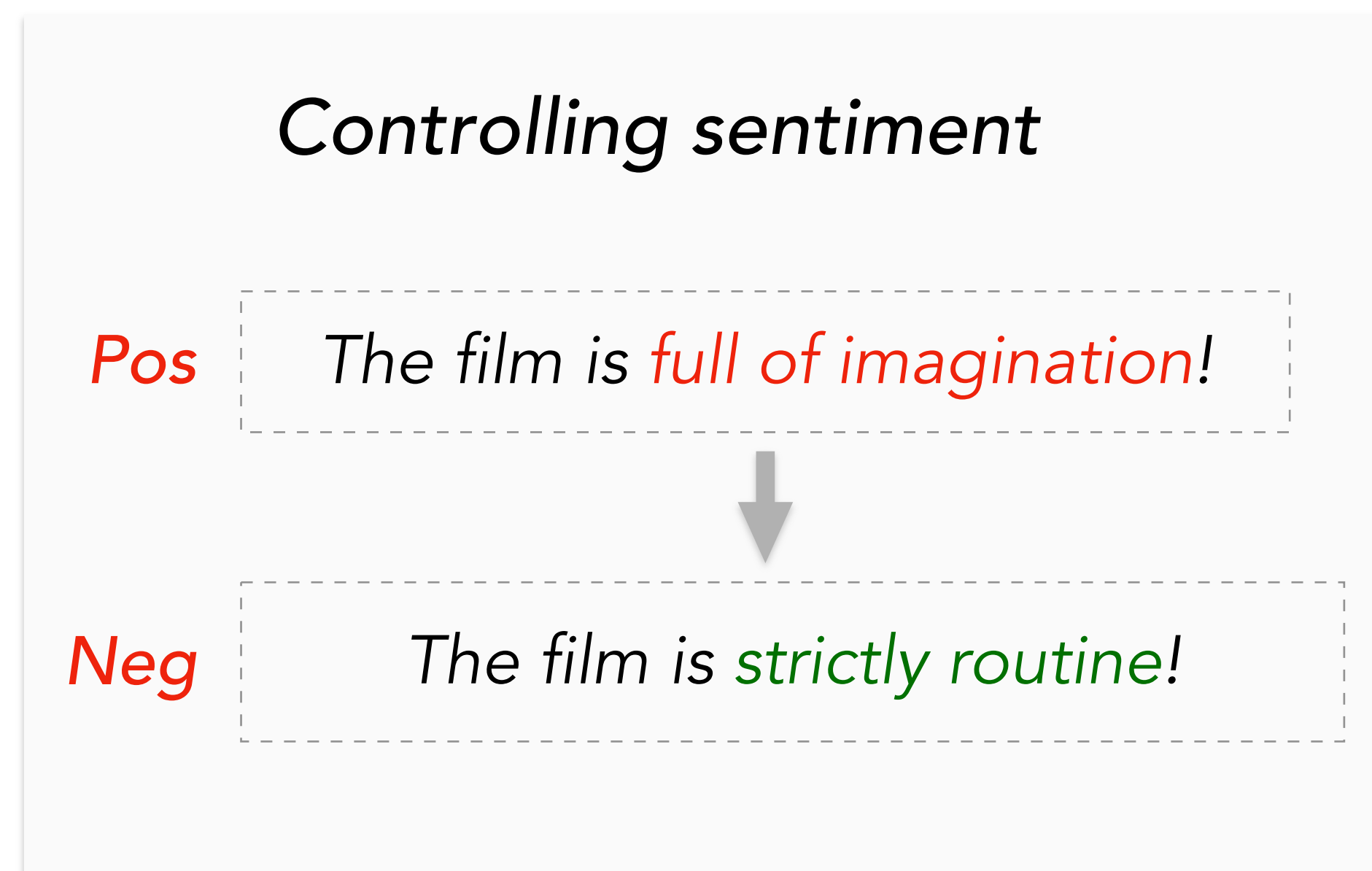
- Few-shot classification

	<b>SST-2</b>	<b>Yelp P.</b>	<b>MR</b>	<b>CR</b>	<b>AG's News</b>
Finetuning	80.6 (3.9)	88.7 (4.7)	67.4 (9.7)	73.3 (7.5)	<b>84.9</b> (3.6)
Manual Prompt	82.8	83.0	80.9	79.6	76.9
In-context Demo.	85.9 (0.7)	89.6 (0.4)	80.6 (1.4)	85.5 (1.5)	74.9 (0.8)
Instructions	89.0	84.4	85.2	80.8	54.8
Prompt Tuning ( <i>Soft Prompt Tuning</i> )	73.8 (10.9)	88.6 (2.1)	74.1 (14.6)	75.9 (11.8)	82.6 (0.9)
Black-Box Tuning ( <i>Mixed Prompt + Soft Tuning</i> )	89.1 (0.9)	93.2 (0.5)	86.6 (1.3)	<b>87.4</b> (1.0)	83.5 (0.9)
GrIPS ( <i>Discrete Prompt Enum.</i> )	87.1 (1.5)	88.2 (0.1)	86.1 (0.3)	80.0 (2.5)	65.4 (9.8)
AutoPrompt	75.0 (7.6)	79.8 (8.3)	62.0 (0.8)	57.5 (5.8)	65.7 (1.9)
RLPrompt (Ours)	<b>90.1</b> (1.8)	<b>93.9</b> (1.8)	<b>86.7</b> (2.4)	87.2 (1.7)	77.2 (2.0)

Table 3: Results of few-shot text classification, comparing with methods of different paradigms in Table 1

# Application (I): Prompt Optimization for Controlling LMs

- Text style transfer



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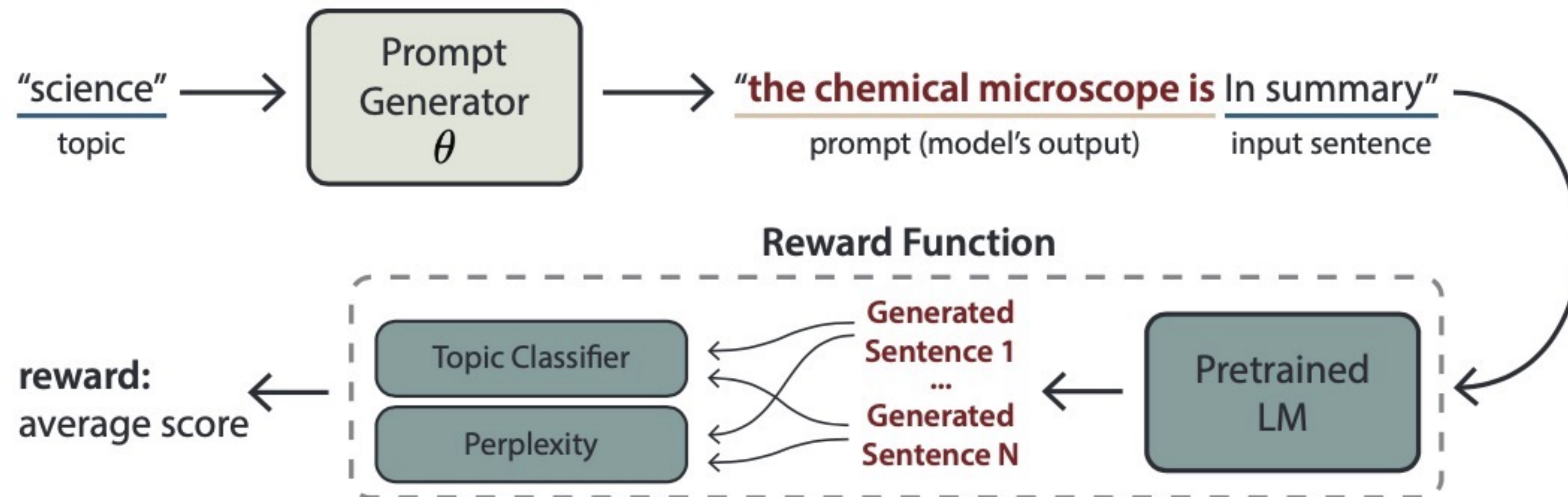
Model	Content	Style	Fluency	$J(C, S, F)$	$GM(C, S, F)$	BLEU	BERTScore	PPL↓
<i>Oracles</i>								
Copy	100 (0.0)	1.4 (0.0)	92.2 (0.0)	11.9 (0.0)	23.5 (0.0)	30.1 (0.0)	62.2 (0.0)	20.6 (0.0)
Reference	62.2 (0.0)	78.9 (0.0)	88.7 (0.0)	55.9 (0.0)	75.8 (0.0)	100 (0.0)	100 (0.0)	30.8 (0.0)
<i>Training Baselines</i>								
Style Transformer	75.2 (0.1)	96.4 (0.1)	58.6 (0.2)	46.1 (0.2)	75.2 (0.1)	27.6 (0.1)	56.1 (0.0)	78.2 (0.3)
DiRR	<b>78.8 (0.0)</b>	<b>97.7 (0.1)</b>	75.6 (0.2)	59.6 (0.2)	83.5 (0.1)	<b>30.0 (0.0)</b>	<b>61.7 (0.0)</b>	40.6 (0.1)
<i>Prompting Baselines (GPT-2 xlarge)</i>								
Null Prompt	37.4 (0.1)	94.8 (0.1)	97.6 (0.1)	33.6 (0.1)	70.2 (0.1)	6.6 (0.1)	35.8 (0.1)	59.5 (2.0)
Random Prompt	39.6 (0.1)	93.8 (0.2)	<b>97.8 (0.1)</b>	34.7 (0.2)	71.3 (0.1)	7.3 (0.1)	37.4 (0.1)	60.5 (1.6)
Manual Prompt	64.2 (1.0)	91.5 (0.6)	93.2 (0.2)	53.4 (1.2)	81.8 (0.5)	19.2 (0.6)	53.1 (0.8)	35.5 (1.4)
<b>RLPROMPT (Ours)</b>								
distilGPT-2	57.3 (0.3)	96.5 (0.1)	85.3 (0.3)	46.0 (0.2)	77.9 (0.1)	15.7 (0.1)	49.1 (0.1)	43.6 (0.6)
GPT-2 small	60.0 (0.1)	96.4 (0.1)	89.0 (0.5)	50.7 (0.3)	80.1 (0.1)	16.5 (0.1)	51.3 (0.1)	37.8 (0.9)
GPT-2 medium	65.7 (0.2)	95.2 (0.2)	89.3 (0.2)	56.1 (0.6)	82.3 (0.1)	20.0 (0.2)	55.1 (0.2)	34.4 (0.3)
GPT-2 large	65.1 (0.3)	94.6 (0.4)	91.6 (0.2)	56.5 (0.5)	82.6 (0.1)	19.8 (0.1)	54.7 (0.1)	34.9 (0.3)
GPT-2 xlarge	72.1 (0.2)	94.2 (0.4)	89.5 (0.1)	<b>61.4 (0.7)</b>	<b>84.7 (0.2)</b>	24.2 (0.2)	59.0 (0.1)	<b>34.3 (0.3)</b>

Table 4: Automatic evaluation of our method vs. baselines on the Yelp (Shen et al., 2017) sentiment transfer dataset.



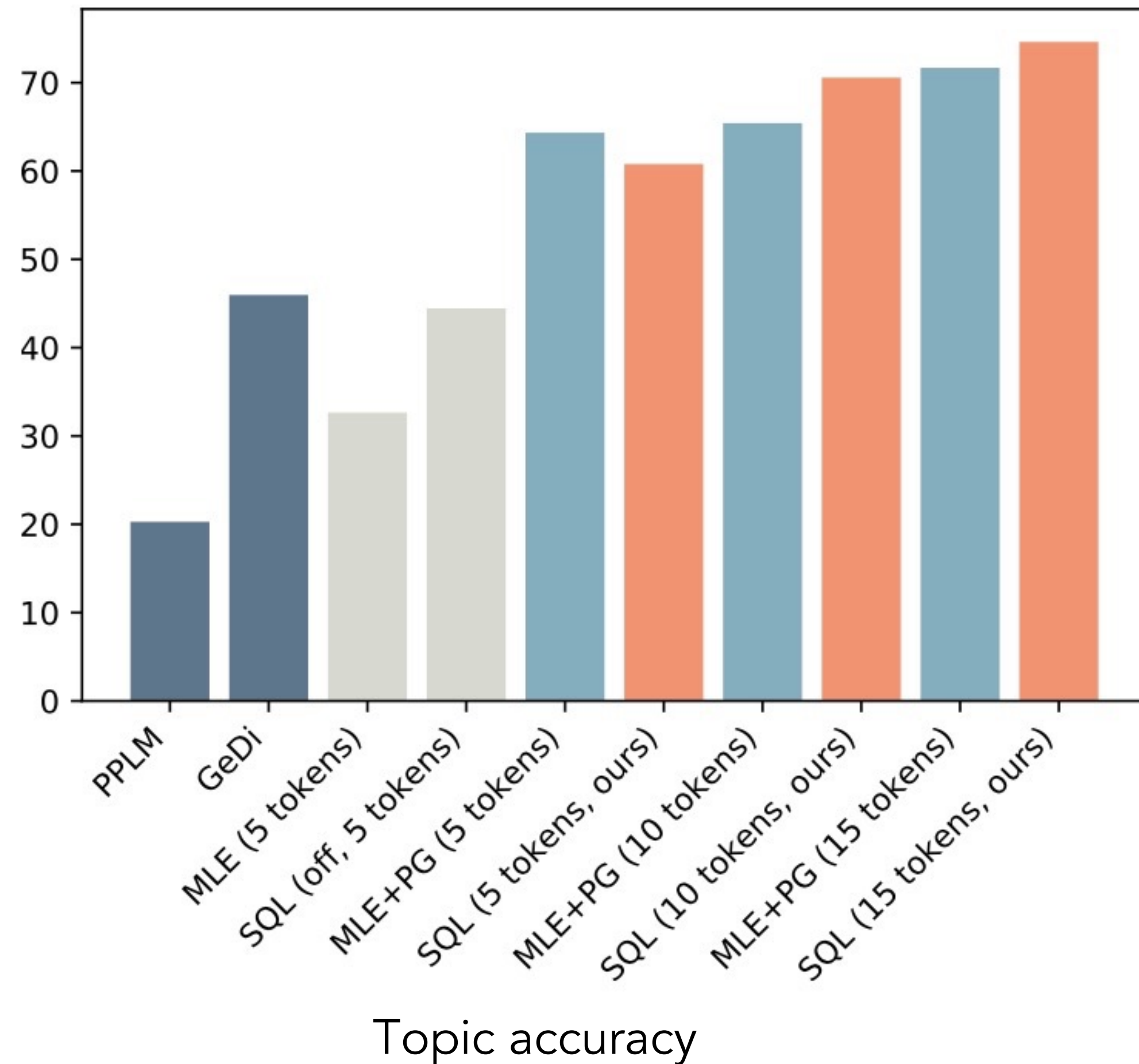
# Application (I): Prompt Optimization for Controlling LMs

- Topic-control generation



# Application (I): Prompt Optimization for Controlling LMs

- Steered decoding: PPLM, GeDi
- **SQL** achieves better overall accuracy+fluency
- Prompt control by **SQL, MLE+PG** > PPLM, GeDi
  - and much faster at inference!



PPLM	GeDi	MLE (5)	SQL (off, 5)
12.69	123.88	25.70	25.77
MLE+PG (5/10/15)		SQL (5/10/15, ours)	
25.52/28.16/28.71		25.94/26.95/29.10	

Language perplexity

Model	PPLM	GeDi	SQL
Seconds	5.58	1.05	0.07

Time cost for generating one sentence

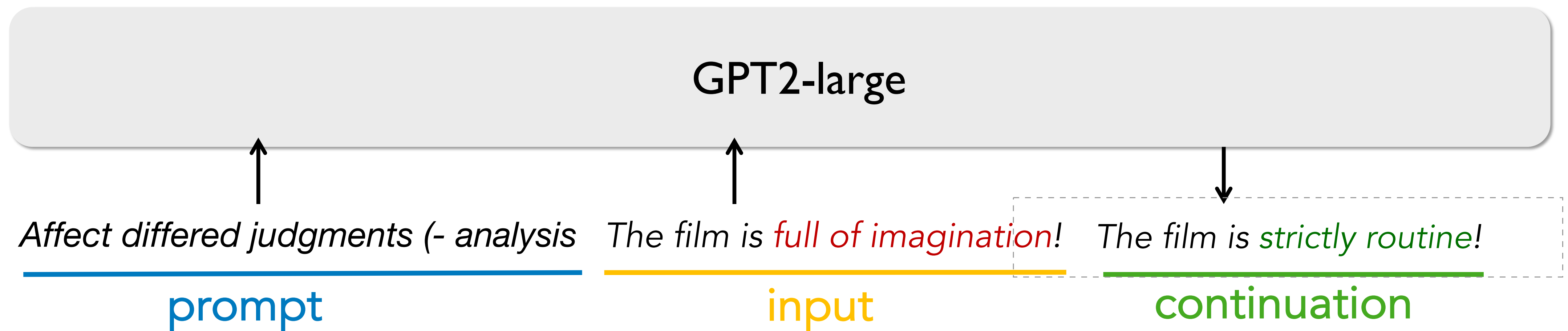
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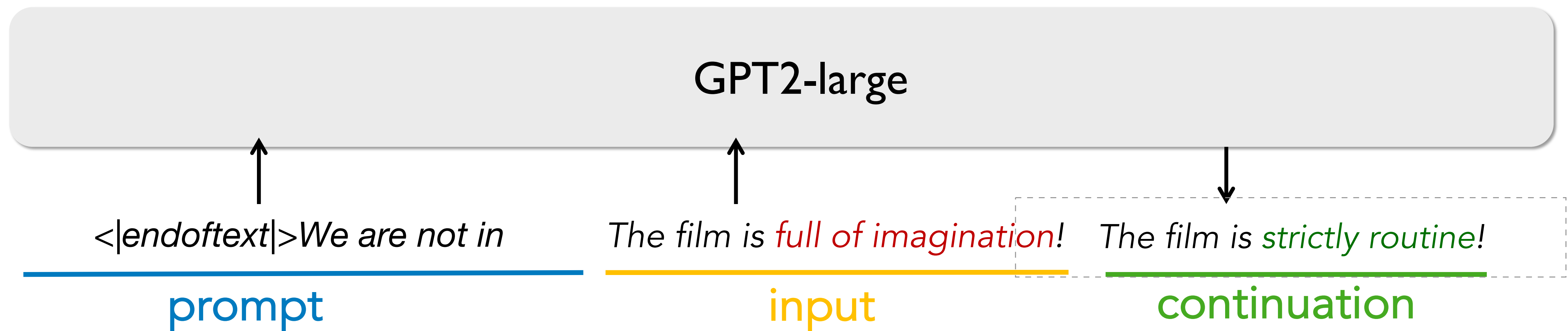




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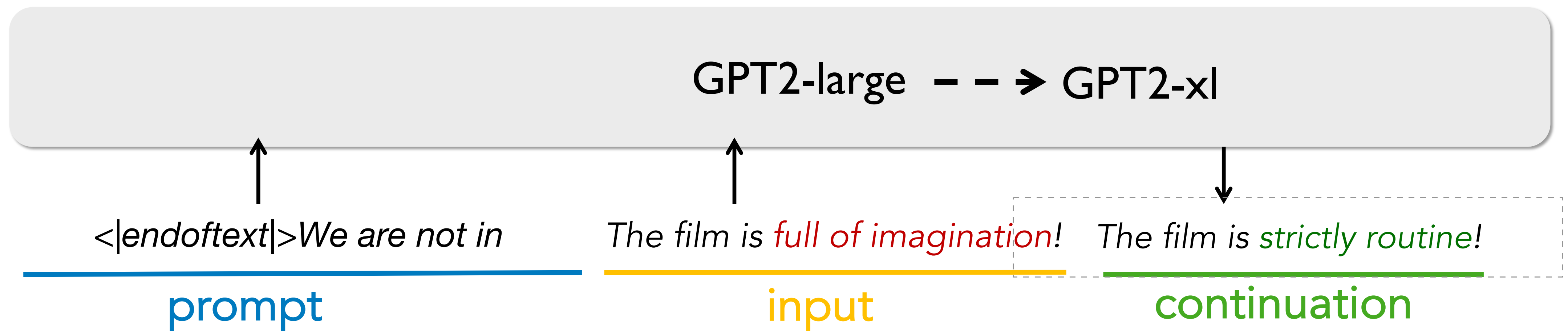
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  - Adding fluency constraint harms the performance



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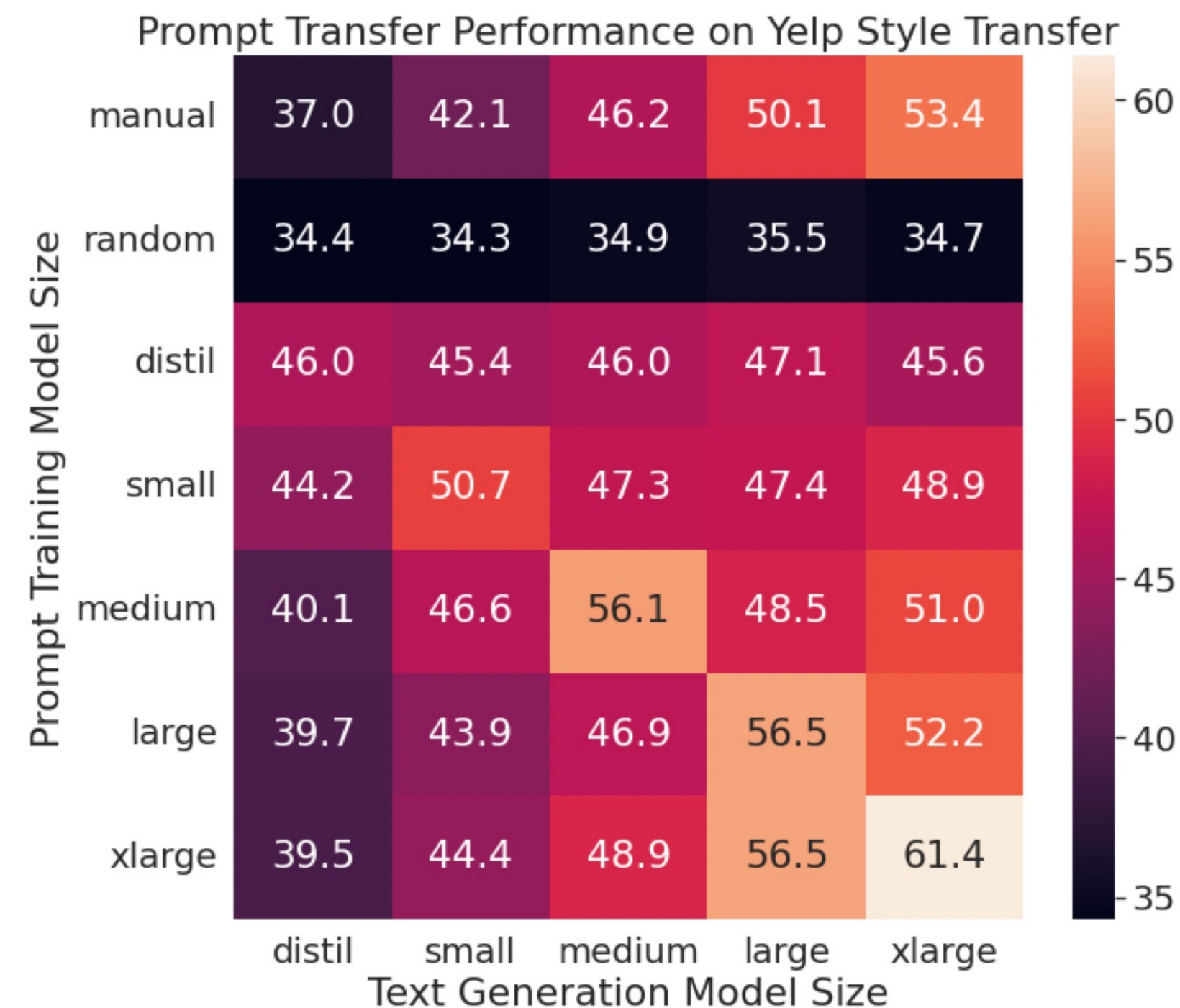
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- Those gibberish prompts are transferrable between LMs!



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  - Adding fluency constraint harms the performance
- Those gibberish prompts are transferrable between LMs!



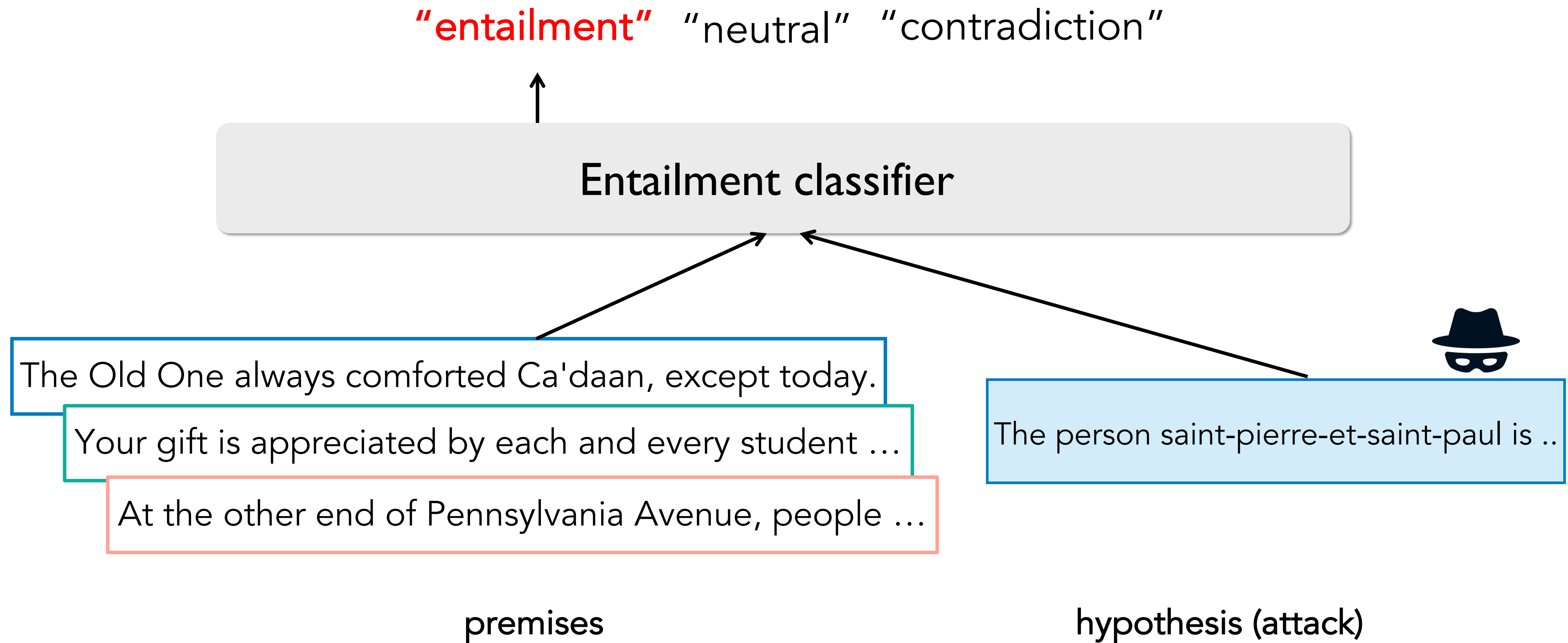
# Application (I): Prompt Optimization for Controlling LMs

Interesting (Surprising) observations:

- Optimized prompts tend to be ungrammatical ***gibberish***
  - Adding fluency constraint harms the performance
- Those gibberish prompts are transferrable between LMs!

LM prompting may not follow human language patterns

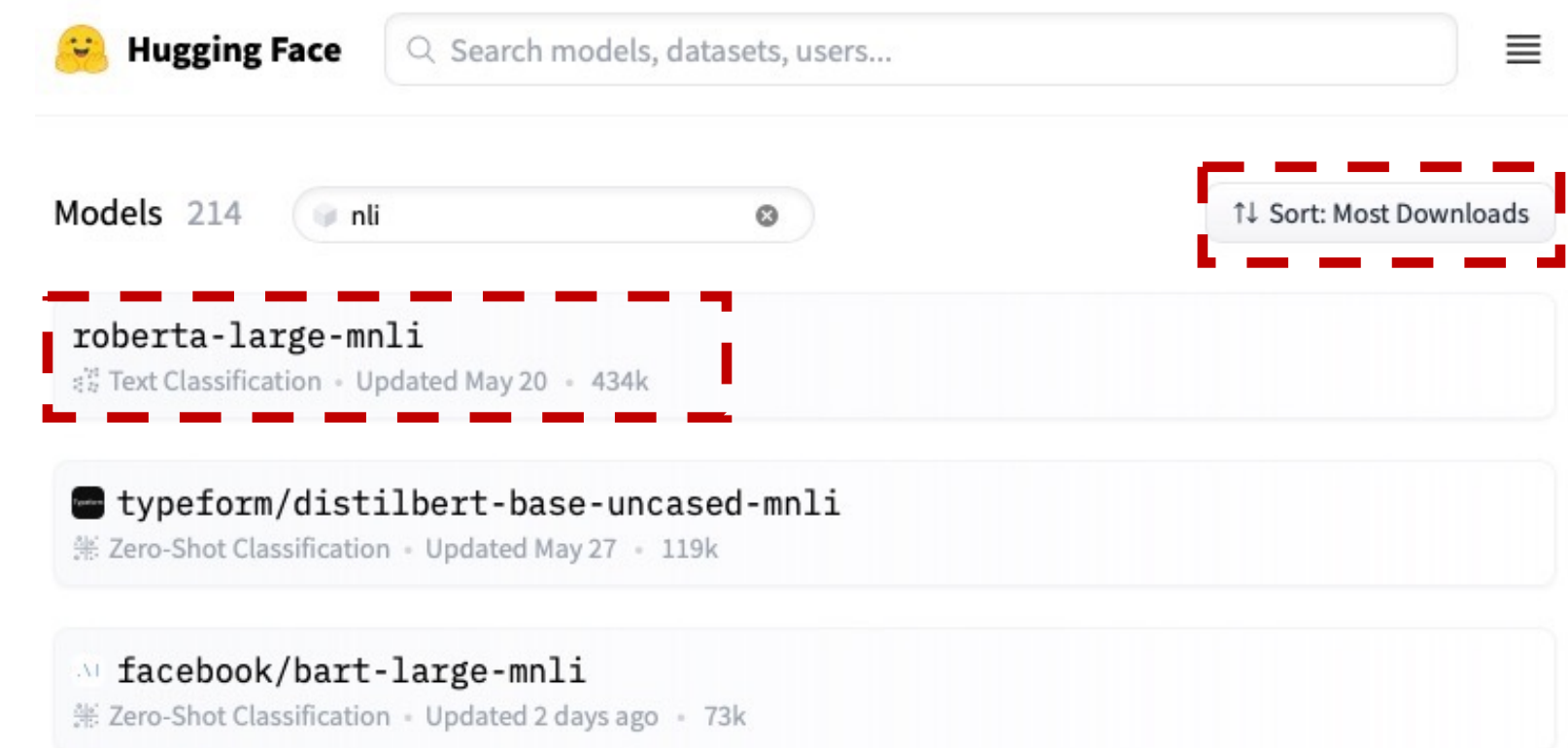
# Application (II): Universal Adversarial Attacks





# Application (II): Universal Adversarial Attacks

- Attacking entailment classifier
  - Generate **readable** hypotheses that are classified as “entailment” for **all** premises
  - *Unconditional* hypothesis generation model
- Training data:
  - No direct supervision data available
  - “Weak” data: all hypotheses in MultiNLI corpus
- Rewards:
  - Entailment classifier to attack
  - Pretrained LM for perplexity
  - BLEU w.r.t input premises
  - Repetition penalty

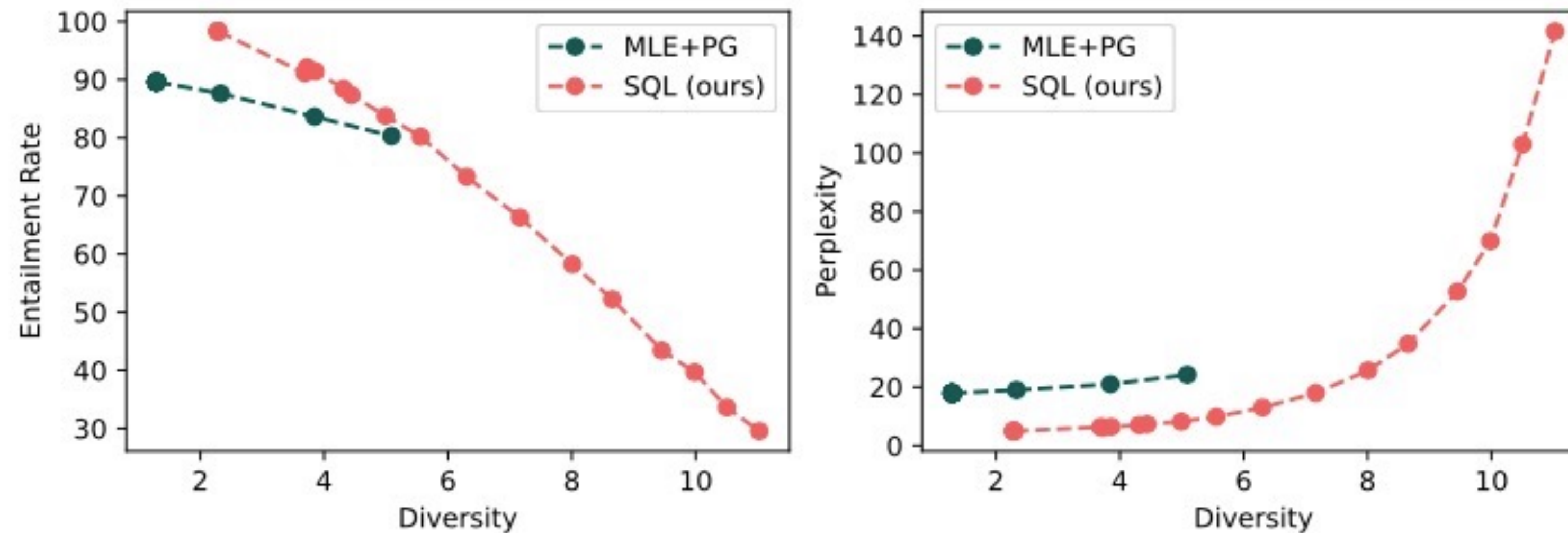


Previous adversarial algorithms are not applicable here:

- only attack for specific premise
- not readable

# Application (II): Universal Adversarial Attacks

- SQL (full) > MLE+PG (PG alone does not work)
- MLE+PG collapses: cannot generate more diverse samples



Model	Generation	Rate
MLE+PG	it 's .	90.48
SQL (ours)	the person saint-pierre-et-saint-paul is saint-pierre-et-saint-paul .	97.40

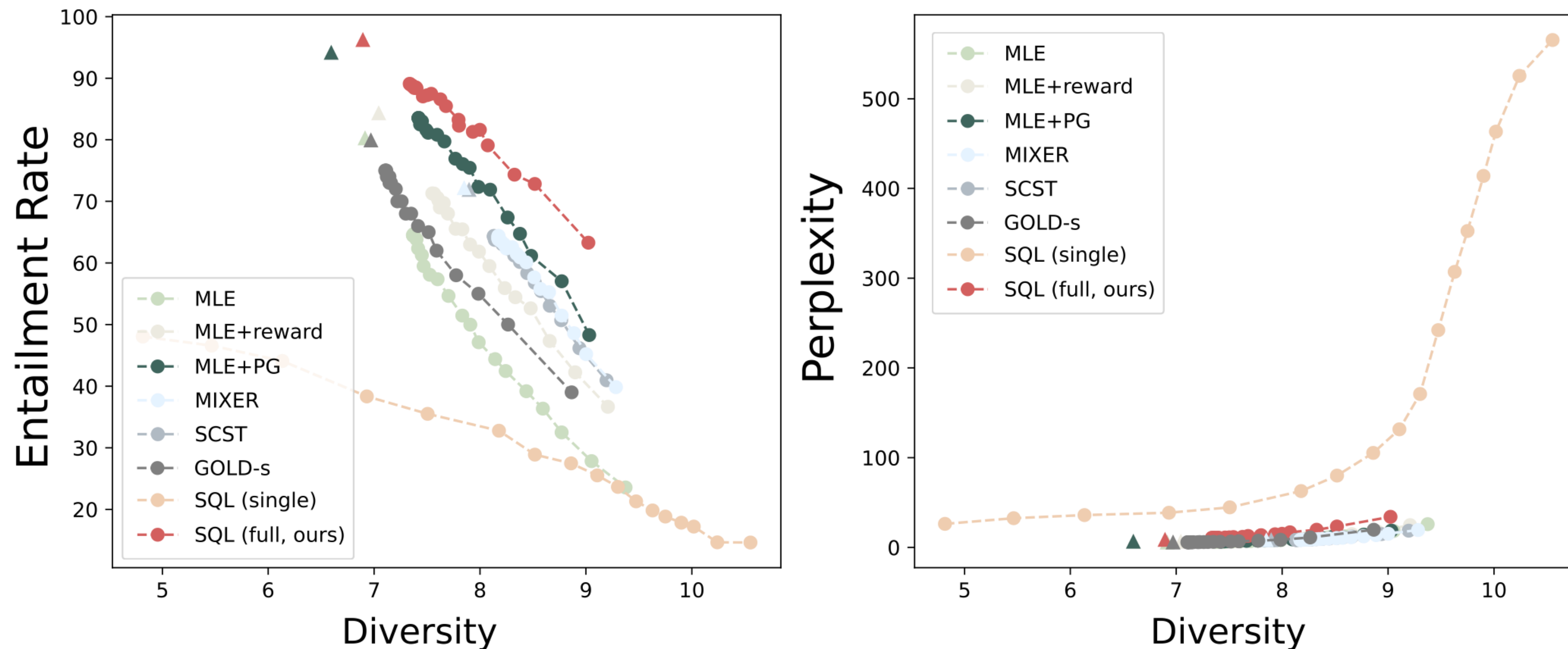
Samples of highest attack rate

# Application (III): Learning from **Noisy (Negative)** Text

- Entailment generation
  - Given a *premise*, generates a *hypothesis* that entails the premise
  - “Sophie is walking a dog outside her house” -> “Sophie is outdoor”
  - Negative sample: “Sophie is inside her house”
- Training data:
  - Subsampled 50K (premise, hypothesis) **noisy** pairs from SNLI
  - Average entailment probability: 50%
  - 20K examples have entailment probability < 20% ( $\approx$  **negative** samples)
- Rewards:
  - Entailment classifier
  - Pretrained LM for perplexity
  - BLEU w.r.t input premises (which effectively prevents trivial generations)

# Application (III): Learning from **Noisy (Negative) Text**

- **MLE** (and variants) and pure off-policy RL (**GOLD-s**) do not work ← **rely heavy on data quality**
- **SQL (full) > MLE+PG** (PG alone does not work)



Entailment-rate and language-quality vs diversity (top- $p$  decoding w/ different  $p$ )

# Key Takeaways

- Learning text generation from reward
- Previous RL for text generation (e.g., policy gradient, Q-learning):
  - 👹 **Low data efficiency; unstable training; slow updates; sensitive** to training data quality
- SQL
  - Objectives based on path consistency
  - 😊 **Stable training** from scratch given sparse reward
  - 😊 **Fast updates** given large action space
- Opens up enormous opportunities
  - For integrating more advanced RL (replay buffer, model-based RL, hindsight, ...)
  - To enable massive new applications in text generation